

Hydrodynamics and Solid Dosage Form  
Disintegration/Dissolution:  
Immediate Release Tablets and Novel *In Situ*  
Polyelectrolyte Gastroretentive Drug Delivery Systems

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### **Erklärung**

Hiermit erkläre ich, dass ich die vorliegende Arbeit selbstständig verfasst und  
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**Jede Lösung eines Problems ist ein neues Problem.**

Johann Wolfgang von Goethe (1749-1832)



# Zusammenfassung

Der Zerfall fester oraler Darreichungsformen im menschlichen Magen ist ein hoch komplexer Prozess, der sowohl von den physikochemischen Eigenschaften des Mageninhaltes als auch von physikalischen Variablen wie Hydrodynamik und mechanischer Beanspruchung abhängig ist. Ein genaues Verständnis der Rolle von hydrodynamischen Bedingungen und mechanischen Belastungen während des Zerfalls fester oraler Darreichungsformen kann helfen, die *in vitro* Testbedingungen und somit die Vorhersagekraft von *in vitro* Tests zu verbessern.

Das Ziel dieser Arbeit war es, ein grundlegendes Verständnis des Einflusses von variierenden hydrodynamischen Bedingungen auf den Zerfall und das Freisetungsverhalten von festen Arzneiformen zu erhalten. Zu diesem Zweck wurden zunächst die hydrodynamischen Bedingungen und Kräfte, die im PhEur/USP Zerfallstester vorherrschen, mittels numerischer Strömungsmechanik (engl. computational fluid dynamics, CFD) charakterisiert. Außerdem wurde ein modifiziertes Zerfallstestgerät entwickelt und die Strömungsverhältnisse darin mittels CFD simuliert. Dieses modifizierte Gerät wurde in zwei Fallstudien mit schnell freisetzenden Tabletten (engl. immediate release (IR) tablet) und gastroretentiven Arzneiformen (engl. gastroretentive drug delivery systems (GRDDS)) eingesetzt.

Durch die Vorgaben des Arzneibuchs folgt die Bewegung des Körbchens des traditionellen Zerfallstesters einem sinusförmigen Geschwindigkeitsprofil. Daher ändern sich die hydrodynamischen Bedingung und mechanische Beanspruchungen während des Bewegungszyklus fortwährend. Die Untersuchungen mittels CFD ergaben, dass die Arzneiform während der Prüfung einer Bandbreite von Flüssigkeitgeschwindigkeiten und Scherkräften ausgesetzt ist. Die hydrodynamischen Bedingungen im traditionellen Testgerät sind somit sehr variabel und nicht kontrollierbar.

Ein neues, modifiziertes Zerfallstestgerät wurde entwickelt, das auf der computergestützten numerischen Steuerung (engl. computerized numerical control (CNC)) basiert. Dieses modifizierte Gerät kann sowohl Bewegungen in alle drei Raumrichtungen als auch radiale Bewegungen vollziehen. Sowohl einfache als auch komplexe Geschwindigkeitsprofile können programmiert werden und der Einfluss von Bewegungsgeschwindigkeit und Bewegungsrichtung auf Zerfall und Freisetungsverhalten fester oraler Darreichungsformen kann untersucht werden. Weiterhin wurde ein modifizierter Probenbehälter entwickelt, der zweiseitige Strömungsbewegung zulässt. Numerische Strömungssimulationen der Flüssigkeitsbewegung und Kräfte im modifizierten Testgerät haben deutliche Unterschiede zum konventionellen

Tester gezeigt. Durch die CNC Steuerung und die frei wählbare Bewegungsgeschwindigkeit und -richtung ist es außerdem möglich, die hydrodynamischen Bedingungen zu kontrollieren.

Das modifizierte Gerät wurde eingesetzt, um den Einfluss der Bewegungsgeschwindigkeit des Probenbehälters auf die Zerfallszeit schnell zerfallender Tabletten zu untersuchen. Es konnten Einblicke in den Einfluss der Bewegungsgeschwindigkeit, der Viskosität des Mediums und der Bauart des Probenbehälters auf die Zerfallszeit gewonnen werden. Weiterhin wurde ein exponentieller Zusammenhang zwischen Zerfallszeit und Bewegungsgeschwindigkeit für den neuen Probenbehälter etabliert. Dieselben Verhältnismäßigkeiten wurden für den Zusammenhang zwischen Zerfallszeit und simuliertem Scherstress erhalten.

Weiterhin wurde eine gastroretentive Arzneiform entwickelt. Dabei wurde die Machbarkeit eines *in situ* Polyelektrolyt-Komplexes untersucht und erfolgreich umgesetzt. Verschiedene Komplexe bestehend aus verschiedenen Chitosanen und Carrageenen und unterschiedlichen Verhältnissen der beiden Polymere wurden hinsichtlich ihres Schwellverhaltens, ihrer mechanischen Stabilität und ihres *in vitro* Freisetzungsprofils des Arzneistoffs untersucht. Anhand einer optimierten Formulierung wurde der Einfluss von hydrodynamischen Bedingungen auf das Schwellverhalten und das Freisetzungsprofil des Wirkstoffes durch Einsatz des modifizierten Zerfallstesters gezeigt. Sowohl das Schwellverhalten der Arzneiform als auch die Freisetzung des Wirkstoffes waren in hohem Maße abhängig von der Bewegungsgeschwindigkeit des Probenbehälters.

Abschließend lässt sich zusammenfassen, dass unter Verwendung des modifizierten Zerfallstestgerätes neue Einblicke in die Rolle von hydrodynamischen Bedingungen bei Zerfalls- und Freisetzungsprozessen von festen Arzneiformen gewonnen wurden. Unter Auswahl geeigneter Bedingungen kann mit Hilfe des modifizierten Gerätes die Vorhersagekraft des *in vitro* Tests gesteigert werden. Außerdem wurde gezeigt, dass die numerische Strömungssimulation ein hilfreiches Werkzeug zur Vorhersage von hydrodynamischen Bedingungen und mechanischen Beanspruchungen in den beiden untersuchten Geräten darstellt.

## Abstract

Solid oral dosage form disintegration in the human stomach is a highly complex process dependent on physicochemical properties of the stomach contents as well as on physical variables such as hydrodynamics and mechanical stress. Understanding the role of hydrodynamics and forces in disintegration of oral solid dosage forms can help to improve *in vitro* disintegration testing and the predictive power of the *in vitro* test.

The aim of this work was to obtain a deep understanding of the influence of changing hydrodynamic conditions on solid oral dosage form performance. Therefore, the hydrodynamic conditions and forces present in the compendial PhEur/USP disintegration test device were characterized using a computational fluid dynamics (CFD) approach. Furthermore, a modified device was developed and the hydrodynamic conditions present were simulated using CFD. This modified device was applied in two case studies comprising immediate release (IR) tablets and gastroretentive drug delivery systems (GRDDS).

Due to the description of movement provided in the PhEur, the movement velocity of the basket-rack assembly follows a sinusoidal profile. Therefore, hydrodynamic conditions are changing continually throughout the movement cycle. CFD simulations revealed that the dosage form is exposed to a wide range of fluid velocities and shear forces during the test. The hydrodynamic conditions in the compendial device are highly variable and cannot be controlled.

A new, modified disintegration test device based on computerized numerical control (CNC) technique was developed. The modified device can be moved in all three dimensions and radial movement is also possible. Simple and complex moving profiles can be developed and the influence of the hydrodynamic conditions on oral solid dosage form performance can be evaluated. Furthermore, a modified basket was designed that allows two-sided fluid flow. CFD simulations of the hydrodynamics and forces in the modified device revealed significant differences in the fluid flow field and forces when compared to the compendial device. Due to the CNC technique moving velocity and direction are arbitrary and hydrodynamics become controllable.

The modified disintegration test device was utilized to examine the influence of moving velocity on disintegration times of IR tablets. Insights into the influence of moving speed, medium viscosity and basket design on disintegration times were obtained. An exponential relationship between moving velocity of the modified basket and disintegration times was established in simulated gastric fluid. The same relationship was found between the disintegration times and the CFD predicted average shear stress on the tablet surface.

Furthermore, a GRDDS was developed based on the approach of an *in situ* polyelectrolyte complex (PEC). Different complexes composed of different grades of chitosan and carrageenan and different ratios of those were investigated for their swelling behavior, mechanical stability, and *in vitro* drug release. With an optimized formulation the influence of changing hydrodynamic conditions on the swelling behavior and the drug release profile was demonstrated using the modified disintegration test device. Both, swelling behavior and drug release, were largely dependent on the hydrodynamic conditions.

Concluding, it has been shown within this thesis that the application of the modified disintegration test device allows for detailed insights into the influence of hydrodynamic conditions on solid oral dosage form disintegration and dissolution. By the application of appropriate test conditions, the predictive power of *in vitro* disintegration testing can be improved using the modified disintegration test device. Furthermore, CFD has proven a powerful tool to examine the hydrodynamics and forces in the compendial as well as in the modified disintegration test device.

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## Abbreviations

ACW	antral contraction wave
API	active pharmaceutical ingredient
BCS	biopharmaceutical classification system
CFD	computational fluid dynamics
CNC	computerized numerical control
CR	controlled release
DGM	dynamic gastric model
DoE	design of experiments
FaSSGF	fasted state simulated gastric fluid
FaSSIF	fasted state simulated intestinal fluid
FDA	food and drug administration
FeSSGF	fed state simulated gastric fluid
FeSSIF	fed state simulated intestinal fluid
FSM	fed stomach model
GRDDS	gastroretentive drug delivery system
HBS	hydrodynamically balanced system
HGS	human gastric simulator
HPMC	hydroxypropyl methylcellulose
IR	immediate release
IVIVC	<i>in vitro-in vivo</i> -correlation
LDV	laser-Doppler velocimetry
MMC	migrating motor complex
MR	modified release

## Abbreviations

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MRI	magnetic resonance imaging
PC	polyelectrolyte
PEC	polyelectrolyte complex
PhEur	European Pharmacopoeia
PIV	particle image velocimetry
pLIF	planar laser induced fluorescence
SGF	simulated gastric fluid
SIF	simulated intestinal fluid
USP	United States Pharmacopeia

# 1 Introduction

Solid oral dosage forms, especially tablets, are the most common administration way of drugs. Various formulations have been developed ranging from straightforward immediate release (IR) dosage forms to complex modified release (MR) dosage forms. The performance of these dosage forms in the human stomach is a highly complex process influenced by physiological as well as physicochemical factors. Currently, the *in vitro* evaluation of solid oral dosage form disintegration and dissolution is usually performed in compendial apparatuses. Since their introduction in the beginning of the 19<sup>th</sup> century they have become an important quality control tool in pharmaceutical development. At the time of their development the knowledge about physiological parameters like gastrointestinal motility or mechanical stresses was very limited. But, the more we learn about processes in the human stomach due to the development of modern diagnostic techniques, the more the demand for biorelevant *in vitro* testing increases.

The present work focuses on the biorelevance of the compendial disintegration test device in terms of hydrodynamic conditions and mechanical forces. The influence of hydrodynamics on the disintegration of IR tablets was investigated using a new, modified disintegration test device. Furthermore, this work describes the development and optimization of a gastroretentive drug delivery system (GRDDS). The influence of hydrodynamics on the swelling behavior and the drug release profile of the GRDDS was evaluated. The results of this work help to understand the influence of hydrodynamic conditions and mechanical forces on disintegration and dissolution of solid oral dosage forms.

In the following sections of the introduction the mechanism of tablet disintegration and the influencing factors are discussed. A short summary of the physiological factors of the gastrointestinal tract which can affect disintegration and dissolution is given. Furthermore, current compendial and biorelevant *in vitro* tools to investigate dissolution are presented. Formulation strategies for GRDDSs are described and the approach of gastroretention via polyelectrolyte complexes (PEC) is introduced.

## 1.1 Solid oral dosage form disintegration

Among solid oral dosage forms, tablets are the most popular ones. Tablet dosage forms can be divided into IR tablets and MR tablets. While IR tablets are supposed to disintegrate in the stomach rapidly after ingestion, MR tablets are designed to deliver the drug in a controlled manner. Several mechanisms are known to control the release of the drug: sustained release, prolonged release, repeated release, and delayed release. With sustained and prolonged release formulations the drug is released over a prolonged period of time. This is for example accomplished by the establishment of diffusion barriers. With repeated release formulations several drug doses are released intermittently. Typical delayed release formulations are enteric coated dosage forms where the drug release in the stomach is prevented by an enteric coat. Reaching the intestine, the coat becomes dissolved and disintegration and dissolution will take place.

After the ingestion of an oral solid dosage form two processes occur that make the drug available for absorption: disintegration and dissolution (Figure 1). Thereby disintegration is the process of breaking the dosage form structure into smaller aggregates and particles. Although disintegration is a prerequisite for rapid drug dissolution from IR dosage forms, complete disintegration does not mean complete dissolution of the active pharmaceutical ingredient (API). On the other hand, in the case of MR dosage forms, dissolution occurs without disintegration but by diffusion and/or erosion. Depending on the desired site of action, disintegration and dissolution are happening in the stomach or in the intestine.

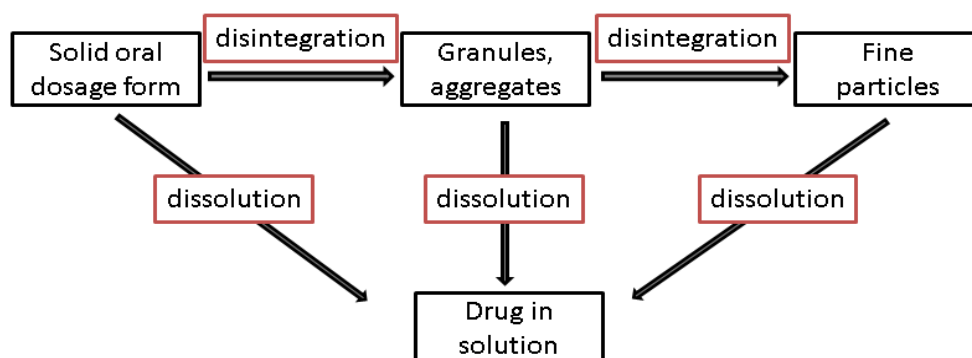


Figure 1: Disintegration and dissolution process.

### 1.1.1 Factors affecting disintegration

Factors affecting disintegration can be divided into formulation related factors, physicochemical characteristics of the immersion fluid, and physical variables the dosage form is exposed to.

Tablet disintegration can be governed by formulation variables such as type, amount, and properties of disintegrant (Shotton and Leonard, 1976; van Kamp et al., 1983; Colombo et al., 1984). The mechanisms of action of disintegrants have been investigated early. Several mechanisms are proposed: swelling, wicking, and repulsive force. Swelling occurs due to penetration of liquid into the tablet. Thereby, force is exerted on the tablet matrix leading to disintegration through rupture (Patel and Hopponent, 1966). Wicking is caused by capillary action upon water penetration into the porous tablet matrix. Thus, the tablet structure is weakened leading to disintegration (Curlin, 1955). Another proposed disintegration mechanism is the occurrence of repulsive forces (Guyot-Hermann and Ringard, 1981). It is hypothesized, that the penetrating water annihilates the hydrogen bonds and van-der-Waals and electrostatic forces. Repulsive forces, e.g. between starch chains, are generated facilitating disintegration. For all these proposed mechanisms the penetration of water into the tablet is essential for action of the disintegrant. How water penetration is influenced by the properties of the fluid is discussed later in this section.

In the human stomach oral dosage form disintegration can further be influenced by physicochemical characteristics of the fluid as well as by physical variables such as hydrodynamics and mechanical stresses. Thereby, the prandial state of the stomach plays an important role since food ingestion changes gastric contents properties as well as hydrodynamic conditions.

Several studies examined the effect of food on tablet disintegration *in vivo*. Kalantzi et al. (2005) found increased tablet disintegration times in dogs after administration of milk compared to administration of water. The same observations were made by Abrahamsson et al. (2004) comparing disintegration times after ingestion of water and nutritional drink. The prolonged disintegration under fed conditions was attributed to the formation of a protein film around the tablet.

Other studies investigated the effect of food on tablet disintegration *in vitro* using viscous model fluids representing the fed state. Brouwers et al. (2011) immersed the tablet in nutritional drink and visualized the water mobility by magnetic resonance imaging (MRI). They explained the delayed tablet disintegration in nutritional drink by reduced water ingress. Recently, attempts have been made to find a disintegration medium exhibiting the properties of

mashed FDA meal (Radwan et al., 2012). A solution of 1.4 % hydroxypropyl methylcellulose (HPMC) was found to exhibit similar rheological properties and viscosity. Delayed disintegration and dissolution in 1.4 % HPMC solution compared to simulated intestinal fluid (SIF) was measured *in vitro*. The effect was related to decreased water penetration into the tablet and reduced water diffusivity.

When exposed to a gastric fluid or a model disintegration test medium, water will penetrate into the tablet. As described above, water penetration is essential for the action of tablet disintegrants causing rupture of the tablet. The water penetration rate depends on the properties of the fluid as well as on the characteristics of the tablet. Water uptake has been shown to be dependent on the viscosity of the fluid (Anwar et al., 2005; Abrahamsson et al., 2004; Radwan et al., 2014). Low viscous media can penetrate fast, whereas high viscous media penetrate slowly. The slow penetration leads to prolonged disintegration times. Abrahamsson et al. (2004) explained the slow penetration of viscous media by the formation of film around the tablet that impedes water uptake. A good correlation between media viscosity, water uptake and disintegration times was established by Radwan et al. (2014).

Water uptake was also found to be dependent on the water diffusivity of the model medium (Radwan et al., 2013). Reduced water diffusivity decreases the water uptake and delays tablet disintegration. Water diffusivity decreased with increasing viscosity of sucrose and HPMC solutions, where the decrease was more pronounced in sucrose solutions indicating an interaction between the sugars in the sucrose solutions and water. For sucrose solutions a linear relationship between water diffusivity and inverse viscosity was found, while this correlation was not linear for HPMC solutions. This indicates that water diffusivity is largely dependent on the chemical structure of the medium components. Furthermore the water diffusivity was dependent on the sodium chloride concentration of the solution. A close correlation between water uptake rates and water diffusivity was observed.

Water uptake is also dependent on the structural properties of the tablet. Functional coatings for example will swell upon contact with media forming a barrier and thereby slowing liquid penetration (Radwan et al., 2012). In general, high porosity is associated with fast disintegration due to fast water absorption. Additionally, the porosity is related to the strength of the tablet matrix, where high porosity results in low strength. For high porous tablets water absorption will be fast and therefore fragmentation and rupture will be the driving force of disintegration. For low porous tablets the water penetration rate will be slow. Thereby, the action of disintegrants is limited retarding disintegration. It needs to be considered, that different disintegrants as well as other formulation components have different affinities to water and

may influence the rate of water uptake. Surface erosion from rigid structures is slower compared to erosion of soft matrices. Surface erosion, rupture, and fragmentation will occur simultaneously.

Despite these ambiguous investigations, the effect of hydrodynamics on disintegration has been neglected so far. Only one study (Radwan et al., 2014) mentions the importance of hydrodynamics for disintegration.

Figure 2 summarizes the factors affecting solid oral dosage form disintegration in the human stomach and under biorelevant *in vitro* test conditions.

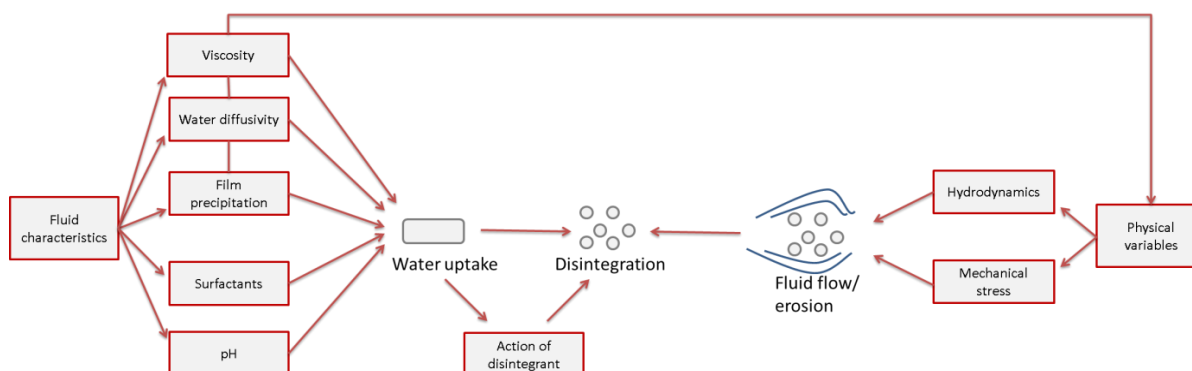


Figure 2: Factors affecting solid oral dosage form disintegration.

### 1.1.2 PhEur disintegration testing apparatus

The disintegration testing apparatus proposed by the European Pharmacopoeia (Ph.Eur., European Pharmacopoeia, 2014) is depicted in Figure 3. It consists of a basket-rack assembly, a 1 L beaker, a thermostatic water bath and a motor for the up and down movement of the basket-rack assembly. The assembly comprises a set of six circular arranged open ended glass tubes that are held in a vertical position by two plates. The bottom of the tubes is limited by a stainless steel wire mesh with quadratic meshes.

According to the PhEur the basket-rack assembly is moved up and down 29 to 32 times per minute over a distance of  $55 \pm 2$  mm. Thereby a sinusoidal moving profile is generated. From the data (30 cycles per minute resulting in a frequency  $f$  of 0.5 Hz and amplitude of  $a = 27.5$  mm) the motion  $s$  is:

$$s = -a * \cos(2\pi * f * t) \quad (1)$$

where  $a$  is the amplitude,  $f$  is the frequency and  $t$  is the time.

Calculating the time derivate we get the moving velocity  $v$ :

$$v = 2\pi * f * a * \sin(2\pi * f * t) \quad (2)$$

with  $2 * \pi * f * a = 86.4 \text{ mm/s}$ .

a)



b)

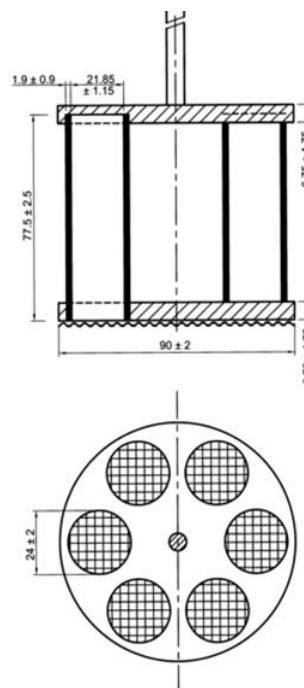


Figure 3: European Pharmacopoeia disintegration apparatus. a) Laboratory setup (PTZ 2 EH, Pharma Test, Hainburg, Germany. b) Schematic representation of the basket-rack assembly (Ph.Eur., European Pharmacopoeia, 2014). Dimensions in mm.

The test is usually performed using water or simulated gastric fluid as disintegration medium. For enteric coated tablets simulated gastric fluid (pH 1.2) is used for the first hours followed by pH shift using simulated intestinal fluid (pH 6.8) for the time period required for disintegration. Disintegration time is defined as the time after which all of the dosage form, except insoluble coating or capsule shell, remaining on the mesh is a soft mass having no palpable core and is usually determined visually.

## 1.2 Physiological considerations for disintegration and dissolution testing

The human stomach is the starting point of solid oral dosage form disintegration and drug dissolution. Depending of the site of action, the drug release process is completed in the stomach or the dosage form is transported to the small and large intestine. To judge the relevance of *in vitro* test methods and to understand dosage form performance, profound knowledge of the *in vivo* situation is required. Therefore, the following section gives an overview of the functions of and the conditions in the human stomach available from literature data.

### 1.2.1 The human stomach

The human stomach can be divided into two functional regions: the fundus and the antrum (Figure 4). While the fundus serves as reservoir for incoming contents and is characterized by low stress and little movement, the antrum acts as “antral mill” exhibiting high stresses and intense movement to prepare the gastric contents for emptying through the pylorus.

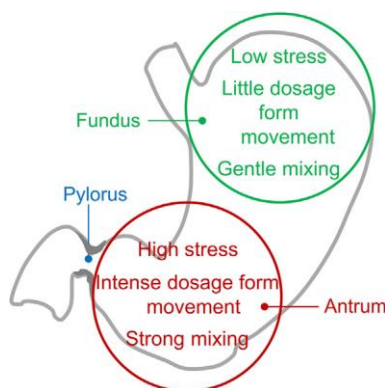


Figure 4: Functional regions of the human stomach (Koziolek et al., 2014).

### 1.2.2 Gastric contents and volume

In the fasted state the stomach is collapsed accommodating only little fluid volumes of 10 to 50 mL (Schiller et al., 2005; Goetze et al., 2009). After meal ingestion the human stomach evolves and is able to host volumes of up to 1 L where the capacity depends on the individual physiology as well as on the meal volume and nature (Chial et al., 2002; Geliebter and Hashim, 2001). Inside the stomach the content is separated by gravity and layering occurs (Schulze,

2006). Particles that are heavier than water will sediment to the antrum while fat will float on top of the contents.

Gastric content is digested by mixing and grinding as well as by the gastric juice. Food intake stimulates the secretion of gastric juice to rates of 10 to 50 mL/min compared to 1 mL/min in the unstimulated state (Koziolek et al., 2013). The main components of the gastric juice are hydrochloric acid, bicarbonate, pepsinogen, gastric lipase, mucins, and bile salts. The pH, surface tension, osmolality, and the buffer capacity as well as the concentration of the components are largely dependent of the prandial state (Kalantzi et al., 2006). Table 1 summarizes the physicochemical properties of the gastric contents in the fasted and fed state. All these parameters need to be considered performing biorelevant *in vitro* disintegration and dissolution studies.

Table 1: Physicochemical properties of gastric secretions in the fasted and fed state.

Property	Fasted state	Fed state	Reference
Volume [mL]	10-50	500-1000	Schiller et al., 2005; Goetze et al., 2009; Chial et al., 2002; Geliebter and Hashim, 2001
pH	1-2	3-7	Kalantzi et al., 2006
Pepsin [mg/mL]	0.11-0.22	0.26-0.58	Kalantzi et al., 2006
Bile salts [mM]	0.008-0.28	0.06	Armand et al., 1996; Vertzoni et al., 2005
Buffer capacity [mmolL <sup>-1</sup> ΔpH <sup>-1</sup> ]	7-18	14-28	Kalantzi et al., 2006
Osmolality [mOsm/kg]	98-140	217-559	Kalantzi et al., 2006
Surface tension [mN/m]	41.9-45.7	30-31	Kalantzi et al., 2006
Viscosity [Pa s]	n/a	10-2000	Abrahamsson et al., 2005

Several biorelevant model media have been introduced during the last years with some of them listed in Table 2. Since biorelevant media are of minor relevance for this work they are not discussed further and the interested reader is referred to corresponding reviews (Klein, 2010; Kleberg et al., 2010; Reppas and Vertzoni, 2012) and research studies (Anwar et al., 2005; Radwan et al., 2012; Parojčić et al., 2008).

Table 2: Biorelevant *in vitro* model media to simulate fasted and fed state physicochemical properties.

Fasted stomach	Fed stomach
Fasted state simulated gastric fluid FaSSGF	Fed state simulated gastric fluid FeSSGF
Fasted state simulated intestinal fluid FaSSIF	Fed state simulated intestinal fluid FeSSIF
	Milk
	Nutrient drinks (Ensure, EnsurePlus)
	1.4 % HPMC solution

### 1.2.3 Motility patterns

The patterns of gastric motility are highly different in the fasted and fed state. During the fasted state the interdigestive migrating motor complex (MMC) occurs. This cycle is characterized by 4 phases of different contraction strength and duration (Takahashi, 2012). Phase I, lasting 40-60 min, is characterized by low contraction frequency and strength. During phase II, which is similar in length, the frequency and intensity of the contraction waves increases. The following phase III is short (4-6 min) but powerful. All undigested material is emptied from the stomach, even large monolithic objects like tablets. During this period highest pressures and forces are acting on the stomachs content. Phase IV is the transition period between phase III and I, lasting for 15 to 30 min during which frequency and intensity of the contractions decrease. The contractions originate in the proximal stomach and propagate towards the pylorus. The cycle is repeated every 1 to 2 h.

Meal ingestion interrupts the MMC and initiates the fed pattern (digestive motor activity). Regarding contractile frequency and strength this pattern is comparable to phase II of the MMC. Thus, forces acting in the fed stomach are lower than in the fasted state and highest forces occur during phase III of the MMC.

Incoming food is transported to the antrum by slow fundic contractions where it is mixed and digested by antral contraction waves (ACW). The ACWs originate from the middle of the greater curvature and travel towards the pylorus with a velocity of about 2 to 3 mm/s and mean occlusion rate of 40 to 60 % (Marciani et al., 2001c; Kwiatek et al., 2006). The contraction

frequency was found to be 3 contractions/min (Marciani et al., 2001c). Reaching the pylorus, fluid and small particles up to approximately 2 mm are emptied into the duodenum while undigested larger particles are retained and digested further. This process is known as gastric sieving (Schulze, 2006). As the ACW approaches the pylorus the sphincter narrows leading to the retro propulsion of chyme into the corpus. Repeated propulsion and retro propulsion causes grinding and size reduction of the solid contents until they can pass through the pylorus. When digestion is finished, the stomach returns to the MMC during which indigestible large objects, like tablets, are emptied.

### *1.2.4 In vivo hydrodynamics and forces*

During gastric mixing and digestion considerable mechanical forces are acting on solid structures like food particles or dosage forms provoking their disintegration. Thereby, fluid flow around the objects generates shear forces that contribute to size reduction and breakage. Only limited information is available in the literature concerning the flow velocity of gastric contents. Hausken et al. (1992) studied the movement of luminal contents utilizing duplex sonography. After ingestion of 500 mL meat soup peak velocities of 0.6 m/s were observed. The maximum velocity during retro propulsion was reported to be 0.2 m/s. Using a velocity-sensitive high speed magnetic resonance imaging technique called echo planar imaging, Boulby et al. (1999) reported maximum forwarded antral flow velocities of 0.05 m/s, 0.029 m/s, and 0.033 m/s 5 minutes after ingestion of a 5 % glucose solution, 10 % glucose solution, and a nutrient drink, respectively. Peak velocities associated with the retro propulsive flow were similar.

The direct measurement of forces on tablets is difficult. The mechanical destructive force in the gastrointestinal tract was evaluated using a destructive force dependent release system (Kamba et al., 2000). A marker drug contained in tablets was released only when the force on the tablets was higher than the predetermined crushing strength. It was reported that the human stomach has the potential to crush a tablet with a crushing strength of 1.50 N in the fasted state and 1.89 N in the fed state. Using agar gel beads Marciani et al. (2001a) applied a similar approach to determine destructive forces. They reported the maximum force exerted by the antrum to be 0.65 N. Vassallo et al. (1992) utilized a combination of radioscinigraphy, manometry, and axial force transducer with an inflatable balloon to measure axial forces during emptying of liquid and solid meals. Cumulated axial forces per unit time are reported 6 N/30 min and 5.5 N/30 min for emptying of liquids and solids, respectively. Laulicht et al. (2010) reported motive forces experienced by an orally ingested magnetic pill using high-resolution pill tracking. Highest motive forces were observed during the MMC reaching 0.02481,

0.03014, and 0.01236 N (2481, 3014, and 1236 dynes) in the three dimensions. Average human gastric emptying forces were insignificantly lower in the fasted state (0.00414 N, 414 dynes) compared to the fed state (0.00657 N, 657 dynes).

Also, pressure fields in the stomach need to be considered since pressure forces may play a critical role in disintegration. Manometry has been widely used to investigate antroduodenal pressures after ingestion of different meals (Indireshkumar et al., 2000; Janssen et al., 2011; Janssen et al., 2012; Pauwels et al., 2014; Hausken et al., 2002). These studies revealed an inhomogeneous pressure field with a pressure gradient between the distal antrum and the proximal duodenum of 80 to 467 Pa (0.6 to 3.5 mm Hg). Fasting intragastric pressures in the range of 800 to 1733 Pa (4.5 to 10 mm Hg) were reported. Infusion of nutritional drinks increased the intragastric pressure, but no more than 1067 Pa (6.5 mm Hg).

### *1.2.5 Gastric emptying*

Liquids and small particles are emptied from the stomach through the pylorus. Thereby, transpyloric flow follows the pattern of antegrade and retrograde fluid movement. Particles, too large to pass the pyloric sphincter are retained and further processed. It is assumed, that particles smaller 2 mm can pass the pylorus. However, particles with a density higher than that of water are retained by the above described process of gastric sieving (Schulze, 2006). Emptying of large indigestible particles occurs only during phase III of the MMC.

Liquids and solids are emptied with different mechanisms. After ingestion of liquids, they distribute rapidly throughout the stomach and are emptied immediately following first-order kinetics (Hellström et al., 2006). In contrast, the emptying pattern of solids is biphasic (Hellström et al., 2006; Schulze, 2006). After ingestion, a lag phase is observed during which only little emptying occurs followed by extensive emptying following first-order kinetics. Thereby, particle size, caloric content, and viscosity have been shown to influence gastric emptying (Marciani et al., 2001b).

### 1.3 Selected biorelevant *in vitro* models for dissolution testing

The USP and PhEur describe different *in vitro* methods to examine drug dissolution from oral solid dosage forms. Many years the gold standard for dissolution testing was the paddle apparatus. However, many studies reported a lack of *in vivo-in vitro*-correlation (IVIVC). With today's knowledge about *in vivo* hydrodynamics and forces we can conclude that this lack of IVIVC is due to the fact that the standard dissolution test devices are not able to simulate the complex *in vivo* conditions appropriately.

In recent years many techniques like magnetic momentum imaging, gamma scintigraphy and telemetry capsules were developed that could be used to visualize and understand gastric flows and forces. Due to this new knowledge about the *in vivo* conditions certain attempts have been done to develop more biorelevant *in vitro* models for the investigation of the drug dissolution from oral solid dosage forms with some of them introduced in this section.

#### 1.3.1 Paddle-bead method (Aoki et al., 1992; Aoki et al., 1993)

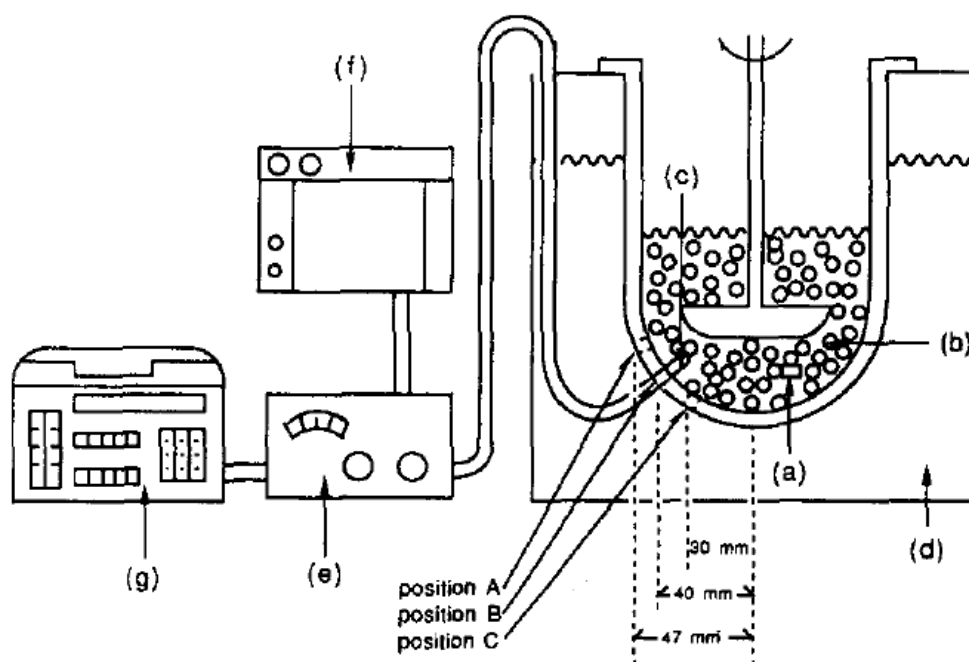


Figure 5: Paddle-bead method. a) Matrix tablet, b) beads, c) catheter, d) water bath, e) voltage control unit, f) recorder, g) integrator (Aoki et al., 1993).

To examine the impact of mechanical stress on drug dissolution Aoki et al (1993; 1992) introduced the paddle-bead method. This apparatus is a modification of the USP paddle apparatus, where polystyrene beads (diameter 6.35 mm, specific gravity 1.05 g/cm<sup>3</sup>) are added to the dissolution medium and dosage form in the vessel (Figure 5). Through the collision between the beads and the solid oral dosage form mechanical forces are generated. The number of the beads, the volume of dissolution medium as well as the paddle rotational speed can be varied to achieve a range of impact forces. The impact force exerted by the beads can be recorded by the catheter connected to the recorder. It was reported that the *in vitro* release was similar to the *in vivo* release in fasted beagle dogs under the conditions of 25 rpm, 250 mL of medium and 2500 beads (Aoki et al., 1992; Aoki et al., 1993).

### 1.3.2 Rotating beaker (Abrahamsson et al., 2005)

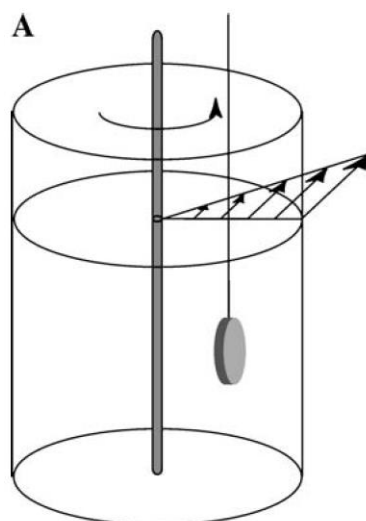


Figure 6: Rotating beaker apparatus (Abrahamsson et al., 2005)

The rotating beaker (Figure 6, Abrahamsson et al., 2004) was designed to simulate *in vivo* surface shear stresses present in the postprandial stomach. The device is a simple modification of the USP II apparatus. It consists of a beaker (220 mm diameter) with a tablet fixed centrally 55 mm from the center of the beaker and 40 mm below the free surface. The beaker can be rotated at a constant rate between 8 and 50 rpm thereby producing a controlled fluid flow around the tablet and biorelevant Reynolds numbers which are in the range of 0.1 to 30 (Abrahamsson et al., 2005). Fluid flow and surface shear stress in this device were calculated. The erosion rate of HPMC matrix tablets was investigated under varying operating conditions. A close relation between experimentally measured erosion rates and predicted shear stress was demonstrated.

The rotating beaker as well as the paddle-bead apparatus are simple models to investigate the effect of an individual parameter on drug dissolution. They are not able to predict the interaction of different parameters like hydrodynamics, mechanical stresses, media volumes and composition and the dynamic changes.

### 1.3.3 Dissolution stress test device (Garbacz et al., 2008)

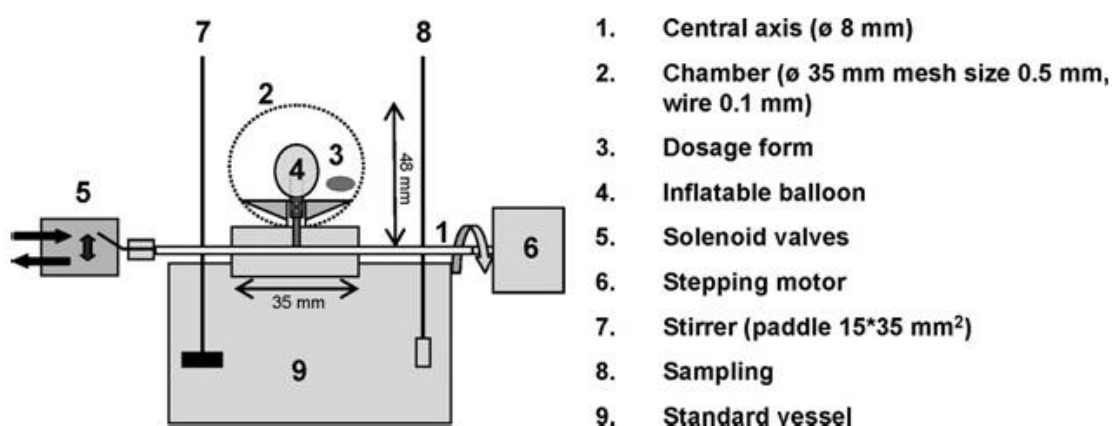


Figure 7: Dissolution stress test device (Garbacz et al., 2008).

On the basis of real time imaging results (Weitschies et al., 1999; Weitschies et al., 2005) the dissolution stress test device was designed with the aim to mimic gastrointestinal movement and mechanical stresses acting on the dosage form during gastrointestinal transit (Garbacz et al., 2008). Six steel netting chambers for hosting the dosage form are attached to a central axis, which is placed on the top edges of the compendial dissolution vessels. Each chamber contains a balloon which generates pressure waves by pulsatile inflation and deflation. The movement of the central axis, the pressure amplitudes and the sampling are computer-controlled. The stress test device is able to produce different patterns of movement and physical forces on the dosage form. Due to the setup the dosage form is exposed to the medium only 50 % of the time of one rotation.

## 1.3.4 Fed stomach model (FSM) (Koziolek et al., 2014)

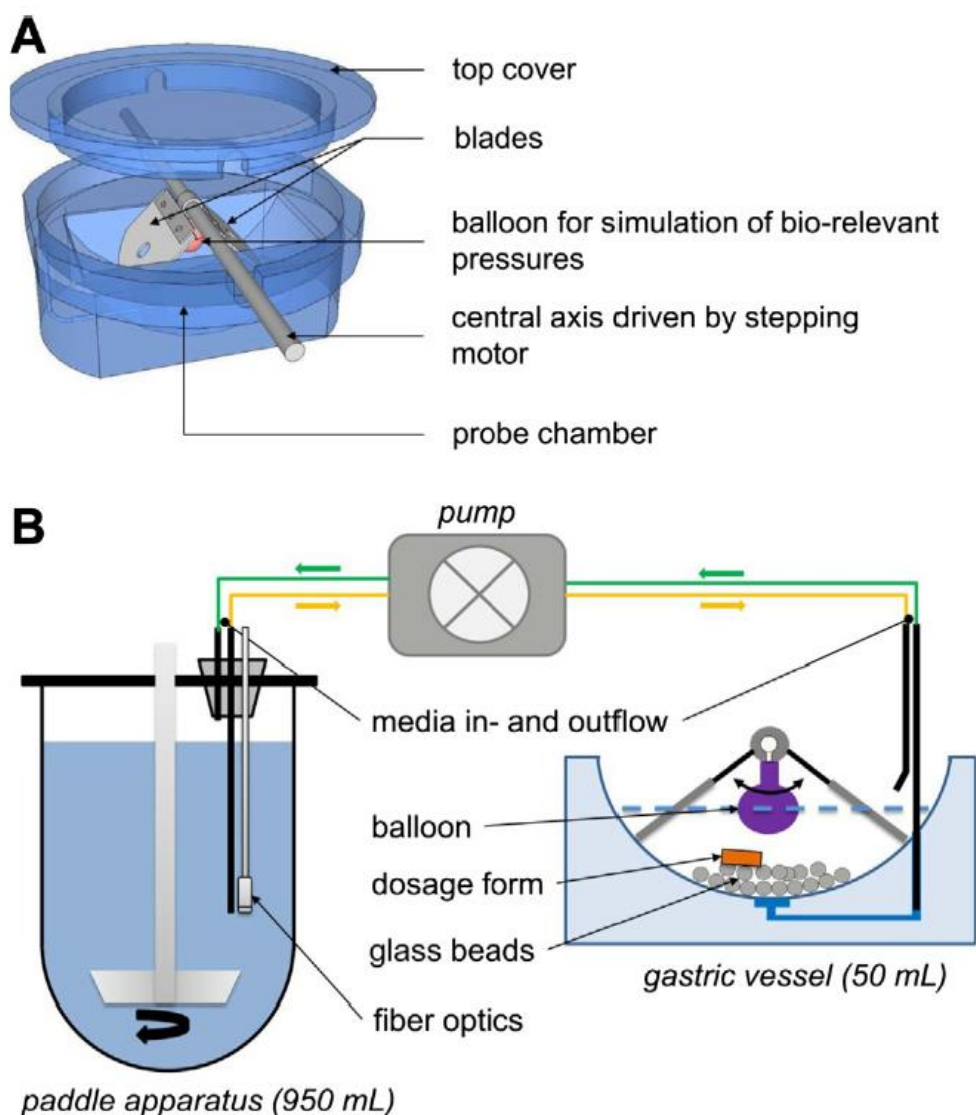


Figure 8: Fed stomach model (FSM). A) FSM gastric vessel, B) closed loop test configuration (Koziolek et al., 2014).

The FSM was developed to simulate the conditions present in the postprandial state with particular focus on mechanical aspects (Koziolek et al., 2014). Adjustable parameters are pressure and transport events generated by gastric contractions *in vivo* as well as hydrodynamics. The principle part of the model is the gastric vessel (Figure 8) which is designed as an open flow through system. Flow between the gastric vessel and the paddle apparatus is controlled via a pump. Two blades are located at a central axis at the top of the gastric vessel that can be moved by a stepping motor. The small glass beads at the bottom of each cell are moved by the blades generating shear forces. Pressure forces can be applied by inflation of the balloon. Complex test scenarios were developed to simulate the varying conditions in the different parts of the stomach.

## 1.3.5 Dynamic gastric model (DGM) (IFR, Norwich, U.K.)

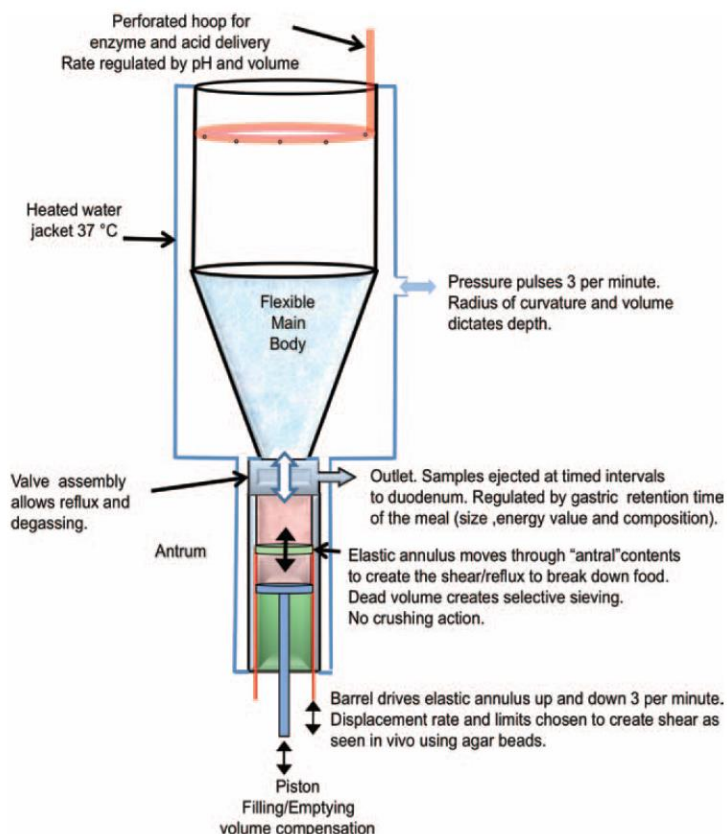


Figure 9: Schematic presentation of the dynamic gastric model (Wickham and Faulks, 2012).

The DGM was initially developed for the dynamic physicochemical simulation of the intragastric processing of food. It comprises two parts representing the fundus and antrum, respectively (Figure 9). In the first part the mixing dynamics, diffusion profiles of acid and enzymes and emptying cycles of the stomach are simulated. The processed material is transported to the second part through a unique emptying cycle where higher shear is present forcing the mechanical breakdown of the contents. The material emptied from the second part can be further processed within a compartment simulating the small intestine. Originating from food science the system was recently used to investigate food effect on drug release from matrix tablets (Chessa et al., 2014).

### 1.3.6 Human gastric simulator (HGS) (Kong and Singh, 2010)

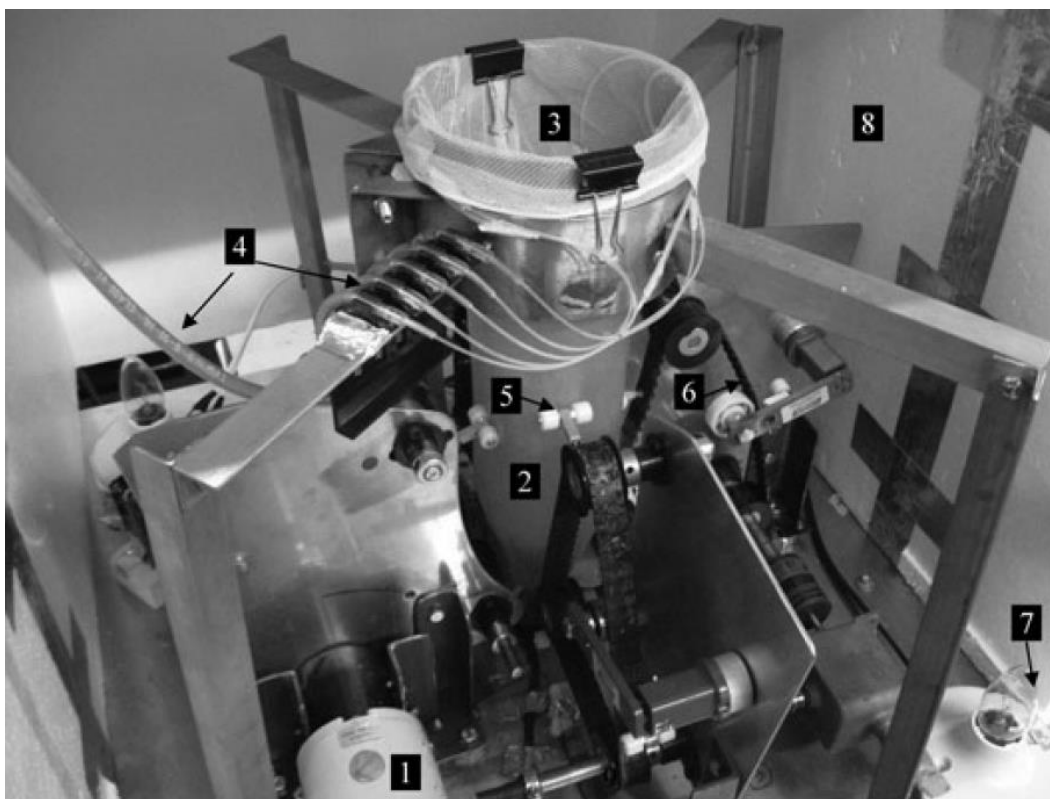


Figure 10: Human gastric simulator (HGS). 1) motor, 2) latex lining, 3) mesh bag, 4) secretion tubing, 5) roller, 6) belt, 7) light bulb for temperature control, 8) plastic foam insulation (Kong and Singh, 2010).

The human gastric simulator (HGS) was introduced to investigate food digestion under accurate simulation of stomach wall movement, producing physiological relevant mechanical forces (Kong and Singh, 2010). The main components comprise a latex lining chamber representing the stomach, a mechanical driving system of 12 rollers secured on belts mimicking gastric wall contractions, gastric secretion and emptying systems, and temperature control (Figure 10). Until now, the HGS has not been utilized for pharmaceutical purposes and its application is limited to the investigation of food digestion.

## 1.3.7 Artificial digestive system TIM-1 (TNO, Zeist, Netherlands)

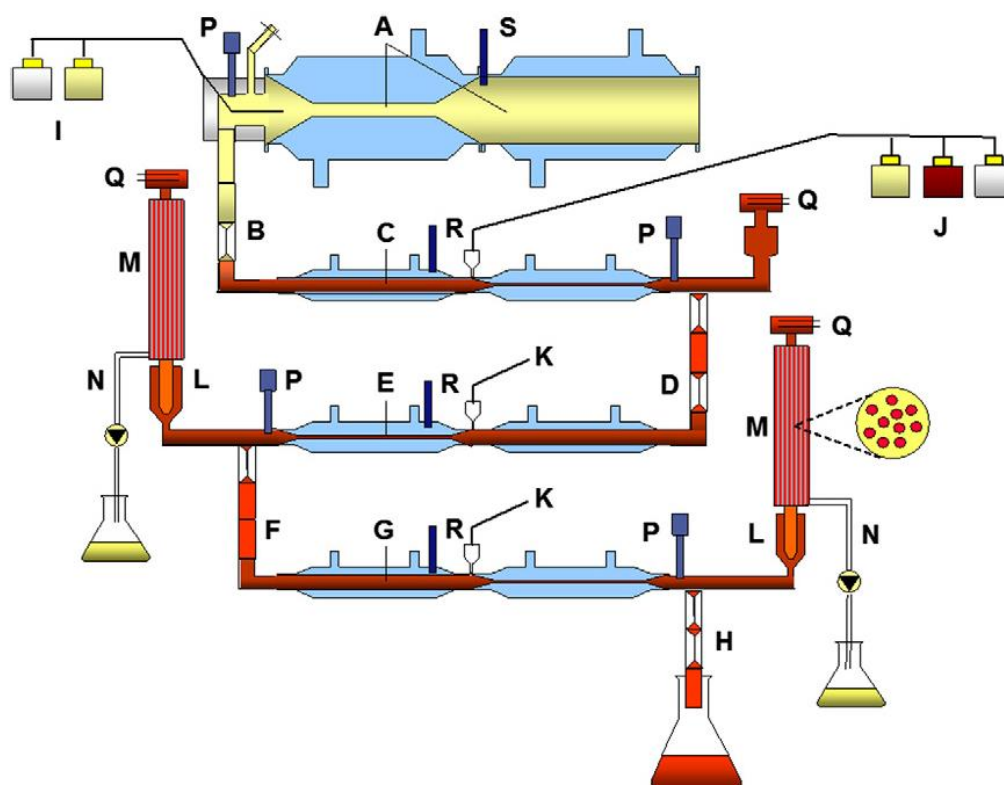


Figure 11: Schematic representation of TIM-1 (Brouwers et al., 2011). A: stomach compartment, B: pyloric sphincter, C: duodenum compartment, D: peristaltic valve, E: jejunum compartment, F: peristaltic valve, G: ileum compartment, H: ileocecal sphincter, I: stomach secretion, J: duodenum secretion, K: jejunum/ ileum secretion, L: prefilter, M: hollow fiber filtration module, N: water absorption, P: pH electrodes, Q: level sensors, R: temperature sensors, S: pressure sensors.

Originally developed for the investigation of the absorption of nutritional materials the TIM-1 system finds more and more application in pharmaceutical development. It allows simulation of the *in vivo* dynamic digestive and physiological processes which occur in the human stomach and small intestine. The computer-controlled system comprises four serial connected compartments representing the stomach, duodenum, jejunum and ileum, respectively. Each compartment is a glass unit with a flexible inner wall. The space between the glass wall and the flexible wall is filled with water at 37 °C. By alternating the water pressure and thereby squeezing the inner wall peristaltic contractions of the stomach wall are simulated. Transit of the chyme is modulated by opening and closing the peristaltic valves according to transit patterns obtained from *in vivo* studies. The jejunum and ileum compartment are connected to semipermeable hollow fiber membranes to simulate absorption of dissolved drug molecules. In each compartment the pH is monitored and can be regulated by the addition of hydrochloric acid in the stomach compartment and sodium bicarbonate in the intestinal compartments. Additionally, simulated gastric, biliary and pancreatic secretions can be added via peristaltic

pumps. The concentration of the secretions remains constant and the dynamics of concentration changes as they occur *in vivo* cannot be simulated. Nonetheless the use of TIM-1 for the prediction of absorption is limited due to two reasons. First, with the hollow fiber membranes only passive transport is possible. The simulation of *in vivo* processes like active transport, efflux and intestinal wall metabolism is not possible. Due to this limitation, the concentration of the added simulated gastric, biliary and pancreatic secretions stays constant. No absorption or metabolism like *in vivo* is possible. Second, the absorption *in vivo* is possible continuously across the small intestine. In the model there are only two absorption points, one in the jejunum the other in the ileum. This is especially prejudicial to drug with a narrow absorption window in the upper part of the small intestine (McAllister, 2010). One further limitation for the application of the system in pharmaceutical development is the design of the valves connecting the compartment. It is not possible for solid dosage forms to cross the valves to enter the next compartment.

The use of complex model like TIM, DGM, and HGS for routine dissolution testing is limited due to their high complexity. Simple models such as the paddle-bead method and the rotating beaker are preferred due to their simplicity and easy of handling. Furthermore, investigations in complex models are more time and cost intensive compared to the simpler models.

## 1.4 Computational fluid dynamics

Computational fluid dynamics (CFD) uses numerical methods and algorithms to solve and analyze fluid flow problems numerically. The fundamental basis of nearly all CFD problems are the Navier-Stokes equations.

A CFD analysis comprises three steps: preprocessing, simulation, and postprocessing. During preprocessing the geometry of the problem needs to be defined. Subsequently, the fluid volume is divided into discrete cells, called the meshing process. Afterwards, the physical properties of the reconstructed geometry are defined and boundary conditions are applied. During the second step, the simulation, the governing equations are solved iteratively. After the simulation is finished postprocessing follows which comprises the analysis and visualization of the simulation results.

Originating from engineering sciences, CFD found its way to pharmaceutical issues in the recent years. The flow field in different apparatuses has been examined and evaluated (Kuriakose and Anandharamakrishnan, 2010; Liu and Li, 2014; Ameer and Bouzit, 2013; Bai and Armenante,

2008). CFD was also applied to parts of the human body like the coronary system (Chaichana et al., 2012; Martorell et al., 2012), the respiratory system (Ides, 2012; Nowak et al., 2003; van Ertbruggen et al., 2005), the nasal cavity (Di et al., 2013; Wang et al., 2012), and even the stomach (Ferrua and Singh, 2010; Ferrua et al., 2011; Imai et al., 2013; Kozu et al., 2010; Pal et al., 2004). The CFD studies on the flow field in the USP dissolution apparatuses and the human stomach are of considerable importance for the present work and will be described in the following sections.

### 1.4.1 Dissolution apparatus

In recent years, CFD was frequently used to examine the hydrodynamics of the USP paddle dissolution apparatus. The results should help to understand the relations between hydrodynamics and dissolution and to explain the failures in dissolution testing.

Several studies (Ameur and Bouzit, 2013; Bai and Armenante, 2008; Bai et al., 2007; Bai et al., 2011; Baxter et al., 2005; Kukura et al., 2004; D'Arcy et al., 2009) have shown that the fluid flow field in the USP 2 apparatus is highly heterogeneous. Velocity vector magnitude and direction are strongly variable throughout the vessel (Figure 12 a)). In the region below the impeller, where the dosage form is typically located, low fluid motion is predicted. Accordingly, the shear rate is very low in this region (Figure 12 b)).

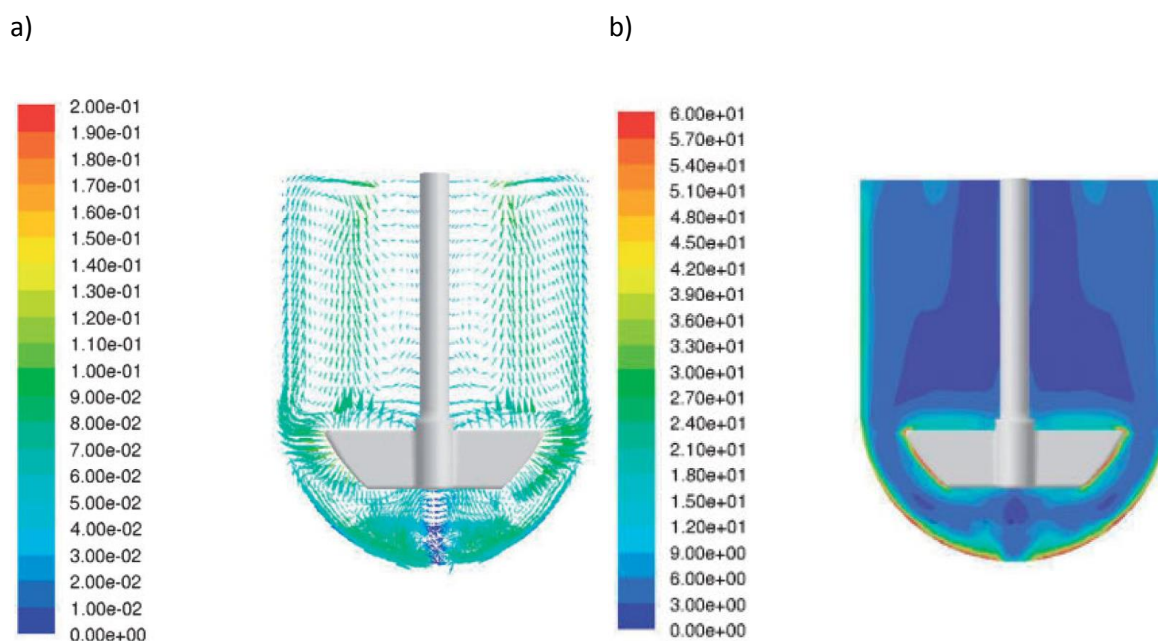


Figure 12: CFD predictions of a) velocity vectors (m/s) and b) strain rate (1/s) on a vertical cross section through the impeller shaft (Bai 2007).

Bai et al. (2011) observed that the flow pattern was nearly independent of the agitation speed. However, local velocity magnitudes increase with increasing agitation speed whereby the velocity in the region below the impeller is less affected by changes in agitation speed. Other studies showed that the hydrodynamics and shear stresses inside the vessel are highly affected by changes in the geometry or location of the impeller (Bai and Armenante, 2008; Ameer and Bouzit, 2013). The dissolution profile was shown to be largely affected by the tablet position due to different shear rates depending on the location (Bai and Armenante, 2009). The results of this study could explain the variability in dissolution testing.

With the help of laser-Doppler velocimetry (LDV), particle image velocimetry (PIV) and planar laser induced fluorescence (pLIF) it was proven that CFD models are able to predict the complex hydrodynamics in the USP apparatus 2 (Bai et al., 2007; Baxter et al., 2005; Kukura et al., 2004).

The above discussed studies show that the CFD approach is capable of predicting complex fluid flows in pharmaceutical test devices. The predicted results visualized and quantified the hydrodynamics and shear rates in the USP dissolution apparatus and helped to explain the problems and variability associated with dissolution testing.

#### *1.4.2 Stomach*

The idea to model the fluid flow field in the human stomach originates from food science. The models were used to gain insights into gastric fluid flow and mixing of food to help to understand food digestion. However, pharmacists can benefit from the results to get an idea of dosage form performance in the stomach. Furthermore, the results can aid to formulate advanced functional dosage forms that are adapted to the gastric environment.

Based on gastric motility patterns and the physicochemical properties of the luminal contents, CFD can be used to examine gastric mixing and digestion. To analyze gastric mixing and digestion a model of the human stomach needs to be constructed. Thereby, it is distinguished between two- and three-dimensional models. Two-dimensional models assume axial symmetry of the stomach and simplify the geometry to one plane. Since this assumption is difficult to justify and the reliability of the results gained with two-dimensional models is questionable, three-dimensional models were developed taking all three dimensions into account. Such models are capable of reconstruct the shape and dimensions of a human stomach in the three-dimensional space. All studies use numerical algorithms to rebuild the geometry of the stomach as a function of time to simulate the propagation of the ACW towards the pylorus.

Initial attempts to numerically model the flow field in the human stomach during digestion were undertaken by Pal et al. (2004). Based on *in vivo* magnetic resonance imaging (MRI) data, the authors constructed a simplified two-dimensional model of the stomach assuming that in axisymmetric geometries the two-dimensional model has the same behavior as a three-dimensional model. The propagation of successive ACWs was simulated using numerical algorithms. The model was used to examine the influence of amplitude and width of the ACW on gastric flow patterns. Two flow patterns inside the stomach were predicted: retroplusive jet-like motions with highest fluid velocities reaching 7.5 mm/s and recirculating flow patterns (eddy structures) between successive ACWs (Figure 13). These predictions are in accordance with MRI results (Boulby et al., 1999). Strongest fluid motions were predicted in the antrum indicating that this is the region of intense mixing and particle breakdown. But, since the stomach is not axisymmetric, the predictions are only of limited value. Furthermore, physical properties of the gastric juice, like viscosity, were not considered.

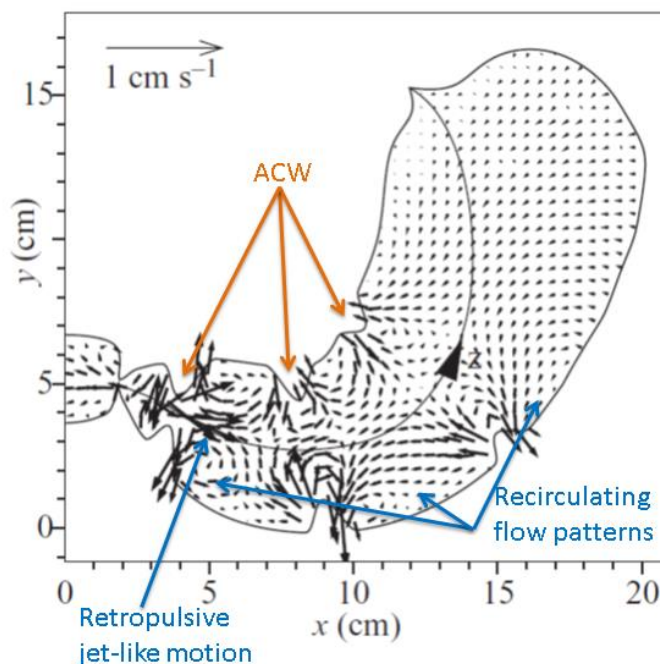


Figure 13: Predicted gastric fluid flow velocity vectors (black) at one time instant (modified from Pal et al., 2004). Due to the propagation of the ACW towards the pylorus the geometry of the stomach is changing continuously. Thus, the flow field is time-dependent and the figure shows an instantaneous snapshot. Two distinct flow patterns were predicted: retroplusive jet-like motions and recirculating structures.

Another two-dimensional CFD study was conducted by Kozu et al. (2010), who examined the influence of fluid viscosity on the flow field. Additionally, attention was paid to fluid shear forces induced by peristaltic flow. As with Pal et al. (2004), the two main flow structures, retroplusive jet and eddy structures, were predicted. Highest retroplusive jet velocities reached 12 mm/s using SGF as model gastric content. The fluid flow velocity in the occluded region was found to be almost independent of the fluid viscosity but the flow velocity backwards the ACW decreased

with increasing fluid viscosity (Figure 14). Maximum shear rates were predicted in the occluded region reaching  $20 \text{ s}^{-1}$ . The shear rate profile was found to be dependent on the fluid viscosity of the model gastric contents.

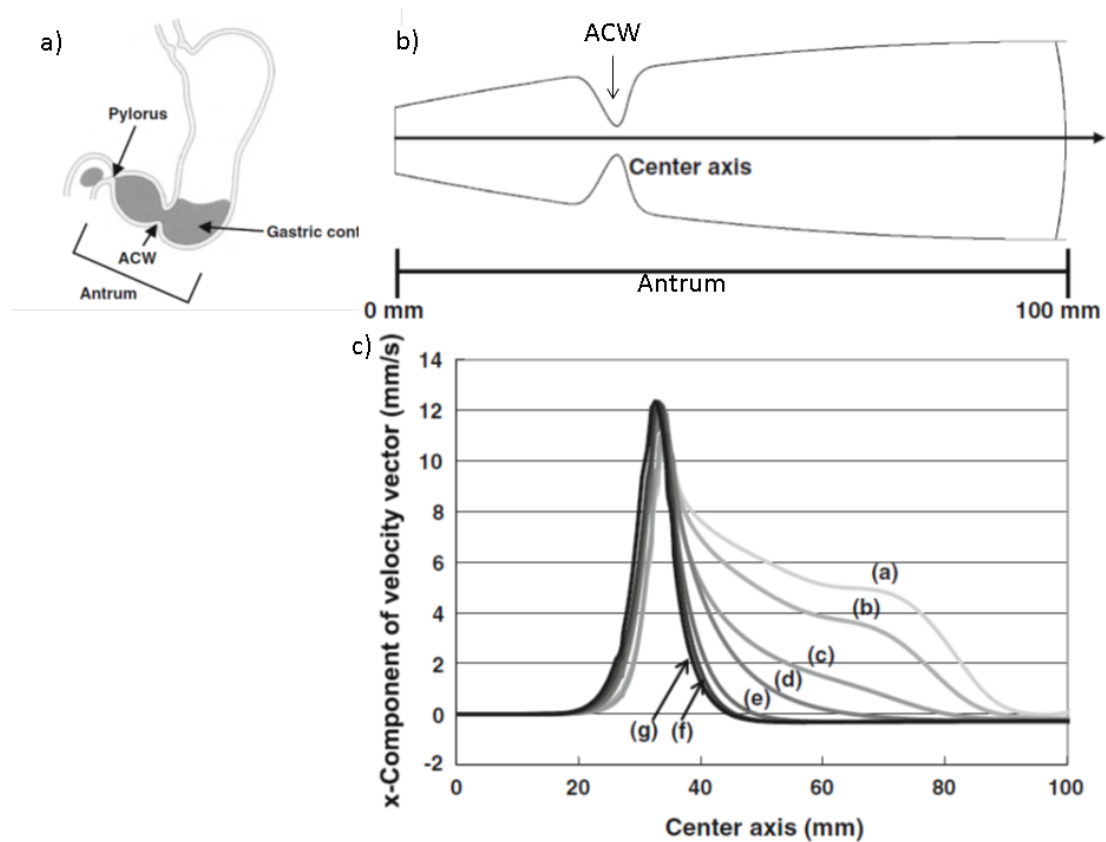


Figure 14: a) Schematic diagram of the cross-sectional stomach shape and peristalsis, b) schematic diagram of the computational domain partly deformed by the ACW ( $t=20 \text{ s}$ ). The computational domain represents the distal part of the stomach, the antrum. The model was simplified to two dimensions. During the time dependent simulation the ACW propagates from the right to the left hand side. c) Velocity profiles along the center axis for different fluid viscosities ((a)  $0.73 \text{ mPa s}$ , (b)  $1.0 \text{ mPa s}$ , (c)  $1.9 \text{ mPa s}$ , (d)  $3.8 \text{ mPa s}$ , (e)  $12.3 \text{ mPa s}$ , (f)  $147 \text{ mPa s}$ , (g)  $4760 \text{ mPa s}$ ) (Kozu et al., 2010).

The first three-dimensional numerical analysis of fluid flow in the human stomach was reported by Ferrua et al. (2010; 2011). A highly three-dimensional flow field was predicted with strongest fluid motions in the lower part of the stomach and slow recirculating flow in the upper part. The two main flow patterns, repulsive jet and eddies, that were already predicted using the two-dimensional models, were also observed with the three-dimensional model (Figure 15). These flow patterns showed a strong viscosity dependence. Using gastric contents of  $1 \cdot 10^{-3} \text{ Pas}$  (1 cP) maximum jet velocity is predicted to be  $76 \text{ mm/s}$ . By increasing the viscosity to  $1 \text{ Pas}$  (1000 cP) highest jet velocity increases to  $119 \text{ mm/s}$  but the jet is restricted to a smaller region. The major shortcomings of this study are the assumption of a fully filled stomach and a constantly closed pylorus.

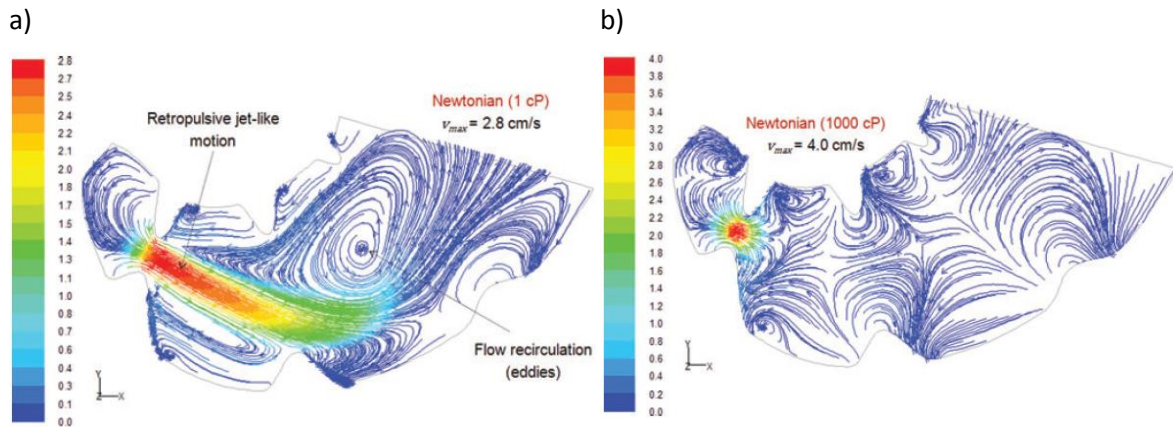


Figure 15: Instantaneous streamlines of gastric flow at  $t=10$  s within the middle plane of the three-dimensional model colored by velocity magnitude (cm/s) (Ferrua and Singh, 2010). a) Newtonian fluid of  $1 \cdot 10^{-3}$  Pas (1 cP), b) Newtonian fluid of 1 Pas (1000 cP). The flow patterns and fluid viscosities show a marked viscosity dependence. By increasing the viscosity retropulsive jet velocities are higher but the jet is restricted to a smaller area compared to lower fluid viscosities.

Recently, Imai et al. (2013) numerically investigated the effects of posture and content volume on the time-averaged flow field using an anatomical model of the stomach. They choose an incompressible Newtonian liquid with a viscosity of 1 Pa s. As already observed in the studies discussed above, a retropulsive jet and recirculating eddies were predicted in the antral region in the upright position (Figure 16). Highest jet velocity is predicted to be 30 mm/s. In supine and lateral positions the jet disappears due to the fact that the antrum is not filled with contents. Only recirculating flow is observed. Regardless of the position, only contents located in the antral recirculation zone are well mixed.

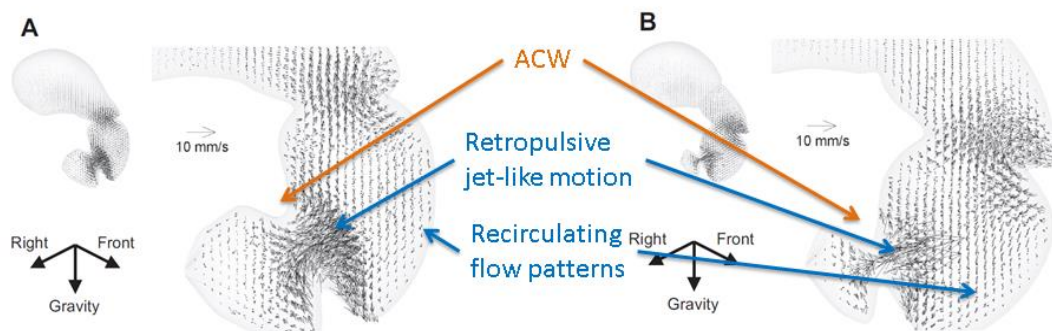


Figure 16: Instantaneous velocity vectors for upright position for two propagation states of the ACW. A)  $t=0$ , B)  $t=1/9T$  ( $T$ = time period) (Imai et al., 2013). Retropulsive flow is observed in the antral lumen narrowed by peristaltic contraction. Large recirculation appears throughout the antrum.

All studies have the occurrence of the retropulsive jet in the antral region and the eddy structures in the distal region in common. The retropulsive jet velocity and length was found to be dependent on the viscosity of the model gastric contents. Highest predicted retropulsive velocities differed strongly in magnitude ranging from 7.5 mm/s predicted by Pal et al. (2004) to 119 mm/s predicted by Ferrua et al. (2011).

## 1.5 Gastroretentive drug delivery systems

Gastroretentive drug delivery systems (GRDDS) belong to the group of controlled release (CR) dosage forms. GRDDS are designed to be retained in the stomach over a prolonged period of time releasing the drug at a slow and constant rate. Several advantages are accompanied with the prolonged gastric residence time. The most important is the enhancement of the bioavailability of drugs with a small absorption window in the upper small intestine. Thereby the therapeutic efficacy is improved, the necessary dose is reduced, and the dosing interval is prolonged. Furthermore, GRDDSs are beneficial for locally active drugs like several antibiotics.

Factors affecting the residence time of GRDDSs in the stomach are size and shape of the dosage form, prandial state of the stomach, gender, age, and posture (Prajapati et al., 2013). The stability of the GRDDSs against hydrodynamic and mechanical forces is critical for their efficiency. Insufficient stability will lead to breakage and loss of release control associated with dose dumping and side effects.

Various approaches and formulations have been investigated since gastroretention has first been mentioned as promising strategy more than 40 years ago (Singh and Kim, 2000). The most common approaches include a) floating or low density systems, b) high density systems, c) swelling or expanding systems, and d) bioadhesive or mucoadhesive systems (Figure 17). Several reviews concerning the different formulation strategies are published (Streubel et al., 2006; Singh and Kim, 2000; Prajapati et al., 2013; Lehr, 1994; Klausner et al., 2003; Bardonnnet et al., 2006; Arora et al., 2005). Therefore, the different approaches will be summarized only briefly within the following sections.

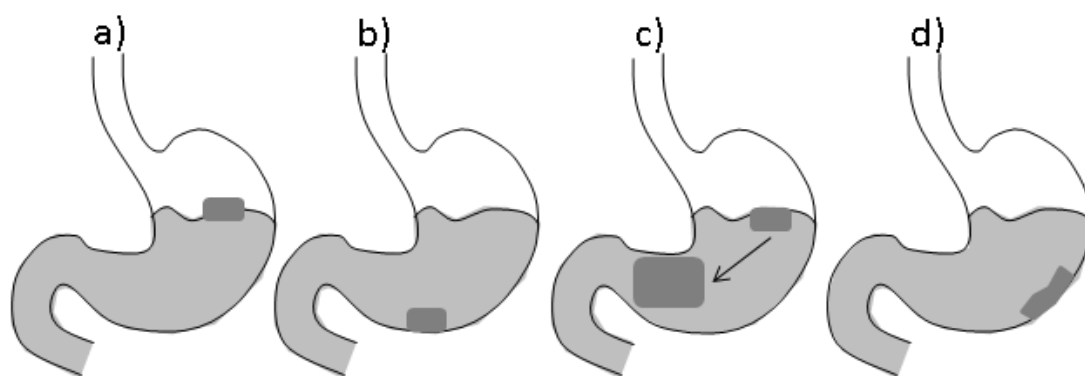


Figure 17: Approaches to achieve gastroretention. a) floating system, b) high density system, c) swelling/expanding system, d) bioadhesive system.

### 1.5.1 Density controlled systems

The group of density controlled systems comprises low as well as high density systems. While low density systems will float on the gastric contents, high density systems will sink to the lower part of the stomach. The density of the gastric juice is reported to be in the range of  $1.004 \text{ g/cm}^3$  (Bardonnnet et al., 2006). Thus, systems with a higher density will settle down and are referred to as high density systems while devices with a lower density will float on the contents and are denoted floating systems.

A density of close to  $2.5 \text{ g/cm}^3$  is necessary to achieve gastro retention via the high density approach (Clarke et al., 1993). Only few research focused on high density systems so far due to the difficulties in achieving sufficient high density. One way to achieve the required density is to coat pellets with heavy inert materials such as barium sulfate, zinc oxide, iron powder, or titanium dioxide (Prajapati et al., 2013). Recently, sinking magnetic microparticles with a maximum density of  $3.52 \text{ g/cm}^3$  were developed (Hao et al., 2014). Still, new technologies and approaches have to be developed to prepare formulations with a sufficiently high density.

In contrast, low density systems are very prevalent and many formulations and approaches have been investigated. The floating properties can be based on several principles including inherent low density, low density due to swelling, and low density due to gas generation and entrapment.

An inherent low density can be achieved by incorporation of low density materials such as fatty substances or foam powder or by entrapment of air. Several hollow chambers, microspheres, and microballoons have been reported providing excellent floating ability (Krögel and Bodmeier, 1999; Kawashima et al., 1992; Sato et al., 2003; Stithit et al., 1998; Ramachandran et al., 2010;

Thanoo et al., 1993). Recently, the incorporation of foam powder was introduced as promising mechanism to achieve floating drug delivery systems (Streubel et al., 2002, 2003).

Floating can also be achieved by swelling. These so called hydrodynamically balanced systems (HBS) consist of gel-forming or highly swellable cellulose derivate hydrocolloids (Singh and Kim, 2000). Upon contact with gastric fluids, water is taken up and the polymers swell to several hundred times of their initial volume. Different polymers have been evaluated for the applicability in HBSs (Dorozyński et al., 2004; Gerogiannis et al., 1993; Baumgartner et al., 2000). The performance of the systems was strongly dependent on the type of polymer, the properties of the polymer, and processing parameters during preparation.

Another principle to provide floating is the generation of carbon dioxide within the device upon contact with acid fluids. The entrapped carbon dioxide provides the floating ability. An acidic component is therefore incorporated into the hydrocolloide matrix of the dosage form. Commonly used compounds are citric acid and sodium bicarbonate (Ingani et al., 1987; Yang and Fassihi, 1996; Rouge et al., 1998; Ichikawa et al., 1991; Li et al., 2003).

Raft forming systems are another type of GRDDSs based on the mechanism of floating. These systems contain a gel forming agent (natural or synthetic polymers such as alginic acid, guar gum, gellan gum, HPMC), effervescent agents and acid neutralizing agents (Mandel et al., 2000; Prajapati et al., 2013). Upon contact with the gastric content a continuous layer floating on top of the stomach content is formed due to gelling of the polymer. Carbon dioxide is generated and entrapped further promoting floating.

The performance of floating drug delivery systems was found to be highly dependent on the filling state of the stomach. It is recommended to administer floating systems after meal ingestion (Agyilirah et al., 1991; Timmermans and Moës, 1994). Regarding published scientific work and output of marketed products floating drug delivery systems are the most important technology among the gastroretentive drug delivery approaches.

### *1.5.2 Swelling/ expandable systems*

Expandable systems are designed to rapidly increase in size upon contact with the stomachs content to prevent their emptying through the pylorus (Klausner et al., 2003). Besides the fast increase in size these systems need to possess sufficient mechanical stability to withstand the hydrodynamic and mechanical forces present in the human stomach. On the other hand, the systems need to degrade after a certain period of time to prevent accumulation following multiple administrations. The large increase in size is reached either by swelling or by unfolding.

Several different shapes and materials were used to prepare unfolding GRDDSs (Cargill et al., 1989; Fix et al., 1993; Kagan et al., 2006; Klausner et al., 2002; Klausner et al., 2003; Sonobe et al., 1991; Curatolo et al., 1995). In order to facilitate swallowing the geometrical devices are folded and placed into capsules. Upon fluid contact the capsule shell dissolves and the device unfolds. The applicability of the unfolding systems is limited due to difficult and cost intensive production.

Size increase can also be reached by swelling. GRDDSs based on this principle contain polymeric hydrogel formers such as polyvinyl pyrrolidone, carbopol, or collagen. Upon contact with fluids they rapidly swell to a few hundred times of their initial weight. Several promising dosage forms are described in the literature (Chen et al., 2000; Deshpande et al., 1997; Shalaby and Park, 1990; Gröning et al., 2007).

### 1.5.3 Bioadhesive systems

Bioadhesive systems contain excipients that mediate adherence to the stomach wall thereby preventing gastric emptying. Several hydrophilic polymers (e.g. crosslinked polyacrylic acids, sodium carboxymethylcellulose, sodium alginate, and carrageenan) possess bioadhesive properties. Several polymers and types of dosage forms have been evaluated for their applicability for gastroretention via bioadhesion including microspheres (Hejazi and Amiji, 2002), microparticles (Cuña et al., 2001), and minitablets (Schmitz et al., 2005). However, only few successful approaches are reported. The main challenge designing bioadhesive dosage forms may be the high turnover rate of the gastric mucus limiting the residence time.

## 1.6 Polyelectrolyte complexes

Polyelectrolytes (PE) are polymers with functional groups that are charged or become charged under suitable conditions (Luo and Wang, 2014). Polycations and polyanions can interact with each other to form a polyelectrolyte complex (PEC). The interactions include electrostatic attraction, dipole-dipole forces, and hydrogen bonds (Il'ina and Varlamov, 2005). Furthermore the formation of the PEC is dependent on the degree of ionization of the PECs, their charge density, their concentration and ratio, and the duration and temperature of formation (Il'ina and Varlamov, 2005).

Several polyelectrolyte complexes have been evaluated for their potential to serve as controlled release drug delivery systems (Moustafine et al., 2013; Moustafine et al., 2005a; Moustafine et

al., 2005b; Moustafine et al., 2006; Obeidat et al., 2008; Park et al., 2008; Prado et al., 2008). Polyelectrolyte complexes are traditionally formed by mixing the solutions of two oppositely charged polymers. Thereby, a reversible electrostatic interaction between the polyelectrolytes is formed. Briefly, solutions of the polyelectrolytes are prepared at the pH where they are soluble. The solutions are mixed whereby the complex is obtained as precipitate that needs to be dried by lyophilization for several days. The powder complex can then be processed to receive the desired dosage form, like tablets or capsules.

Due to the complex and time consuming nature of the traditional manufacturing process, the possibility of an *in situ* polyelectrolyte complex was investigated (Li et al., 2013b; Tapia et al., 2002; Tapia et al., 2004).

Polyelectrolyte complexes for intragastric delivery are rare (Bani-Jaber et al., 2011; de la Torre et al., 2005; Gómez-Burgaz et al., 2008; Ngwuluka et al., 2013). However, due to their high ability to swell and to retard drug dissolution, they are ideal candidates for gastroretentive drug delivery systems. Therefore, this work describes the preparation and evaluation of an *in situ* polyelectrolyte complex for intragastric drug delivery. This approach combines the swelling and floating principle of gastroretention.

## **1.7 The need of a gastroretentive drug delivery system for trospium chloride**

Trospium chloride, 3-(2-hydroxy-2,2-diphenylacetoxy)spiro[bicyclo[3.2.1]octane-8,1'-pyrrolidin]-1'-ium chloride, (Figure 18) is a quaternary amine belonging to the group of muscarinic antagonist urinary antispasmodics. It is indicated for the treatment of overactive bladder with symptoms of urgency, frequency, and urges incontinence. Different commercial oral products are available comprising IR tablets (for example Trospi<sup>®</sup>, Spasmex<sup>®</sup>, Spasmolyt<sup>®</sup>) and CR capsules (Urivex<sup>®</sup>).

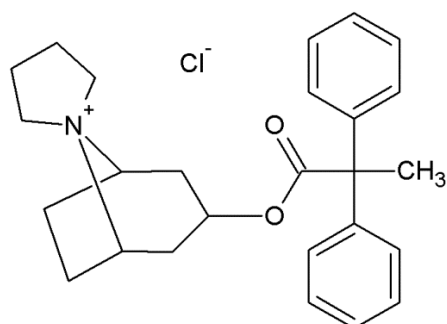


Figure 18: Structure of trospium chloride.

According to the biopharmaceutical classification system (BCS), which classifies APIs by their solubility and permeability, trospium chloride is a BCS class III compound characterized by high water solubility and low permeability. After oral administration the absorption of trospium is slow and incomplete. The reported mean bioavailability is approximately 10 % (Doroshenko et al., 2005). Concomitant food intake further decreases the bioavailability. The low bioavailability is potentially due to the small absorption window for trospium which is located in the upper part of the small intestine (Schröder et al., 2004). The drug can only be absorbed when it reaches this absorption window in dissolved form (Figure 19). A retarded formulation is therefore not suitable for the delivery since all drug released following the absorption window cannot be absorbed. A gastroretentive formulation, releasing the drug constantly in the stomach, is a more promising approach to enhance the low bioavailability.

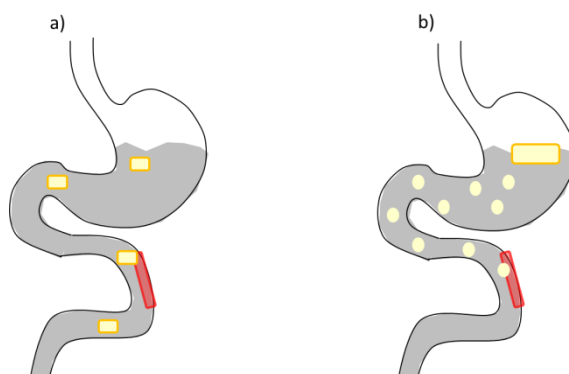


Figure 19: Drug absorption from a) controlled release dosage form and b) gastroretentive dosage form.

## 2 Aims

Solid oral dosage form disintegration in the human stomach is a highly complex process dependent on physicochemical properties of the stomach contents as well as on physical variables such as hydrodynamics and mechanical stress. The PhEur recommends a simple test device to evaluate disintegration times *in vitro*. However, in recent years knowledge about the *in vivo* conditions has grown. With this new knowledge the demand for biorelevant *in vitro* testing emerged and several biorelevant *in vitro* dissolution test devices have been introduced lately. However, disintegration testing has been neglected so far. Understanding the role of hydrodynamics and forces in disintegration and dissolution of oral solid dosage forms can help to improve *in vitro* disintegration testing and the predictive power of the *in vitro* test.

In this work the hydrodynamic conditions and forces in the compendial PhEur disintegration test device should be investigated using computational fluid dynamics (CFD). Fluid velocity and shear stress on tablet surface should be quantified under simulating fasted and fed fluid characteristics. To validate the computer simulation results experimental particle image velocimetry (PIV) should be utilized. The predicted results should be compared to literature data to evaluate the biorelevance of the compendial device.

Moreover, a modified disintegration test device should be constructed to mechanistically investigate the influence of fluid velocity and pressure forces on disintegration of solid oral dosage forms. The modified device should allow simple handling to be suitable for routine testing. In addition, it should be possible to vary moving velocity as well as applied pressure over a wide range. Furthermore, the modified device should not be limited to vertical movement like the compendial device but movement in the three-dimensional space should be possible. *In vitro* experiments should be conducted utilizing the modified device to determine disintegration times of immediate release (IR) tablets. Hydrodynamic conditions and pressure forces should be varied to simulate both, the fasted and the fed state. The relationship between model medium, moving velocity, applied pressure, simulated shear stress and disintegration times should be investigated.

Furthermore, a gastroretentive drug delivery system should be developed to enhance the low bioavailability of the BCS III compound trospium chloride. The approach of an *in situ* polyelectrolyte complex should be verified. By this means, a strong polymeric network should form upon contact with the stomach content to swell to a size too large to be emptied from the stomach. Due to the expected low density of the matrices the systems are furthermore

supposed to float on the gastric content. Thereby two mechanisms of gastroretention are utilized: swelling and floating. The *in vitro* evaluation of the matrices should comprise the common techniques to evaluate the density, the degree of swelling, the mechanical stability, and the drug release.

The resistance of gastroretentive drug delivery systems against hydrodynamic and shear stresses present in the human stomach is essential for treatment success. Therefore, the degree of swelling and the drug release should be tested utilizing the new modified disintegration test device. The results should be compared with those of the classical *in vitro* tests.

## 3 Materials and Methods

### 3.1 The modified disintegration test device

The modification of the compendial PhEur disintegration test device comprised three alterations:

- Movement by a computerized numerical control (CNC)

By this modification the simulation of biorelevant moving velocities and profiles is possible. While the movement of the basket is restricted to a sinusoidal vertical movement using the compendial device various movement profiles in all three dimensions can be generated using the modified device. The movement of the basket is accomplished by a thooted belt CNC drive (LEZ 1, Isel Germany AG, Eichenzell, Germany) with high-torque stepping motor (MS045HT, Isel Germany AG, Eichenzell, Germany) and 1:2 gear, that is controlled by a 4- axis stepping motor controller (CSD 405-IMC, Isel Germany AG, Eichenzell, Germany). The program coding for the movement of the drive was written in ProNC (Isel Germany AG, Eichenzell, Germany) (see 8.3). All investigations performed in this work concentrate on the vertical movement of the basket.

- Construction of a modified basket with open mesh structure

The advantage of the modified basket is its open design. While the fluid is restricted to the tubes using the compendial basket, two-sided fluid flow is occurring using the modified basket. The module consists of three quadratic probe chambers, where the chamber dimensions and volume are referring to the descriptions of the compendial device given in the PhEur. The front and back side of the probe chambers is made of wire mesh with a mesh size of 2 mm and 0.5 mm wire diameter (EKA, Bergisch Gladbach, Germany) allowing two-sided fluid flow. All solid parts are made of polyethylene. Schematic diagrams, pictures and dimensions of the modified basket are given in the results section (4.2) and in the appendix (8.2). The modified device can be operated with both basket designs.

- Simulation of forces by balloons

The modified basket can further be equipped with balloons to simulate biorelevant pressure forces on the tablet surface. Therefore, cutaways are milled into the lateral polyethylene chamber boundaries, in which the balloons can be clamped (picture see results section 4.2). Inflation and deflation of the balloons is accomplished by the in-house built computerized pressure-vacuum unit 'DisPress' (description see appendix 8.2).

## 3.2 Computational fluid dynamics (CFD)

Computational fluid dynamics is a powerful tool to examine fluid flow phenomena numerically. In this work the CAD software SolidWorks (Dassault Systèmes SolidWorks Corporation, Waltham, Massachusetts, USA) was used for construction of the geometry and for calculating the solution of the fluid flow problems.

Simulations were performed for the PhEur/USP disintegration test device (3.2.2) and an in-house built modified test device where the design of the basket was also modified (3.2.4).

### 3.2.1 Governing equations (from (SolidWorks Flow Simulation 2012 Technical Reference))

SolidWorks flow simulation solves the Navier-Stokes equations to predict the fluid flow field. Those comprise the conservation of mass, momentum, and energy:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i) = 0 \quad (3)$$

$$\frac{\partial \rho u_i}{\partial t} + \frac{\partial}{\partial x_j} (\rho u_i u_j) + \frac{\partial p}{\partial x_i} = \frac{\partial}{\partial x_j} (\tau_{ij} + \tau_{ij}^R) + S_i \quad i = 1, 2, 3 \quad (4)$$

$$\frac{\partial \rho H}{\partial t} + \frac{\partial \rho u_i H}{\partial x_i} = \frac{\partial}{\partial x_i} (u_j (\tau_{ij} + \tau_{ij}^R) + q_i) + \frac{\partial p}{\partial t} - \tau_{ij}^R \frac{\partial u_i}{\partial x_j} + \rho \varepsilon + S_i u_i + Q_H \quad (5)$$

$$\text{with } H = h + \frac{u^2}{2}$$

where  $u$  is the fluid velocity,  $\rho$  is the fluid density,  $S_i$  is a mass-distributed external force per unit mass due to a porous media resistance ( $S_i^{porous}$ ), a buoyancy ( $S_i^{gravity} = -\rho g_i$ , where  $g_i$  is the gravitational acceleration component along the  $i$ -th coordinate direction), and the coordinate system's rotation ( $S_i^{rotation}$ ),  $h$  is the thermal enthalpy,  $Q_H$  is a heat source or sink per unit volume,  $\tau_{ik}$  is the viscous shear stress tensor,  $q_i$  is the diffuse heat flux.

To predict turbulent flows, the Favre-averaged Navier-Stokes equations are used. Through this procedure, extra terms appear in the equations. The shear stress tensor and the Reynolds-stress tensor are defined as follows:

$$\tau_{ij} = \mu \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \frac{\partial u_k}{\partial x_k} \right) \quad (6)$$

$$\tau_{ij}^R = \mu_t \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \frac{\partial u_k}{\partial x_k} \right) - \frac{2}{3} \rho k \delta_{ij} \quad (7)$$

with  $\delta_{ij}$  the Kronecker delta function,  $\mu$  the dynamic viscosity coefficient,  $\mu_t$  the turbulent eddy viscosity coefficient and  $k$  the turbulent kinetic energy.  $\mu_t$  and  $k$  are zero for laminar flow.

To calculate turbulent kinetic energy and its dissipation the  $k - \varepsilon$  model is employed. In the frame of this model the turbulent eddy viscosity coefficient is defined as:

$$\mu_t = f_\mu \frac{C_\mu \rho k^2}{\varepsilon} \quad (8)$$

with  $k$  the turbulent kinetic energy and  $\varepsilon$  the turbulent dissipation.  $f_\mu$  is a turbulent viscosity factor defined by:

$$f_\mu = [1 - \exp(-0.025R_y)]^2 \left( 1 + \frac{20.5}{R_T} \right) \quad (9)$$

$$\text{where } R_T = \frac{\rho k^2}{\mu \varepsilon} \text{ and } R_y = \frac{\rho \sqrt{k} y}{\mu}.$$

The following equations are used to describe the turbulent kinetic energy and dissipation:

$$\frac{\partial \rho k}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i k) = \frac{\partial}{\partial x_i} \left( \left( \mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_i} \right) + S_k \quad (10)$$

$$\frac{\partial \rho \varepsilon}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i \varepsilon) = \frac{\partial}{\partial x_i} \left( \left( \mu + \frac{\mu_t}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_i} \right) + S_\varepsilon \quad (11)$$

$$\text{with } S_k = \tau_{ij}^R \frac{\partial u_i}{\partial x_j} - \rho \varepsilon + \mu_t P_B \quad (12)$$

$$\text{and } S_\varepsilon = C_{\varepsilon 1} \frac{\varepsilon}{k} \left( f_1 \tau_{ij}^R \frac{\partial u_i}{\partial x_j} + \mu_t C_B P_B \right) - C_{\varepsilon 2} f_2 \frac{\rho \varepsilon^2}{k} \quad (13)$$

$P_B$  represents the turbulent generation due to buoyancy forces and is defined as:

$$P_B = -\frac{g_i}{\sigma_B} \frac{1}{\rho} \frac{\partial \rho}{\partial x_i} \quad (14)$$

where  $g_i$  is the gravitational acceleration in direction  $x_i$ ,  $\sigma_B = 0.9$ , and  $C_B=1$  when  $P_B > 0$  and 0 otherwise.  $f_1$  and  $f_2$  are defined as follows:

$$f_1 = 1 + \left( \frac{0.05}{f_\mu} \right)^3, \quad f_2 = 1 - \exp(-R_T^2) \quad (15)$$

The following constants are defined empirically;  $C_\mu = 0.09$ ,  $C_{\varepsilon 1} = 1.44$ ,  $C_{\varepsilon 2} = 1.92$ ,  $\sigma_\varepsilon = 1.3$ , and  $\sigma_k = 1$ .

### 3.2.2 Simulations in the PhEur disintegration apparatus

#### 3.2.2.1 Geometry

The geometry of the basket-rack assembly with surrounding beaker was reconstructed according to the depiction and dimensions mentioned in the PhEur (Ph.Eur., European Pharmacopoeia, 2014; see also Figure 3). The beaker was constructed with 149 mm height and an inner diameter of 106 mm. Since the requirement for an internal fluid flow analysis is a closed geometry, the beaker was closed with a lid at the top. The glass tubes are 77.5 mm in length with an inner diameter of 21.88 mm and a wall thickness of 1.9 mm. Both plates, keeping the tubes in the vertical position, have a diameter of 90 mm and a thickness of 6.75 mm. The mesh was constructed with a mesh size of 2 mm and a wire diameter of 0.615 mm. A tablet of 9 mm diameter and 5 mm height was placed in one of the tubes. Simulations were run under the condition that the tablet is fixed at the wire mesh. Although this assumption does not

necessarily mimic the actual situation in the disintegration tester, it should be preferable due to the defined position of the tablet when exposed to the hydrodynamic conditions. Figure 20 shows the reconstructed geometry of the PhEur basket-rack assembly.

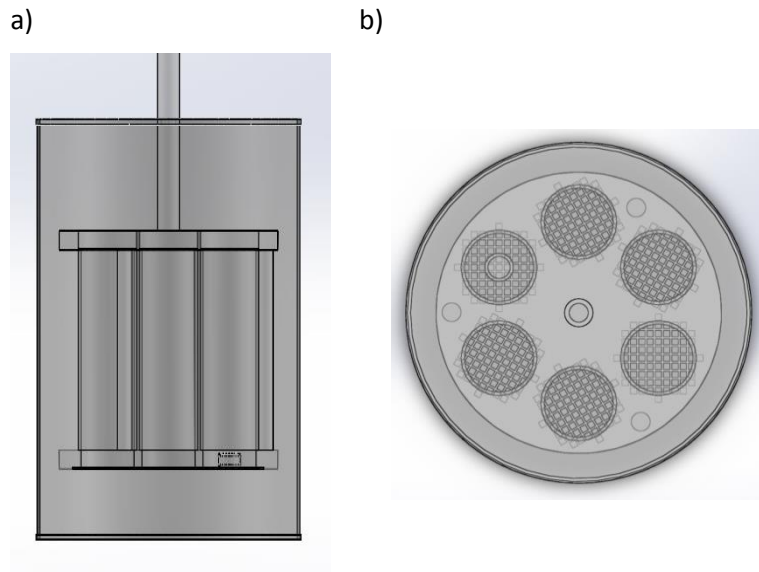


Figure 20: Reconstructed CFD geometry of PhEur basket-rack assembly with surrounding beaker. a) Front view, b) top view.

### 3.2.2.2 CFD setup

The setup used for this study is summarized in Table 3. The solution of the fluid flow in the basket-rack assembly requires an internal analysis. Furthermore, the analysis is time dependent due to the sinusoidal movement profile discussed in 1.1.2 and described by eqn. ( 2 ). Different model liquids and pasty foods were chosen as model fluids to examine the influence of viscosity on hydrodynamics. The properties of the fluid are discussed in detail in section 3.2.6. For the Newtonian fluids the laminar and turbulent flow type was selected. For non-Newtonian fluids the flow type is set to laminar only by default and cannot be changed. The temperature of the system was set to 37 °C.

### 3 Materials and Methods

Table 3: CFD setup of the investigations in the PhEur disintegration test device.

<u>Analysis type:</u>	
Analysis type	Internal
Exclude cavities without flow conditions	Yes
Heat conduction in solids	No
Radiation	No
Time dependent	Yes
Gravity	-9.81 m/s in y-plane
Rotation	No
<u>Fluids:</u>	
Project fluids	SGF, apple juice, tomato juice, champignon soup, tomato soup, 1.4 % HPMC solution, FDA meal
Flow type	Laminar and turbulent for Newtonian fluids Laminar only for non-Newtonian fluids
<u>Wall conditions:</u>	
Wall thermal condition	Adiabatic
Wall roughness	0 micrometer
<u>Initial conditions:</u>	
Pressure	101324 Pa (760 mm Hg)
Pressure potential	Yes
Temperature	310.2 K
Velocity in x-direction	0 m/s
Velocity in y-direction	0 m/s
Velocity in z-direction	0 m/s
Turbulence intensity	2 %
Turbulence length	0.001 m

### 3.2.2.3 *Boundary conditions*

To solve the governing equations it is necessary to apply boundary conditions to the model. By default the velocity boundary condition at all solid walls is set to non-slip. Atmospheric pressure was applied to the top lid of the beaker. The bottom of the beaker was defined as fluid inlet and outlet for the down and up movement, respectively. The fluid velocity at the inlet and outlet followed the sinusoidal profile described by eqn. ( 2 ). The fluid flow condition was set to fully developed. The wall of the beaker was defined as a real wall with no roughness and moved together with the fluid.

### 3.2.2.4 *Grid settings*

To solve the governing equations over the fluid containing domain, the domain must be separated into small elements, generally known as mesh or grid. The smaller the cell of the grid, the more accurate the solution. However, with more cells, the computational effort increases and the more computational power is required. Thus, the level of the grid always is a compromise of accuracy and calculation time needed.

SolidWorks Flow Simulation possesses an automatic mesh generation tool which applies a rectangular element mesh to the computational domain to differentiate between solid and fluid cells. Varying levels, ranging from 1 to 8, can be selected by the user, with 1 being the coarsest mesh and 8 being the most refined. For the Newtonian fluids, level 8 was applied. Due to computational limitations, the mesh level was reduced to 5 for the non-Newtonian fluids.

## 3.2.3 *Validation*

To validate the CFD results, the predicted data was compared to experimental data obtained from particle image velocimetry (PIV) (see 3.3). Therefore, the velocity inlet boundary condition was changed to a constant velocity of 0.06 m/s which is similar to the fluid velocity applied in the PIV experiment. The model fluid was SGF.

## 3.2.4 *Simulations in the modified disintegration apparatus*

### 3.2.4.1 *Geometry*

The geometry of the modified basket was reconstructed according to the illustration and dimensions of the technical drawing (Appendix 8.2). The beaker was constructed with 145 mm height and an inner diameter of 103 mm. Since the requirement for an internal fluid flow

analysis is a closed geometry, the beaker was closed with a lid at the top. Each of the three probe chambers is a rectangle of 22\*25 mm. The solid boundaries of the chambers are 84 mm in height with a thickness of 0.7 mm. The mesh was constructed with a mesh size of 2 mm and a wire diameter of 0.5 mm. A tablet of 9 mm diameter and 5 mm height was placed in the middle probe chamber. Simulations were run under the condition that the tablet is fixed at the wire mesh. Although this assumption does not necessarily mimic the actual situation in the disintegration tester, it should be preferable due to the defined position of the tablet when exposed to the hydrodynamic conditions. Figure 21 shows the reconstructed geometry of the modified basket design.

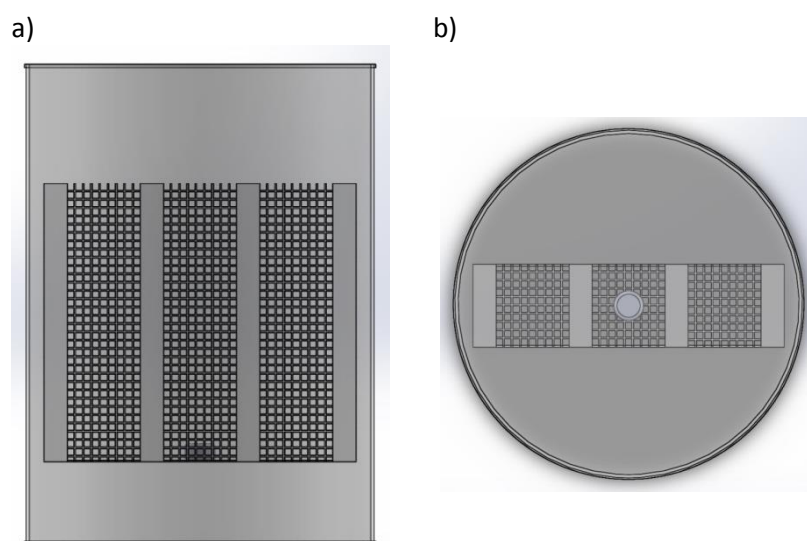


Figure 21: Reconstructed CFD geometry of modified basket with surrounding beaker. a) Front view, b) top view.

#### 3.2.4.2 CFD setup

The setup used for this study is summarized in Table 4. The solution of the fluid flow problem requires an internal analysis. Furthermore, the analysis is time dependent. SGF, 1.4 % HPMC solution, and FDA meal were chosen as model fluids to examine the influence of viscosity on hydrodynamics. The properties of the fluid are discussed in detail in section 3.2.6. For the Newtonian fluids the laminar and turbulent flow type was selected. For non-Newtonian fluids the flow type is set to laminar only by default and cannot be changed. The temperature of the system was set to 37 °C. The velocity in y-direction was set to 0.08 m/s.

Table 4: CFD setup modified disintegration test device.

<u>Analysis type:</u>	
Analysis type	Internal
Exclude cavities without flow conditions	Yes
Heat conduction in solids	No
Radiation	No
Time dependent	Yes
Gravity	-9.81 m/s in y-plane
Rotation	No
<u>Fluids:</u>	
Project fluids	SGF, 1.4 % HPMC solution, FDA meal
Flow type	Laminar and turbulent for Newtonian fluids Laminar only for non-Newtonian fluids
<u>Wall conditions:</u>	
Wall thermal condition	Adiabatic
Wall roughness	0 micrometer
<u>Initial conditions:</u>	
Pressure	101324 Pa (760 mm Hg)
Pressure potential	Yes
Temperature	310.2 K
Velocity in x-direction	0 m/s
Velocity in y-direction	0.08 m/s
Velocity in z-direction	0 m/s
Turbulence intensity	2 %
Turbulence length	0.001 m

#### 3.2.4.3 *Boundary conditions*

To solve the governing equations it is necessary to apply boundary conditions to the model. By default the velocity boundary condition at all solid walls is set to non-slip. Atmospheric pressure was applied to the top lid of the beaker. The bottom of the beaker was defined as fluid inlet. The fluid velocity at the inlet was set to 0.08 m/s. The fluid flow condition was set to fully developed.

#### 3.2.4.4 *Mesh settings*

Section 3.2.2.4 gives a detailed description of the meshing process. For this analysis the mesh level was set to 5 for all simulations.

#### 3.2.5 *What if study*

A ‘what if’ study allows to perform a set of calculations varied by selected parameters. Variable parameter can be model dimensions, initial settings as well as boundary conditions. In the present study the inlet fluid velocity, the model fluid, and the tablet size were varied (Table 5). The ‘what if’ study was performed with the model of the modified basket design only. The study comprised 30 calculation runs.

Table 5: Parameters and values examined in the what if study.

Parameters	Values
Inlet velocity [m/s]	0.02 , 0.04, 0.06, 0.08, 0.1
Tablet diameter [m]	0.005, 0.009, 0.013
Fluid	SGF, 1.4 % HPMC solution

#### 3.2.6 *Media*

Simulations in the PhEur disintegration tester were run with different types of beverages and pasty foods to examine the effect of viscosity on the flow field and forces: SGF, apple juice, orange juice, champignon soup, tomato soup, and mashed FDA meal. Additionally, 1.4 % HPMC solution was used as model fluid since it was recently proposed as suitable surrogate for diluted mashed FDA meal to simulate food effect on tablet disintegration (dilution of 460 mL meal with 240 mL of water) (Radwan et al., 2012). However, to deeply investigate the effect of viscosity, the dilution of mashed FDA meal with water was not considered here. Simulations in the modified disintegration device were run with SGF, 1.4 % HPMC solution, and mashed FDA meal. Finally, the ‘what if’ study was performed with SGF and 1.4 % HPMC solution only.

Some physicochemical parameters of the fluids are listed in Table 6. Simulated gastric fluid (SGF), which in terms of viscosity is equal to the simulated intestinal fluid (SIF), apple juice and orange juice are Newtonian fluids, i. e. their viscosity is not influenced by the shear rate. In contrast, champignon soup, tomato soup, and mashed FDA meal exhibit non-Newtonian flow behavior, in which the viscosity decreases with increasing shear rate. This is important to consider because of the different shear stresses during a cycle of up and down movement due to the sinusoidal velocity profile.

Table 6: Viscosities and densities of the different model media.

Medium	Viscosity [mPa*s]	Density [g/L]	Flow behavior
SGF	0.817*	0.997*	Newtonian
Apple juice	1.062*	1.031*	Newtonian
Orange juice	3.367*	1.034*	Newtonian
Champignon soup	Shear rate-viscosity profile	1.007*	non-Newtonian
Tomato soup	Shear rate-viscosity profile	1.002*	non-Newtonian
Mashed FDA meal	Shear rate-viscosity profile	0.992*	non-Newtonian
1.4 % HPMC solution	Shear rate-viscosity profile	1.031	non-Newtonian

\*: from (Radwan et al., 2014)

The rheological profiles of champignon soup, tomato soup, 1.4 % HPMC solution, and mashed FDA meal (Figure 22) were experimentally measured using a Haake Rheostress 1 viscosimeter (Thermo Fisher Scientific, Karlsruhe, Germany), operating at room temperature at shear rates in the range of 0 to 600  $s^{-1}$ . Data from rheological measurements were evaluated using the attached RheoWin 4 data manager software. The shear stress-viscosity rheograms were loaded into the fluid characteristics description of the software SolidWorks to account for the non-Newtonian behavior. The software corrects the inserted values for the 37 °C used in this study and adjusts the viscosity data for this temperature.

Champignon and tomato soup (Le Gusto, Dr. Lange & Co., GmbH, Düsseldorf, Germany) were prepared by dissolving the content of the sachets in 500 mL boiling water. The homogenized FDA meal was prepared of 2 slices of toasted white bread with butter, 2 eggs fried in butter, 2 slices of bacon, 2 ounces of hash browned potatoes and 8 ounces of whole milk and thoroughly homogenized using an immersion blender. No further dilution with water was performed to emphasize the effect of viscosity on hydrodynamics. Therefore, the viscosity of the mashed FDA meal is higher compared to that of champignon soup, tomato soup, and 1.4 % HPMC solution over the whole range of shear stress. The addition of 240 mL of water as proposed by Radwan

et al. (2012) and recommended by the FDA, will result in a similar rheological profile as those obtained for champignon soup, tomato soup, and 1.4 % HPMC solution.

To prepare the HPMC solution, SGF was heated to boiling. 1.4 % HPMC E4M (w/w) was added under stirring. The suspension was left to cool over night with continuous stirring to dissolve the HPMC. After stirring over night the solution was clear.

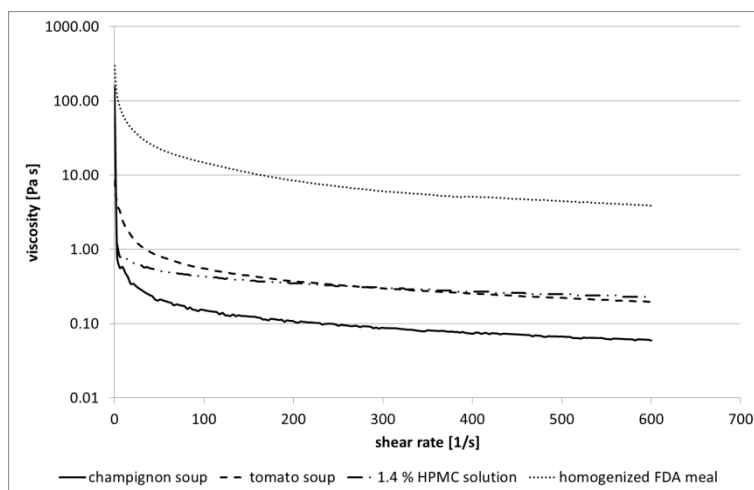


Figure 22: Rheological profiles of champignon soup, tomato soup, 1.4 % HPMC solution, and the mashed FDA meal. Note that the viscosity of the mashed FDA meal used in this thesis is higher compared to that of the 1.4 % HPMC solution. This is due to the fact that it was refrained from dilution with 240 mL water, as recommended by Radwan et al. (2012) and the FDA, to emphasize the effect of viscosity on hydrodynamics. The addition of 204 mL of water will result in a similar profile as that obtained for 1.4 % HPMC solution.

### 3.3 Particle image velocimetry

Particle image velocimetry (PIV) is an optical method to determine 2 dimensional flow fields. Figure 23 shows the experimental setup used for the PIV measurements.

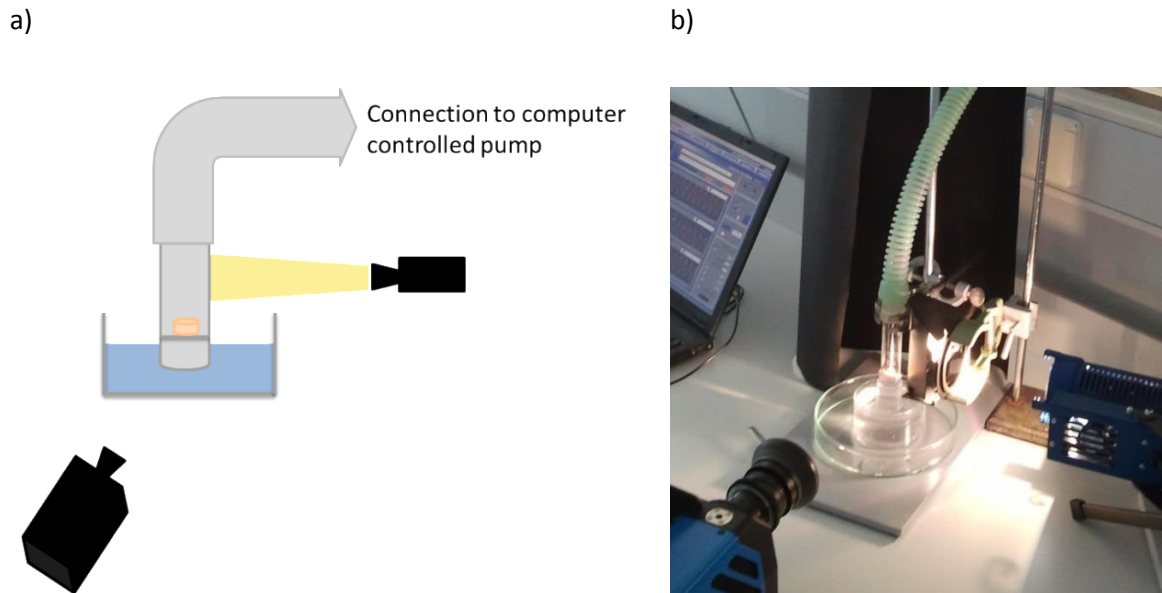


Figure 23: Experimental setup of particle image velocimetry experiments. a) Schematic representation, b) laboratory setup.

A tube of the compendial disintegration test device was closed at the bottom by a wire mesh. An in-house built plastic dummy tablet (9 mm in diameter) was fixed on the wire mesh in the center of the tube. The bottom of the tube with the tablet was immersed in water containing aluminum glitter as tracer particles. The top of the tube was plugged into a pipe which was connected to a computer controlled pump. With the help of the computer control, the fluid was pumped up and down with constant velocity (0.06 m/s). The setup comprised furthermore a lamp and optics with a slit aperture to generate a light sheet. The particles in the plane of the light sheet were illuminated and recorded by the high speed camera in millisecond intervals.

For the evaluation of the data and calculation of velocity magnitude, four successive pictures were analyzed. A line was drawn 10 mm above the mesh. The x-and y-coordinate of several particles on this line was determined. By the knowledge of the time span between the pictures the velocity in y-and x-direction was calculated. The mean of the four successive velocities was calculated.

### 3.4 Disintegration testing of immediate release tablets

All disintegration studies were performed using the modified disintegration test device described in 3.1 and 8.2 using 800 mL of medium (SGF or 1.4 % HPMC solution, see 3.2.6). The compendial as well as the modified basket design were employed. Immediate release (IR) tablets were manufactured to examine the influence of hydrodynamics and pressure forces on disintegration time. The composition of the investigated immediate release tablets is given in Table 7. The powders were mixed thoroughly using a turbula mixer (Willy A. Bachofen AG Maschinenfabrik, Muttenz, Switzerland) and compressed to 500 mg tablets (diameter 12 mm) on an eccentric press (Korsch EKO, Korsch AG, Berlin, Germany). The compression force was adjusted to 1, 2, 3, and 4 t to get batches with different tablet hardness.

Table 7: Composition of immediate release tablets.

Excipient	Percentage
Lactose (Pharmatose® DCL 11, DMV international, Veghel, The Netherlands)	93
Polyvinylpyrrolidone K90 (Carl Roth GmbH, Karlsruhe, Germany)	2
Talc (Fagron, Barsbüttel, Germany, Ph Eur quality)	2
Aerosil (Fagron, Barsbüttel, Germany; Ph Eur quality)	2
Magnesium stearate (Caelo, Hilden, Germany; Ph Eur quality)	1

The influence of moving speed along the vertical axis, medium viscosity, and compression force on disintegration time of IR tablets was investigated. Since the modified disintegration tester can be operated with both, the compendial and the modified, basket design, the influence of basket design can also be examined. To investigate the influence of these factors on disintegration time, a design of experiments (DoE) was created using the software MODDE (Umetrics, Umea, Sweden). Two separate designs were created for the compendial basket design and the modified basket design. The factors and their level are summarized in Table 8 and the worksheet is depicted in the appendix 8.4.

Table 8: Settings of the factors used for the DoE.

Parameter	Low level	High level
Moving speed [mm/s]	40	80
Medium Viscosity [% HPMC]	0	1.4
Compression force [t]	Multilevel: 1, 2, 3, 4	

For comparison purpose, the disintegration times of commercial available calibrator tablets mainly composed of lactose (RS tablets, Erweka, Heusenstamm, Germany) were measured utilizing the modified disintegration test device equipped with the compendial basket and operating at 40 and 80 mm/s in SGF and 1.4 % HPMC solution.

The programming software ProNC (isel Germany AG, Eichenzell, Germany) was used to write the application program of the CNC controller (Appendix 8.3). This program controls the vertical movement of the arm with constant velocity. Disintegration times were investigated at different moving speeds of 20, 40, 60, 80, and 100 mm/s.

For measurements, investigating the influence of pressure on disintegration time, the modified basket was equipped with balloons. Inflation and deflation was accomplished by the in-house built computerized pressure-vacuum unit (8.2). The balloons were inflated to 100 mbar every 10 s.

### **3.5 Development and in vitro evaluation of a gastroretentive drug delivery system**

#### **3.5.1 Materials**

A gastroretentive drug delivery system based on a polyelectrolyte complex should be developed and evaluated *in vitro*. Thereby, the polyelectrolyte complex should form *in situ*, in contrast to the traditional strategy of forming the complex in solution. Hence, both polyelectrolytes need to be ionized in the pH range of the stomach. Two natural polyelectrolytes that accomplish this requirement are chitosan and carrageenan.

##### **3.5.1.1 Chitosan**

Chitosan (Figure 24) is a natural polysaccharide composed of repeating glucosamine and N-acetyl glucosamine units. It is obtained by N-deacetylation of chitin, which is found in the exoskeleton of crustaceans, insects, and fungi. In acidic medium the amino groups become protonated resulting in high charge density making it an ideal candidate to form a polyelectrolyte complex interaction. Due to its good solubility in acidic medium chitosan alone has limited capability for controlling drug release.

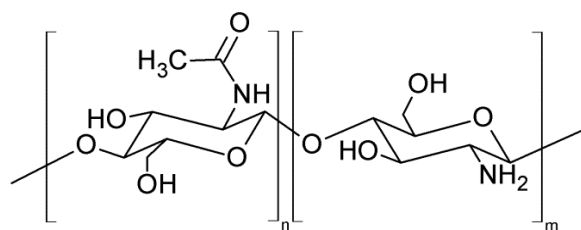


Figure 24: Structural formula of chitosan.

In this study three different types of chitosan were utilized to examine the influence of the degree of deacetylation and the viscosity on the formation of a polyelectrolyte complex and on the physicochemical stability. All types were purchased from Heppe Medical Chitosan (Heppe Medical Chitosan, Halle, Germany). Table 9 lists the specifications of the used types of chitosan 80/1000, 80/500, and 95/500. The first value in the names states the degree of deacetylation and the second the viscosity.

Table 9: Specifications of chitosan.

	95/500	80/500	80/1000
Degree of deacetylation	94.9 %	78 %	79.8 %
Viscosity (1 % in 1% acetic acid, 20 °C)	364 mPa s	710 mPa s	1037 mPa s
pH (10 g/L in 1% acetic acid, 20 °C)	3.0-4.0	3.0-4.0	3.0-4.0

### 3.5.1.2 Carrageenan

Carrageenan is a natural, sulphated polysaccharide consisting of galactose and 3,6-anhydrogalactose units. In acidic medium the sulfate groups become deprotonated resulting in high charge density making it an ideal candidate to form a polyelectrolyte interaction. Two types of carrageenan, namely iota-carrageenan 379 and lambda-carrageenan 209 (Figure 25), were utilized in this work. Both were kindly provided by IMCD/ FMC BioPolymer (IMCD Germany GmbH & Co. KG, Cologne, Germany). Table 10 lists the specifications of the used types of carrageenan.

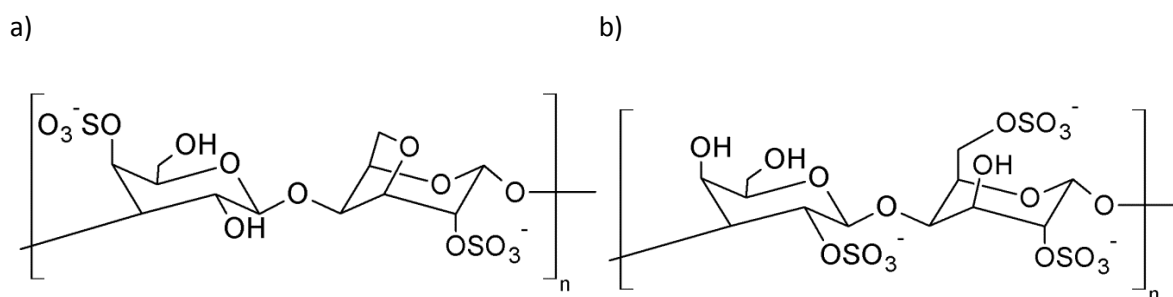


Figure 25: Structural formula of carrageenan a) iota carrageenan 379, and b) lambda- carrageenan 209.

Table 10: Specifications of carrageenan.

	lota-carrageenan 379	Lambda-carrageenan 209
Anionic groups per monomer unit	2	3
Viscosity (water viscosity 1.5 %)	40	590
pH (1.5 %)	9.6	9.6

### 3.5.2 Methods

#### 3.5.2.1 Preparation of capsules

The polymers were mixed and homogenized using a mortar and pestle. For dissolution experiments 30 mg of trospium chloride as model drug were incorporated. The mixture was filled into hard gelatin capsules size 0 using the manual filling device Aponorm® (Wepa, Hillscheid, Germany). Table 11 lists the combinations of polymers and their ratio (w:w) investigated in this study. Polyelectrolyte complexes with ratios of chitosan: lambda-carrageenan 209 = 1:1 (w:w), chitosan: iota-carrageenan 379 = 1:1 (w:w) and chitosan: iota-carrageenan 379 = 1:8 (w:w) were chosen. Also, capsules of polycation and polyanion only were prepared and tested.

Table 11: Formulations tested in this study

Polymers	Ratio (w:w)
80/1000:379	1:8
80/1000:379	1:1
80/1000:209	1:1
80/500:379	1:8
80/500:379	1:1
80/500:209	1:1
95/500:379	1:8
95/500:379	1:1
95/500:209	1:1
379	1
209	1
80/1000	1
80/500	1
95/500	1

#### 3.5.2.2 FT-IR

To confirm the formation of a polyelectrolyte complex FT-IR was utilized. Spectra of chitosan, carrageenan, and complexes were taken. For the latter the complexes was freeze dried (Christ Alpha 1-4, Martin Christ GmbH, Osterode, Germany) after 24 h of dissolution testing in SGF. Spectra were obtained using a FT-IR spectrophotometer (FT-IR 8400S, Shimadzu, Duisburg, Germany) equipped with an ATR attachment at 4000-750  $\text{cm}^{-1}$ .

#### 3.5.2.3 Density of the gastroretentive matrix

The capsules were immersed in SGF maintained at 37 °C and softly agitated in a water bath. At predetermined time intervals the complexes were removed from the immersion medium and topically dried by tissue paper. The weight, diameter and length of the complexes were determined. The complexes were returned to the medium. Volume and density were calculated. Density measurements were undertaken in triplicate and the mean $\pm$ SD reported.

#### 3.5.2.4 Matrix swelling

The weighed capsules were placed in a beaker containing 100 mL of SGF or acetate buffer pH 4.5 at 37°C. The beaker was placed in a water bath maintained at 37 °C and softly agitated. At predetermined time intervals the matrices were removed from the medium, topically dried by tissue paper, weighed, and returned to the medium.

The degree of swelling  $S$  was calculated using Eqn. ( 16 ).

$$S = \frac{m_t - m_i}{m_i} * 100 \quad (16)$$

where  $m_t$  is the mass at time  $t$ , and  $m_i$  is the initial mass. Matrix swelling for each formulation was undertaken in triplicate and the mean $\pm$ SD reported.

#### 3.5.2.5 Effect of hydrodynamics on swelling

To examine the matrices ability to withstand hydrodynamic stress the systems were tested using the compendial PhEur/USP disintegration tester. All systems were investigated in SGF at 37 °C. Also, capsules containing chitosan only and carrageenan only were tested. Formulations 80/1000:379 1:8 and 80/1000:209 1:1 were additionally investigated in acetate buffer pH 4.5 to examine the pH dependency of the matrices. All studies were undertaken in triplicate and the mean $\pm$ SD reported.

Formulation 80/1000:379 = 1:8 was additionally tested using the modified disintegration test device (3.1) equipped with the compendial basket to examine the influence of different moving velocities along the vertical axis on the swelling behavior. The formulation was investigated in SGF and the device was operated at 40 and 80 mm/s.

The capsules were weighed, placed in the tubes/ probe chambers of the device, and the up and down movement was started. At predetermined time intervals the complexes were removed, topically dried by tissue paper, and weighed. The degree of swelling  $S$  was calculated using Eqn. ( 17 ).

$$S = \frac{m_t - m_i}{m_i} * 100 \quad (17)$$

where  $m_t$  is the mass of the swollen complex at time  $t$ , and  $m_i$  is the initial mass of the complex.

### 3.5.2.6 Physicomechanical strength

The ability of the complexes to withstand mechanical stress was tested using a Texture Analyzer (TA.XTplus, Stable Microsystems, Surrey, UK). Therefore, capsules were placed in a beaker containing 100 mL of SGF. The beaker was placed in a water bath maintained at 37 °C and softly agitated. At 2, 4, 6 and 8 h the complexes were removed from the immersion medium and force-time and force-distance diagrams were recorded using a 12 mm (MH, DE) and a 25 mm (MR) probe, respectively. Data were recorded and evaluated using the Texture Exponent software. The settings employed for the study are summarized in Table 12.

Table 12: Parameter settings for texture analyzer study

Parameters	MR (%)	MH (N/mm <sup>2</sup> )	DE (J)
Pre-test speed	1 mm/s	1 mm/s	1 mm/s
Test speed	0.5 mm/s	0.5 mm/s	0.5 mm/s
Post-test speed	10 mm/s	10 mm/s	10 mm/s
Trigger type	Auto	Auto	Auto
Trigger force	1 g	1 g	1 g
Load cell	5 kg	5 kg	5 kg
Target mode	Strain (5%)	Distance (5 mm)	Distance (5 mm)

Matrix resilience (MR) was calculated from the force-time profile as the ratio between the area under the curve (AUC) of the peak to baseline after the force is removed (AUC<sub>24</sub>) and the baseline to peak before the force removed (AUC<sub>12</sub>) (Figure 26 a). Matrix hardness (MH) and deformation energy (DE) were calculated from the force-distance profiles (Figure 26 b). Here, MH is the gradient between initial and maximal force and DE is the area under the curve (AUC<sub>12</sub>) (Bawa et al., 2011; Ngwuluka et al., 2013).

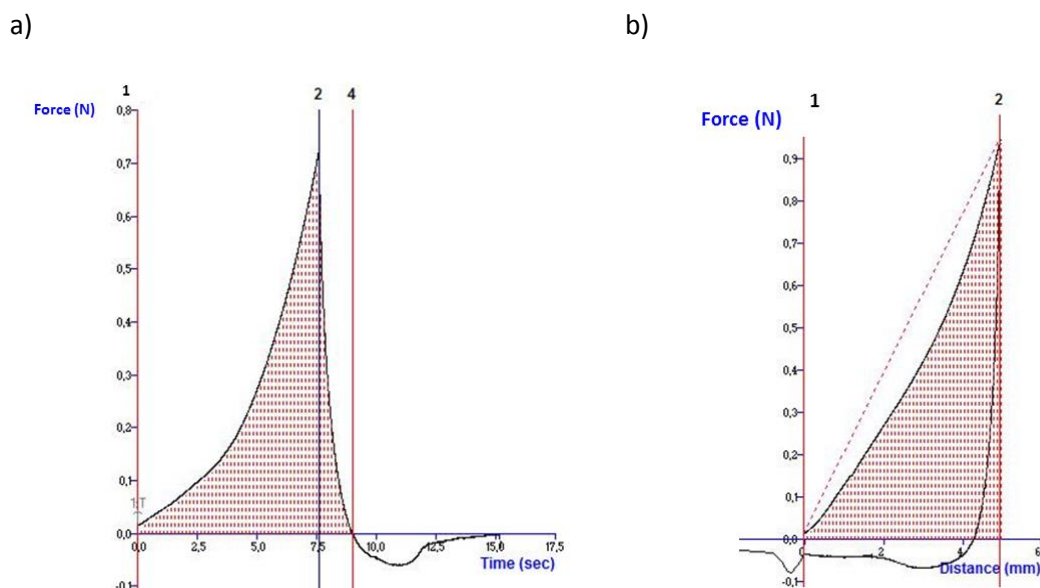


Figure 26: Typical a) force-time and b) force-distance profiles for determining matrix resilience (a) and matrix hardness and deformation energy (b).

### 3.5.2.7 *In vitro* drug release

*In vitro* release testing of trospium chloride was performed using USP dissolution apparatus 2 (Sotax AT7, Holm and Halby, Allschwil, Switzerland) connected to an autosampler (Dissoette II, Hanson research, Chatsworth, CA, USA). 900 mL SGF or acetate buffer pH 4.5 maintained at 37 °C were used. Paddle speed was set to 50 rpm. At predefined time intervals 5 mL samples were withdrawn and replaced with fresh medium. Samples were analyzed by HPLC. Drug release studies were undertaken in triplicate within each medium for every formulation and the mean $\pm$ SD reported.

Release testing of formulation 80/1000:379 = 1:8 was additionally performed utilizing the modified disintegration test device (3.1) equipped with the compendial basket operating at 40 and 80 mm/s to examine the influence of hydrodynamics on the drug release profile. 800 mL of SGF maintained at 37 °C were used. The vertical movement of the modified device was set to 40 and 80 mm/s and the profiles were compared to that obtained using USP apparatus II. Drug release studies at 80 mm/s were undertaken in triplicate, where one capsule was measured per trial on three days and the mean $\pm$ SD is reported. Due to the low SD, drug release studies at 40 mm/s were undertaken in triplicate, where three capsules were measured per trial on one day and the obtained concentration was divided by three and reported as mean.

#### 3.5.2.7.1 HPLC procedure

Before analyzing by HPLC samples were precipitated with acetonitrile (sample: acetonitrile= 1:2) and centrifuged at 5 °C and 14000 rpm for 30 min and injected into the HPLC system. Chromatic

### 3 Materials and Methods

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conditions are summarized in Table 13. Calibration solutions were prepared in SGF or acetate buffer, respectively.

Table 13: Chromatographic conditions for the detection of trospium chloride from dissolution samples.

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Column	LiCroChart 125 x 4 mm, RP-8, Supersphere 60, Merck, Darmstadt, Germany	
Mobile phase	Acetonitrile:Phosphate buffer	70:30
Phosphate buffer	K <sub>2</sub> HPO <sub>4</sub> x 3 H <sub>2</sub> O	0.003 M
	Phosphoric acid 85 %	1.5 mL
	pH adjusted (NaOH)	2.2
temperature	ambient	
Flow rate	1.2 mL/min	
detection	UV absorption at 210 nm	
Injection volume	20 µL	
Running time	5 min	

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The HPLC method was validated for linearity, precision, accuracy, limit of detection (LOD), and limit of quantification (LOQ). To confirm linearity standard calibration curves in the range of 0.5 to 30 µg/mL (corresponding to 2 to 140 % of maximum probe concentration) were prepared and measured each day on three subsequent days. Linear regression analysis of peak area versus drug concentration curves was performed to calculate the coefficient of correlation (R), slope and intercept. The data of peak area versus drug concentration were treated by linear regression analysis. Precision, expressed as % relative standard deviation (RSD), and accuracy, expressed as % relative error (RE), were investigated for three concentration levels within one day (intra-day, n=3) as well as on three successive days (inter-day, n=3). LOD and LOQ were determined based on the standard deviation of the blank and the slope of the calibration curve according to ( 18 )and ( 19 ) and were 0.045 µg/mL and 0.2 µg/mL, respectively. Results of the validation procedure are summarized in Table 14.

$$\text{LOD} = 3.3 * \frac{\sigma}{S} \quad (18)$$

$$\text{LOQ} = 10 * \frac{\sigma}{S} \quad (19)$$

Table 14: Results of validation procedure.

<b>Linearity (0.5 to 30 µg/mL corresponding to 2 to 135 % of maximum concentration) (mean±SD)</b>			
	R	Slope	Intercept
Day 1 (n=3)	0.9994±0.0003	0.7710±0.0122	0.2321±0.0832
Day 2 (n=3)	0.9987±0.0005	0.8242±0.0262	0.2964±0.1661
Day 3 (n=3)	0.9992±0.0007	0.8341±0.0185	0.3084±0.1054
Day 1-3 (n=9)	0.9991±0.0011	0.8100±0.0336	0.2970±0.0410
<b>Intra-day variability</b>			
Nominal concentration [µg/mL]	Measured concentration [µg/mL]	%RSD	%RE
5	4.99±0.07	1.48	-0.18
10	10.22±0.22	2.10	2.19
15	14.89±0.45	2.92	-0.75
<b>Inter-day variability</b>			
Nominal concentration [µg/mL]	Measured concentration [µg/mL]	%RSD	%RE
5	4.81±0.15	3.08	-3.79
10	10.33±0.09	0.90	3.27
15	15.32±0.43	2.80	2.11

### 3.5.2.7.2 Drug release kinetics

To determine the drug release kinetics, the dissolution data were fitted to several kinetic models (Table 15).

Table 15: Kinetic models used for fitting the dissolution data.

Model	Equation	
Zero order	$F = k_0 * t$	(20)
First order	$F = 100 * (1 - e^{-k_1 t})$	(21)
Higuchi	$F = k_H t^{0.5}$	(22)
Korsmeyer-Peppas	$F = k_{KP} t^n$	(23)
Hixson-Crowell	$F = 100 * [1 - (1 - k_{HC} * t)^3]$	(24)

Where  $F$  is the fraction (%) of drug released at time  $t$ ,  $k_0$  is the zero order release constant,  $k_1$  is the first order release constant,  $k_H$  is the Higuchi release constant,  $k_{KP}$  is the Korsmeyer-Peppas release constant,  $n$  is the diffusional exponent,  $k_{HC}$  is the Hixson-Crowell release constant,  $A$  is the diffusional term,  $B$  is the erosional term,  $Ti$  represents the lag time before onset release,  $\alpha$  is the factor defining the time scale,  $\beta$  is the factor defining the shape of the curve ( $\beta = 1$ : exponential,  $\beta > 1$ : sigmoid,  $\beta < 1$ : parabolic).

The release exponent  $n$  derived from fitting to the Korsmeyer-Peppas model is used to analyze the mechanism of release. For a cylindrical matrix the release mechanism is Fickian diffusion if  $n = 0.45$ , non-Fickian release or anomalous transport if  $0.45 < n < 0.89$ , case II transport or zero-order release if  $n = 0.89$ , and super case II transport if  $n > 0.89$  (Table 16; Costa and Sousa, 2001).

Table 16: Interpretation of diffusional exponent.

Release exponent ( $n$ )	Drug transport mechanism
0.45	Fickian diffusion
$0.5 < n < 0.89$	Anomalous transport
0.89	Case-II transport
$> 0.89$	Super case-II transport

To compare the dissolution profiles of the different matrices the similarity factor was calculated according to eqn. ( 25 ).

$$f_2 = 50 * \log \left\{ \left[ 1 + \frac{1}{n} \sum_{t=1}^n (R_t - T_t)^2 \right]^{-0.5} * 100 \right\} \quad (25)$$

where  $R_t$  and  $T_t$  are the percent drug dissolved at each time point for the reference and the test formulation, respectively and  $n$  is the number of time points. According to the guidelines profiles are denoted similar for  $f_2$  values between 0.5 and 1.

## 4 Results

The scientific work of this thesis can be divided into a theoretical and an experimental part (Figure 27).

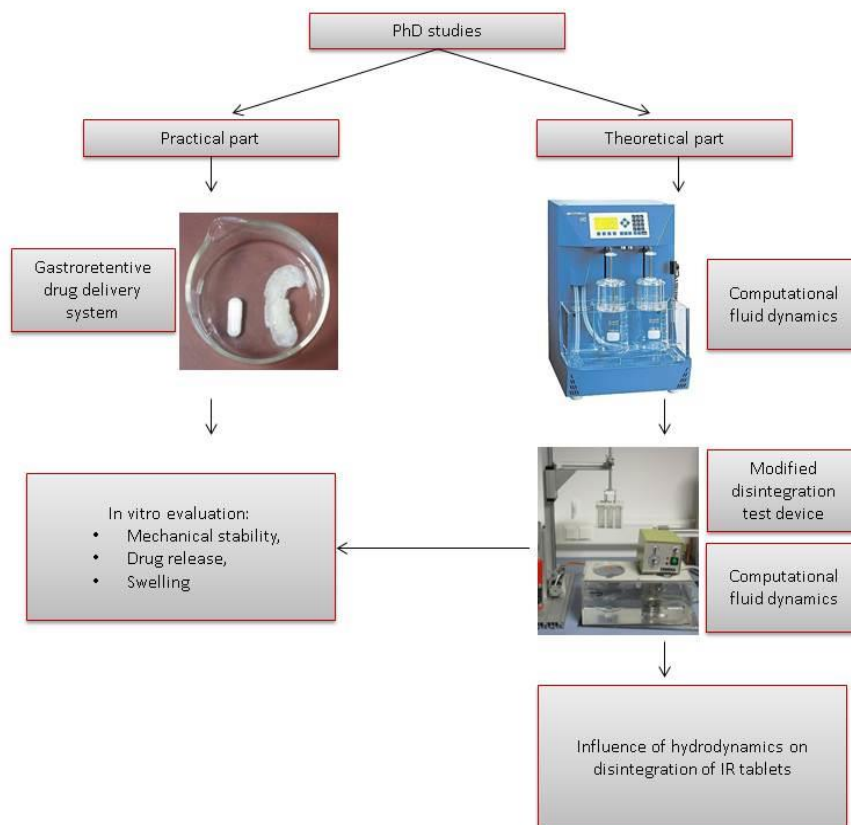


Figure 27: Schematic overview of the experimental and theoretical parts of this PhD thesis.

In the theoretical part of the work a computational fluid dynamics (CFD) analysis was performed to characterize the hydrodynamics and forces in the compendial PhEur/USP disintegration test device (4.1). The simulation results were compared to *in vivo* literature data to evaluate the biorelevance of the device and operating conditions. This investigation led to the development of a modified disintegration test device (4.2). Again, a CFD analysis was conducted to examine the hydrodynamics and forces in the modified device and to compare them to the situation in the compendial device (4.3). Additionally, a ‘what if’ study was performed to examine the influence of changing operating conditions on the hydrodynamics and forces (4.4). The modified disintegration device was utilized to examine the influence of hydrodynamics and pressure forces on disintegration times of immediate release (IR) tablets experimentally (4.5).

Another part of the work comprised the development and *in vitro* evaluation of a gastroretentive drug delivery system (GRDDS) (4.6). Since these systems are supposed to remain

in the stomach for a prolonged period of time, they are exposed to a wide range of hydrodynamics and forces over time. To guarantee their successful performance it is essential that they withstand these conditions. Therefore, the influence of changing hydrodynamic conditions on the swelling behavior and drug release profile was examined using the modified disintegration test device (4.7).

### **4.1 Characterization of the hydrodynamics in the PhEur/USP disintegration test device**

Since disintegration of solid oral immediate release (IR) dosage forms is a prerequisite for drug absorption, disintegration testing is a commonly used tool in pharmaceutical development and quality control. The PhEur describes a simple device that is moved vertically in a medium (Ph.Eur., European Pharmacopoeia, 2014; see also chapter 1.1.2). The basis for this test device is the apparatus for tablet disintegration introduced by Greshberg and Stoll in 1946 (Gershberg and Stoll, 1946). Since its introduction and following adoption to the pharmacopoeias the apparatus and operating conditions remained almost unchanged. Due to increasing knowledge about the *in vivo* situation in terms of fluid motion and gastric forces it becomes possible to challenge the biorelevance of the compendial device. In this chapter the results of a CFD study of the hydrodynamics and forces in the compendial PhEur/USP disintegration test device are presented. The simulations were performed with several beverages and pasty foods, representing the fasted and the fed state. Additionally, 1.4 % HPMC solution was used as a model medium, since it was recently proposed as an *in vitro* model fluid exhibiting similar characteristics as mashed diluted FDA meal (460 mL mashed meal + 240 mL water) (Radwan et al., 2012).

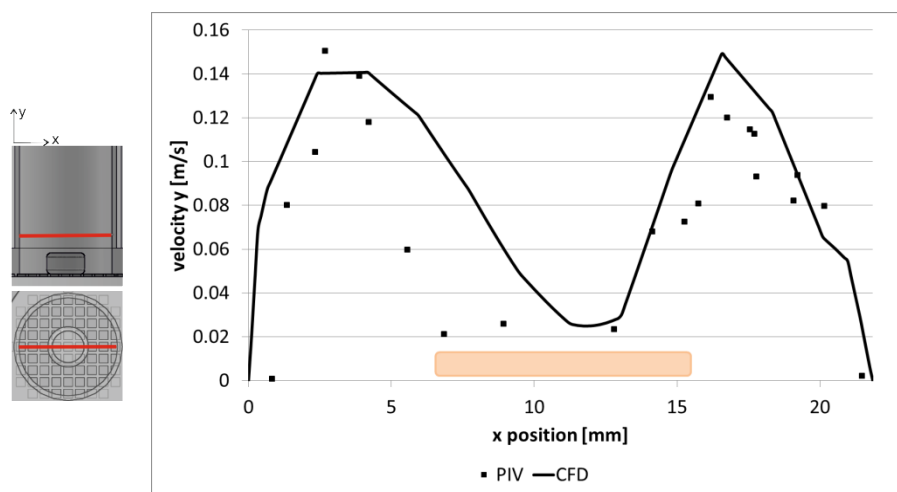
#### *4.1.1 Validation of CFD model using PIV experimental data*

Before any investigation it is necessary to prove the capability of the CFD model to predict the hydrodynamic environment in the disintegration test device. To validate the CFD model a simulation with constant moving velocity (0.06 m/s) and SGF as fluid was run. The predicted velocity in vertical direction in the vicinity of the tablet (10 mm above the mesh) was compared to experimental data from particle image velocimetry (PIV) measurements (Figure 28).

The predicted CFD profiles show good agreement with the experimental PIV velocity profiles, in both pattern and absolute velocities. There are three data points in the region above the tablet

(5.57 to 8.93 mm) where the simulation overestimates the fluid velocity. This may be due to the paucity of experimental particle data points in this range. An acceptable correlation between PIV results and CFD predictions was found ( $R^2 = 0.6046$ ). The deviation between measured and calculated velocities is largest for low velocities, whereas at high velocities a very good agreement was found. The deviation between measurement and model at low velocities can be attributed to the manual analysis of the PIV data. However, the results indicate that the CFD methodology is capable of predicting the hydrodynamics in the tubes of the disintegration device.

a)



b)

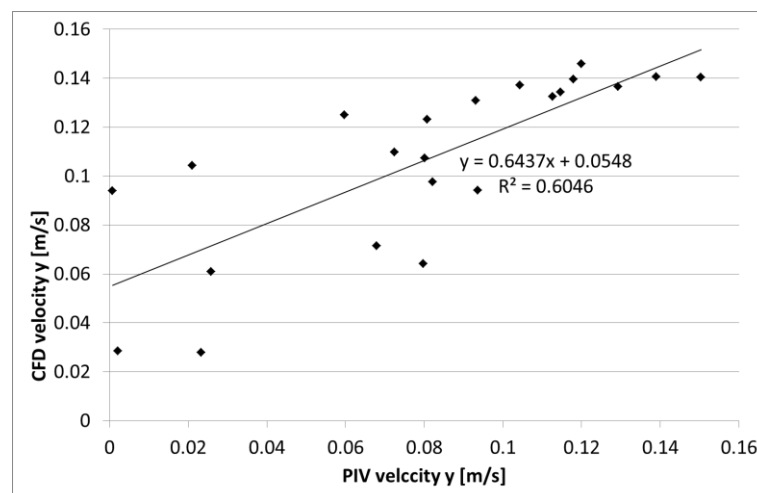


Figure 28: a) Comparison between predicted and experimental velocity profiles along a horizontal line (10 mm above mesh); the position of the tablet is represented by the orange square. b) Correlation between velocity magnitude from PIV experiments and CFD predictions. An acceptable correlation between PIV results and CFD predictions was found indicating that the CFD approach is capable of predicting the hydrodynamics in the disintegration test device.

### 4.1.2 Fluid flow field

Hydrodynamic flow inside the tubes of the PhEur/USP disintegration tester is generated by the vertical up and down movement of the basket-rack assembly. Since the motion follows a sinusoidal velocity profile described by eqn. ( 2 ), the velocity magnitude and direction is time dependent and the fluid flow field is continuously changing during the movement cycle (duration of one down and up movement is 2 s). Figure 29 and Figure 30 show a time sequence of the CFD predicted velocity contour plots for simulated gastric fluid (SGF) and homogenized FDA meal, respectively. In the tube which does not contain a tablet (Figure 29 and Figure 30, right tube), the fluid flow is accelerated by entering the tube for both, SGF and the homogenized FDA meal. Inside the tube, the non-slip condition comes into effect, which results in zero velocity at the solid boundary. The fluid velocity is highest in the center of the tube and lowest at the vicinity of the walls. Nevertheless, there is a distinct difference between Newtonian versus non-Newtonian media. While the flow field of the non-Newtonian FDA meal is characterized by a highly ordered motion and a homogeneous velocity distribution, the flow field and velocity profile of the Newtonian SGF develops more fluctuations and is more disordered.

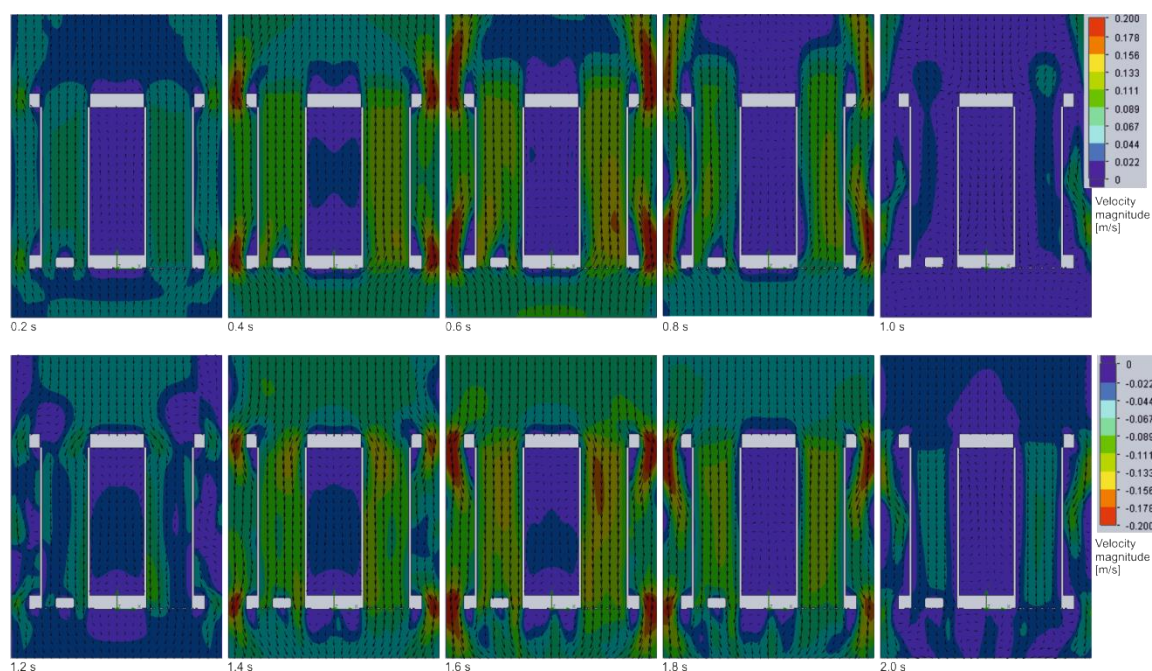


Figure 29: Time sequence of CFD predicted velocity contour plots on a vertical cross section for SGF. The tube on the right side does not contain a tablet while the tube on the left side does contain a tablet. The velocity magnitude is color coded (blue: low, red: high). Due to the sinusoidal movement profile the fluid flow field and velocity magnitude are time-dependent. Velocity magnitude accepts positive and negative values due to the change from down to up movement at 1.0s resulting in a reversal of fluid flow along the vertical y-axis.

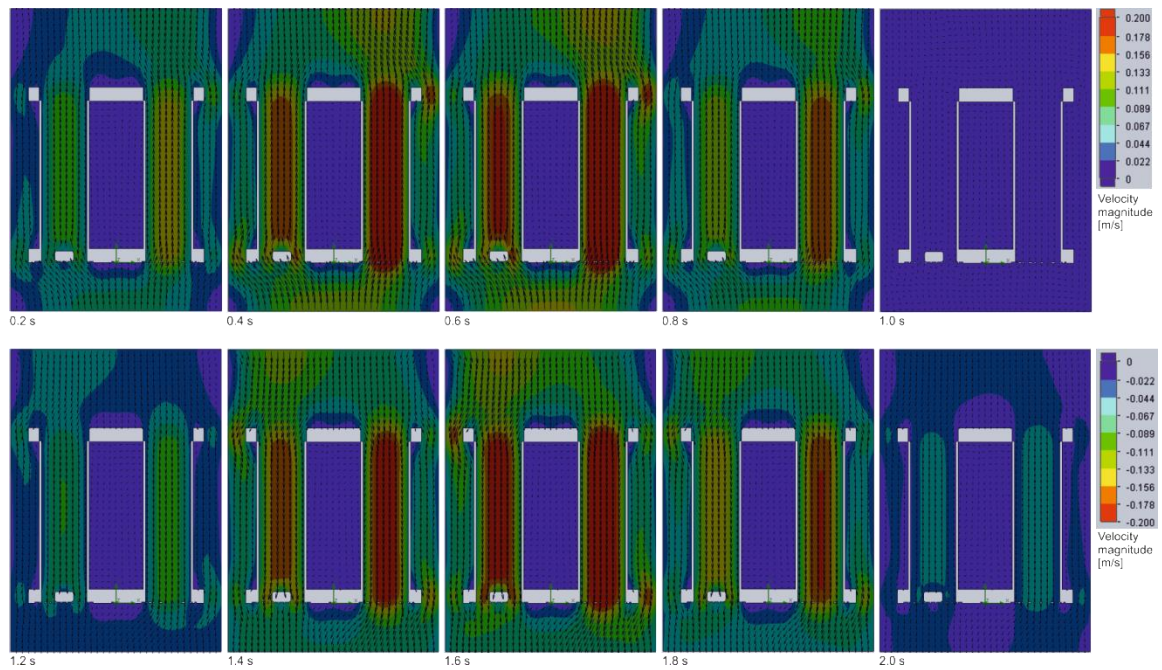


Figure 30: Time sequence of CFD predicted velocity contour plots on a vertical cross section for homogenized FDA meal. The tube on the right side does not contain a tablet while the tube on the left side does contain a tablet. The velocity magnitude is color coded (blue: low, red: high). Due to the sinusoidal movement profile the fluid flow field and velocity magnitude are time-dependent. Velocity magnitude accepts positive and negative values due to the change from down to up movement at 1.0s resulting in a reversal of fluid flow along the vertical y-axis.

These observations can be explained by the principles of fluid flow in tubes. For fluid flow in tubes it is postulated that the flow is governed by the ratio of inertia to viscous forces. Thereby, inertia is the fluids resistance to change in motion. Viscous forces are frictional shear forces that arise from shear stress and friction between the different layers of the fluid. The Reynold's number ( $Re$ ), representing the ratio of inertial to viscous forces, can be calculated according to eqn. ( 26 ):

$$Re = \frac{\rho v D}{\mu} \quad (26)$$

where  $D$  is the diameter of the tube,  $v$  is the velocity of the fluid,  $\rho$  is the density of the fluid and  $\mu$  is the fluid viscosity.

Depending on the ratio of inertial to viscous forces the flow can either be laminar or turbulent. At very low Reynold's numbers, where inertial forces can be neglected, the fluid flow will be laminar. In contrast, at high Reynold's numbers, where viscous forces are small compared to inertial forces and flow is assumed to be inviscid, the fluid flow will be turbulent.

It is generally assumed that at  $Re < 2300$  the fluid flow in tubes is laminar and that at  $Re > 4000$  fluid flow becomes turbulent. In the range in between a transition takes place where the flow

fluctuates between laminar and turbulent. Calculations for the Reynold's number for SGF and FDA meal using the maximum flow velocity of each fluid at 0.5 s and the averaged viscosity at 30 mm above the mesh at 0.5 s, revealed values of 2731 and 0.3 for SGF and FDA meal, respectively. These calculations underline the observation of a laminar flow for the homogenized FDA meal and a transitional flow for SGF in the PhEur/ USP disintegration tester.

The fixed tablet represents an obstacle for the fluid which is forced aside (Figure 29 and Figure 30 left tube). Approaching the tablet, flow is decelerated due to the obstacle, then accelerates again. Right above or below the tablet, depending on the direction of basket movement, a sheltered region with negligible fluid flow emerges. This sheltered zone is more pronounced for the low viscous SGF compared to the high viscous FDA meal. Calculations of the Reynold's number around the tablet using the predicted average viscosity and the predicted average velocity around tablet and the tablet diameter of 9 mm, revealed values of 834 and 0.02 for SGF and the homogenized FDA meal, respectively. These values indicate different flow patterns around the tablet for the two fluids. For Reynold's numbers  $>100$ , as in the case of SGF, frictional forces are negligible and inertial forces are dominant resulting in oscillation of the flow behind the tablet. This oscillation of flow results in the formation of recirculating flow structures, so called eddies, in the sheltered region of the tablet. In contrast, at very small Reynold's numbers, observed for the homogenized FDA meal, frictional forces overpower acceleration and no eddy structures are to be expected around the tablet.

The fluid flow velocity is a vector quantity in the three dimensional space specified by the three components in x-, y-, and z-direction. To illustrate the contribution of each component, a horizontal cross section was drawn at the middle height of the tablet (plane 1 in Figure 31). Figure 31 shows the velocity vector (a), as well as the contribution of its components in x-, y- and z-direction (b, c, d) on this horizontal cross section. The magnitude and direction along plane 1 are represented by the color code. The depicted fluid flow field is a snapshot at  $t=0.5$  s, which is the point of maximum moving velocity of the down movement during the movement cycle. In terms of direction the fluid flow field is similar for all simulated fluids. The vertical y-component is dominating over the x- and z- component indicated by the high velocity magnitude values. The x- and z-component represent the horizontal fluid flow. Depending on the direction of flow, they can accept positive and negative values. Positive values indicate flow from the left to the right (x-component) and from the back to the front (z-component). Negative values indicate flow from the right to the left (x-component) and from the front to the back (z-component).

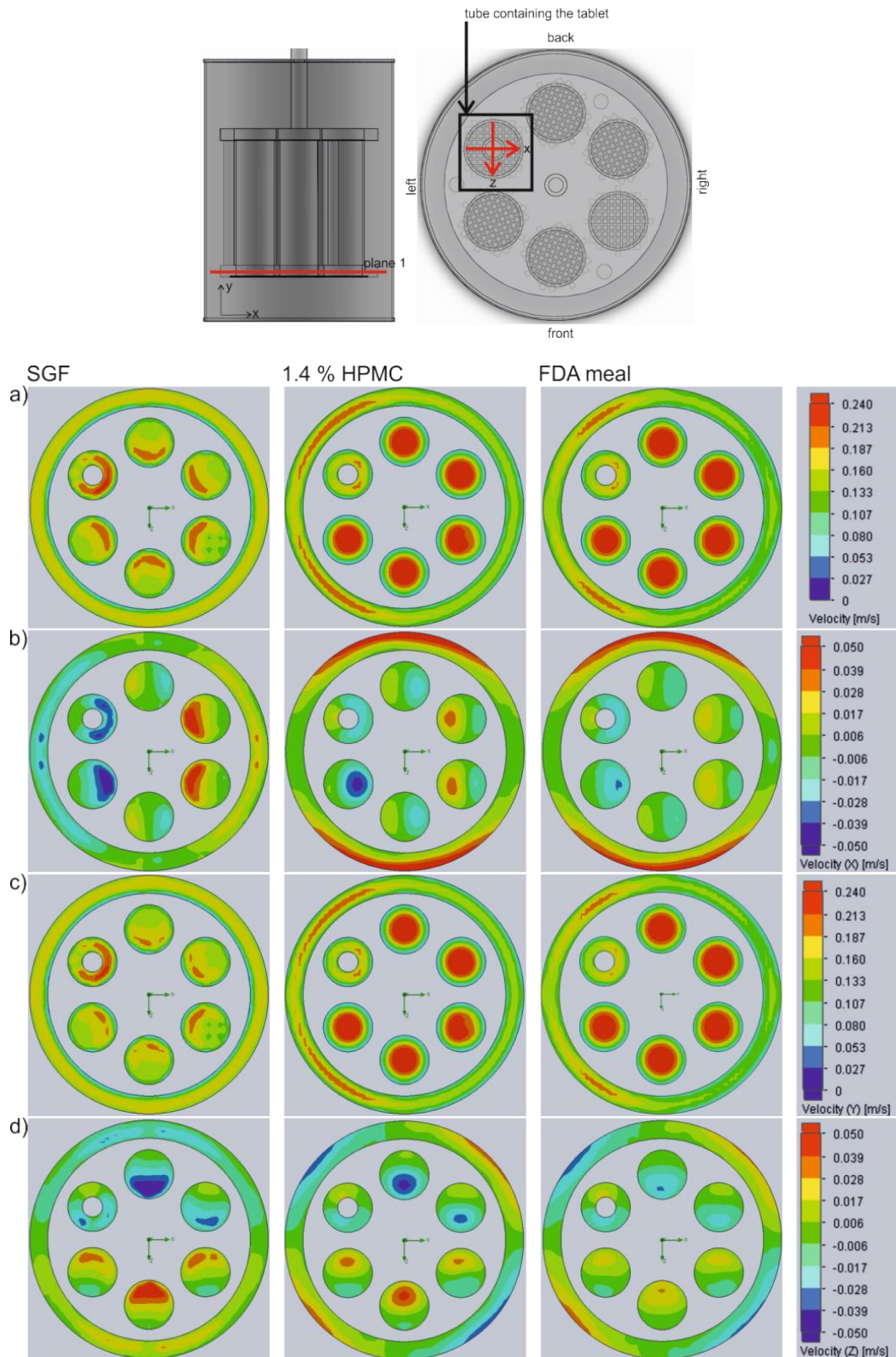


Figure 31: CFD predicted contour plots of velocity magnitude on a horizontal cross section at the middle of the tablet (plane 1) for SGF, 1.4 % HPMC solution, and mashed FDA meal at  $t=0.5$  s. a) Magnitude of velocity vector. b) Magnitude of the x-component of the velocity vector. The x-component is directed from the left to the right (see top). Thus, positive values (green to red color) indicate fluid flow from the left to the right and negative values (light green to blue color) indicate fluid flow from the right to the left. c) Magnitude of the y-component of the velocity vector. The y-component is directed upwards and shows only positive values. d) Magnitude of the z-component of the velocity vector. The z-component is directed from the back to the front (see top). Thus, positive values (green to red color) indicate fluid flow from the back to the front and negative values (light green to blue color) indicate fluid flow from the front to the back.

The fluid flow along the x-and z-axis is limited by the glass walls of the tube where the fluid is pushed towards the tablet from all sides. The higher the viscosity of the fluid, the lower is the fluid velocity in x-and z-direction and the higher the fluid velocity in y-direction.

### 4.1.3 Effect of viscosity on velocity magnitude

To investigate the effect of medium viscosity on velocity magnitude, the velocity vector components were plotted along the x- and z-axis going through the tube containing the tablet illustrated by the red arrows in Figure 31. Thereby the y-component of the velocity vector points upwards in the direction of flow and is shown on both axes (Figure 32 a) and b)). The x-component (Figure 32 c)) represents horizontal fluid motion to the left or the right along the x-axis and the z-component (Figure 32 d)) shows horizontal fluid motion to the front and the back along the z-axis. Depending on the direction of movement, the x- and z-component can exhibit positive or negative values. The profiles show the instantaneous velocity magnitude at  $t=0.5$  s, which is the point of highest moving velocity during the down movement of the moving cycle.

The y-velocity, pointing in the direction of flow, shows only positive values indicating that no retrograde fluid flow is occurring. Since the tubes are symmetrically, there is no difference between the y-velocity along the x- and z-axis. Velocity in y-direction is highest in the middle of the gap between tablet and tube wall along the x-axis and the z-axis. By increasing the viscosity of the medium, the y-velocity decreases, whereby the velocity magnitude in each group of fluids, Newtonian or non-Newtonian, is almost independent of the viscosity. The highest predicted velocities for SGF and 1.4 % HPMC solution reach values of 0.22 m/s and 0.18 m/s, respectively. Since the moving velocity is approximately 0.085 m/s the fluid is accelerated by a factor of 2.75 and 2.25 for SGF and 1.4 % HPMC solution, respectively.

The x-and z-velocity component are approximately one order of magnitude lower compared to the y-component. The change from positive to negative values for both components indicates that the horizontal fluid flow is pointing to the center of the tube pushing the fluid towards the tablet.

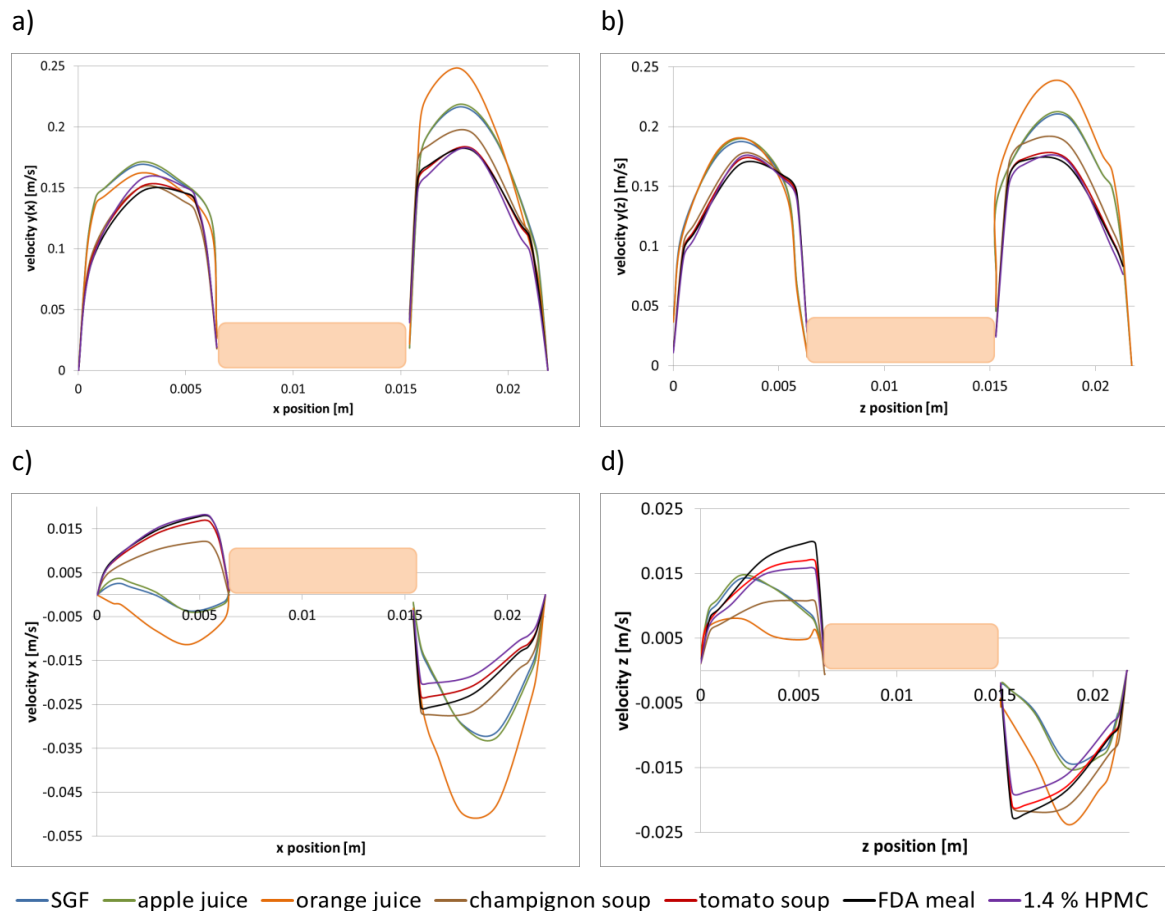


Figure 32: Velocity profiles on a horizontal cross section at the height of the middle of the tablet (plane 1) of SGF, apple juice, orange juice, champignon soup, tomato soup, mashed FDA meal, and 1.4 % HPMC solution at  $t=0.5$  s. a) Velocity profile of the y-component (directed upwards) of the velocity vector along the x-axis (directed from the left to the right). b) Velocity profile of the y-component (directed upwards) of the velocity vector along the z-axis (directed from the back to the front). c) x-component of the velocity vector along the x-axis (directed from the left to the right). Positive values indicate fluid flow from the left to the right and negative values indicate fluid flow from the right to the left. d) z-component of the velocity vector along the z-axis (directed from the back to the front). Positive values indicate fluid flow from the back to the front and negative values indicate fluid flow from the front to the back. For illustration of plane 1 and x- and z-axis see Figure 31.

#### 4.1.4 Shear rate and viscosity

The investigation of the effect of moving velocity on the shear rate and dynamic viscosity during a cycle is especially important for the non-Newtonian fluids, since they are characterized by a shear rate-dynamic viscosity-dependence. In contrast, the viscosity of the Newtonian fluids is independent of the shear rate and constant throughout the device and during the moving cycle. Figure 33 shows the CFD predicted contour plots of dynamic viscosity on a vertical cross section at the beginning of the down movement at  $t=0.1$  s and at the point of maximum velocity of the down movement at  $t=0.5$  s for the non-Newtonian fluids champignon soup, tomato soup, and mashed FDA meal.

The comparison of the contour plots at 0.1 (a) and 0.5 s (b) shows that an increase in moving velocity causes a decrease in dynamic viscosity for all fluids. The lowest viscosity is observed around the tablet indicating a high shear rate in this region. By increasing the viscosity of the medium the dynamic viscosity around the tablet is increasing.

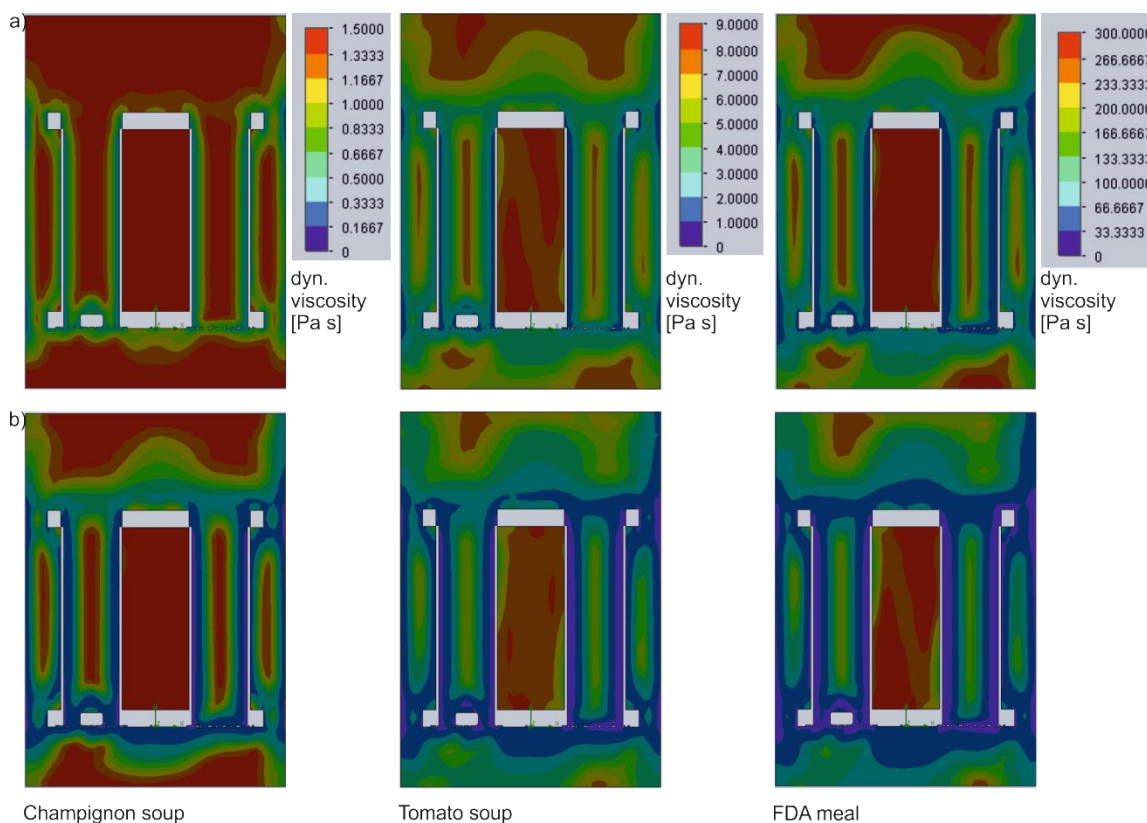


Figure 33: CFD predicted contour plots of dynamic viscosity at a)  $t=0.1$  s and b)  $t=0.5$  s of the moving cycle for champignon soup, tomato soup, and homogenized FDA meal on a vertical cross section. The tube on the right side does not contain a tablet while the tube on the left side does contain a tablet. Due to the sinusoidal movement profile the dynamic viscosity is time-dependent. Due to the non-Newtonian behavior of champignon soup, tomato soup and FDA meal, the dynamics viscosity is different throughout the device. In regions of high shear rate the dynamic viscosity is low (blue) and in regions of low shear rate the dynamic viscosity in high (red).

To investigate the shear rate and dynamic viscosity more precisely, Figure 34 shows the shear rate and the dynamic viscosity in the region of the tablet for 1.4 % HPMC solution and mashed FDA meal. Highest shear rates are observed adjacent to the base height of the tablet (Figure 34 a, red). These high shear rates are related to low dynamic viscosities in this region (Figure 34 b). The shear rate reaches values of up to  $200\text{ s}^{-1}$  at the tablets side. Figure 34 c) shows the range of dynamic viscosities along the x-axis on the horizontal cross section through the middle of the tablet. The range of dynamic viscosities of FDA meal is higher reaching values of 14 to  $42\text{ Pa}\cdot\text{s}$  compared to 0.4 to  $0.6\text{ Pa}\cdot\text{s}$  for 1.4 % HPMC solution. Both non-Newtonian fluid exhibit higher dynamics viscosities compared to that of SGF ( $0.0007\text{ Pa}\cdot\text{s}$ ).

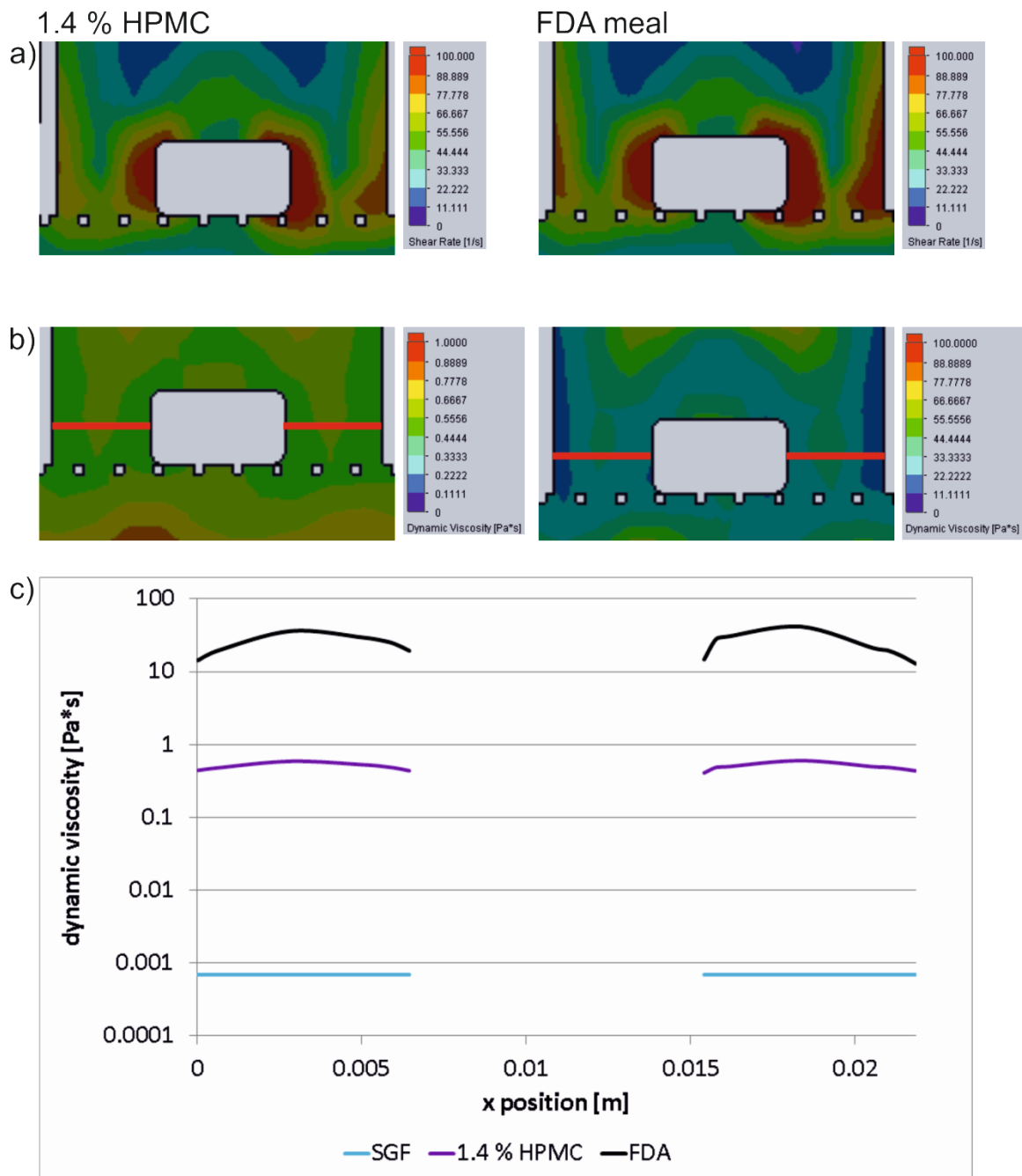


Figure 34: CFD predicted contour plot of a) shear rate and b) dynamic viscosity on a vertical cross section through the middle of the basket for 1.4 % HPMC solution and mashed FDA meal at  $t=0.5$  s. c) Range of dynamic viscosity along the red horizontal sketch shown in b) at  $t=0.5$  s for SGF, 1.4 % HPMC solution and mashed FDA meal. The viscosity of non-Newtonian fluids is dependent on the shear rate. High shear stress, occurring especially near the base height indicated by the red color, lowers the viscosity in this region. In c) the viscosity of SGF is shown in blue for comparison purpose.

#### 4.1.5 Shear stress on tablet surface

The force on an object in a streaming fluid is the sum of the stresses caused by pressure and shear. While pressure stress acts perpendicular to the surface of the object, shear stress acts tangential to it. Due to the sinusoidal movement velocity profile the tablet is exposed to changing shear forces. Figure 35 shows the time sequence of shear stress on the tablet surface for SGF (a) and FDA meal (b).

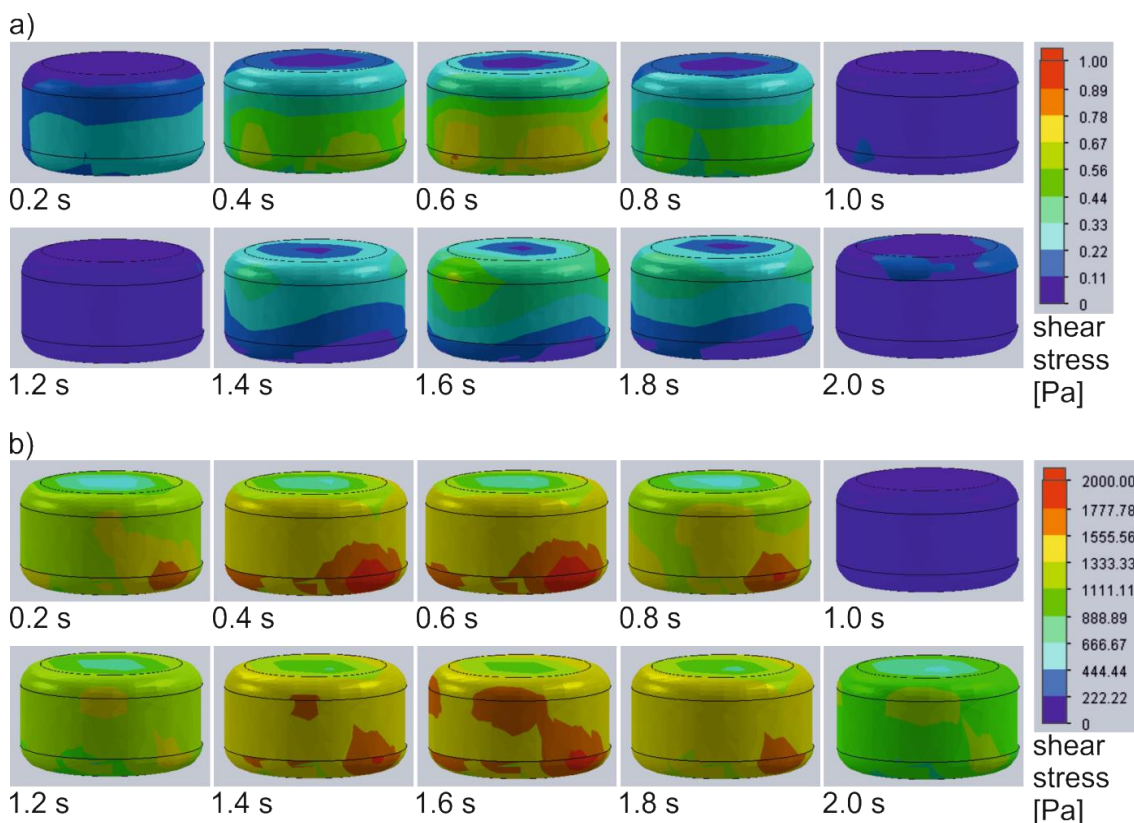


Figure 35: Time sequence of CFD predicted shear stress on tablet surface for a) SGF and b) homogenized FDA meal. Due to the sinusoidal movement profile of the device the shear stress is time dependent. From 0 to 1.0 s the basket is moved down and from 1.0 to 2.0 s the basket is moved up. Highest shear stress is observed between 0.4 and 0.6 s or 1.4 and 1.6 s, which is the time of highest moving velocity during down and up movement.

From 0 to 0.5 s the moving velocity of the down movement is increased. This leads to an increase of shear stress on the tablet surface. From 0.5 to 1.0 s the moving velocity of the down movement is decreased leading to decreasing surface shear stress. The same observations are made for the up movement between 1.0 and 2.0 s. For both fluids highest shear stresses are predicted in the middle of the base height. At the bottom and the top of the tablet lower shear stresses are predicted. The range of shear stress for SGF is very small extending from 0 to 1 Pa. For the homogenized FDA meal a high variability of local shear stress over the tablet surface in the range of 0 to 2000 Pa is predicted.

The surface shear stress shows marked proportional viscosity dependence as shown in Figure 36 at  $t=0.5$  s. By increasing the fluid viscosity the average surface shear stress increases from values of 0.50 Pa for SGF to 1442 Pa for the FDA meal.

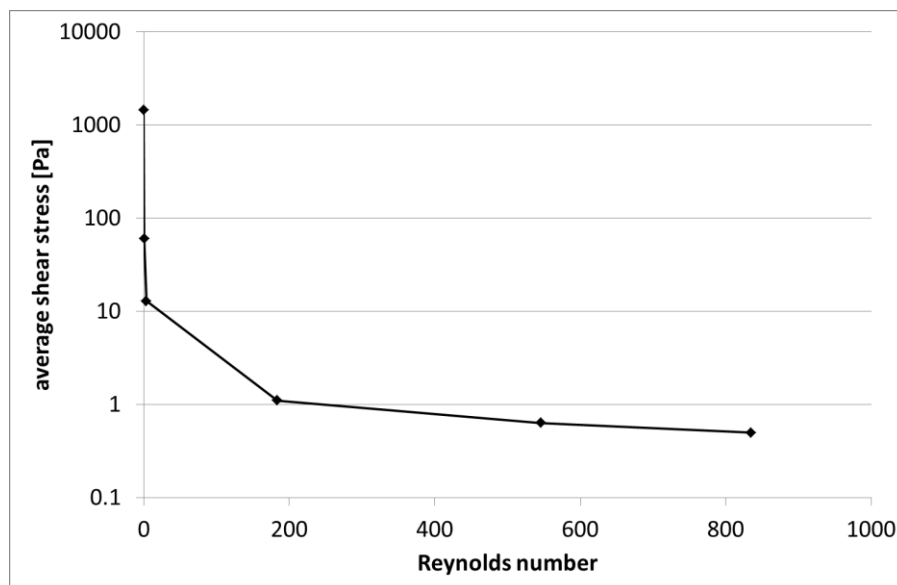


Figure 36: Average shear stress on the tablet surface as a function of the Reynold's number at  $t=0.5$  s (point of maximum moving velocity during down movement).

#### 4.1.6 Drag force

All objects positioned in a fluid stream experience a hydrodynamic drag force  $F_D$  acting opposite to the relative motion of the object. The drag depends on the properties of the fluid as well as on the size and shape of the tablet:

$$F_D = \frac{1}{2} \rho v^2 c_D A \quad (27)$$

where  $F_D$  is the drag force,  $\rho$  is the fluid density,  $v$  is the fluid velocity,  $A$  is the area of the tablet and  $c_D$  is the drag coefficient.  $c_D$  is not a constant but varies with fluid velocity, flow direction, fluid density, fluid viscosity and object size. For the calculation it makes no difference whether the tablet moves through the static fluid or whether the fluid moves past a static tablet. In this simulation  $F_D$  is the force along the vertical  $y$ -axis. Due to the change from down to up movement during the movement cycle,  $F_D$  can accept positive and negative values depending on the direction of action.

Figure 37 a) shows the drag force as a function of time for the Newtonian fluids. The force increases to a maximum of 0.0043 to 0.0048 N which is reached at 0.7 s. After this turning point the force decreases to a minimum value of 0.0013 N. During the whole cycle the force is very low and directed upwards. A change in the direction of force due to the change of fluid flow

direction would be expected but as the fluid flow is very sparse right above and below the tablet for the Newtonian fluids there is no large change in force. For champignon soup the drag force profile looks similar to those of the low viscous Newtonian fluids with forces in the range of 0.0060 and -0.0009 N. In the last part of the up cycle the force points downwards indicating that the fluid pushes the tablet towards the wire mesh (Figure 37 b). By further increasing the viscosity this effect becomes more pronounced and the range between upwards and downwards directed forces becomes larger. For tomato soup the upwards directed force increases to a maximum of 0.014 N at 0.6 s followed by a rapid direction change at 1 s. The maximum downward directed force is reached at 1.6 s and is half the size of the upward directed (-0.0084 N) (Figure 37 b). For mashed FDA meal the range between upward and downward force is even larger ranging from 0.2 N to -0.3 N (Figure 37 c).

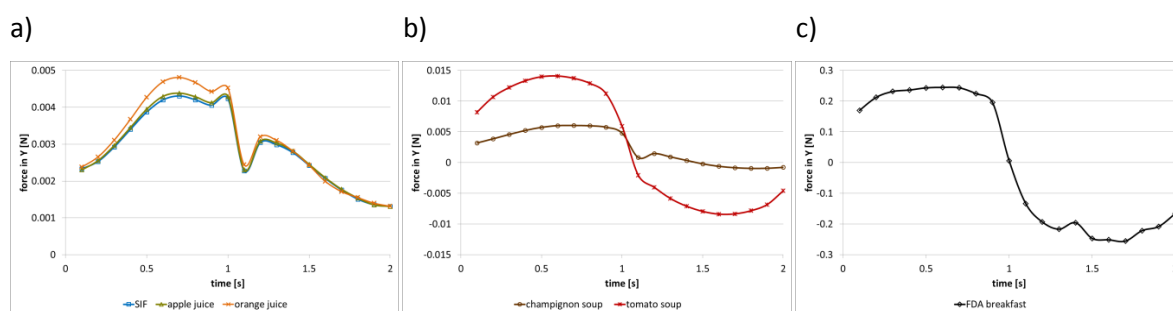


Figure 37: Drag force as a function of time. a) Newtonian fluids; b) non-Newtonian fluids champignon soup and tomato soup; c) non-Newtonian homogenized FDA meal. Due to the sinusoidal movement profile of the device the drag force is time dependent. From 0 to 1.0 s the basket is moved down and from 1.0 to 2.0 s the basket is moved up. Due to the reversal of moving direction, the force acting in y-direction (upwards) can accept positive and negative values.

In case the drag force exceeds the weight force, the tablet will be carried with the fluid experiencing less force. When the tablet is moved with the same velocity as the fluid, no force is acting on it. The weight force ( $G$ ) can be calculated according to

$$G = m * g \quad (28)$$

where  $m$  is the mass of the tablet and  $g$  is the gravity acceleration ( $g = 9.81 \text{ m/s}^2$ ). For a tablet of 500 mg the weight force is 0.005 N. This value is exceeded with all non-Newtonian fluids indicating that in practice, where the tablet is not fixed at the wire mesh, the tablet would be carried with the viscous fluids experiencing zero forces.

### 4.1.7 Relative pressure fields

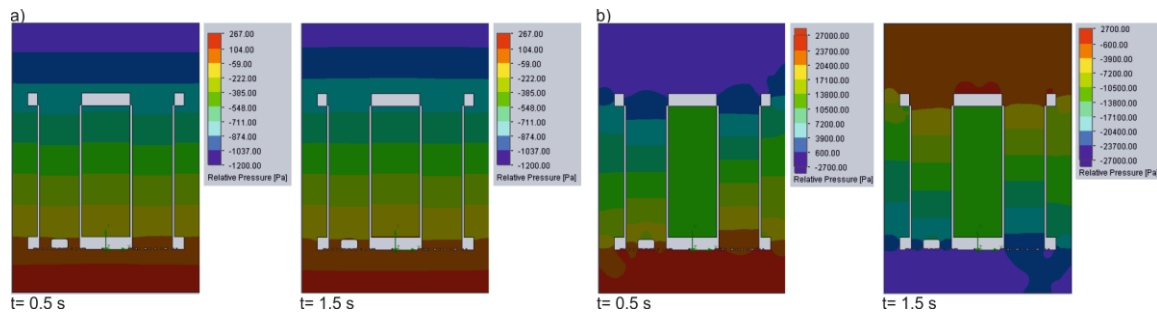


Figure 38: CFD predicted contour plots of relative pressure for a) SGF and b) homogenized FDA meal on a vertical cross section at  $t=0.5$  s (down movement) and  $t=1.5$  s (up movement). Due to the sinusoidal moving velocity profile of the device the relative pressure field is time dependent. At 0.5 and 1.5 s maximum moving velocities of down and up movement are reached.

Figure 38 shows the relative pressure inside the basket-rack assembly on a vertical cross section for SGF and homogenized FDA meal at 0.5 s and 1.5 s which are the time points of maximum moving velocity during down and up movement, respectively. For both a vertical relative pressure gradient is predicted. However, the gradient differs in nature and range. For SGF the relative pressure in the basket-rack assembly is in the range of 267 to -1200 Pa s (2.00 to -9.00 mmHg) with a vertical gradient for high values at the bottom and low values on top for the down and up movement (Figure 38 left side). For FDA meal the range is much larger extending from 27 kPa s to -27 kPa s (200.00 to -200.00 mmHg) showing reverse gradients for up and down movement (Figure 38 right side). With increasing the viscosity of the fluid the relative pressure difference inside the tube from the top to the bottom increases. Also, the relative pressure difference between bottom and top becomes more pronounced with increasing moving velocity and thus is highest at 0.5 and 1.5 s. As pressure is defined as force over surface and the surface is the same for both fluids, the large difference must be due to different forces acting on the surface. Pressure in SGF is generated by the gravitational force which is directed downwards for both, the up and down movement. Highest pressures are generated at the bottom of the beaker. In the homogenized FDA meal viscous forces and resistance to flow dominate over gravitational force. Shear stress and frictional forces are acting in the direction of movement generating high pressures at the bottom of the vessel for the down movement and low pressures at the bottom of the vessel for the up movement.

Figure 39 shows a time sequence of the average pressure at the bottom of the tablet for the Newtonian SGF, apple juice, and orange juice and the non-Newtonian champignon soup, tomato soup, and mashed FDA meal. The change in relative pressure for the Newtonian fluids is negligible fluctuating between 71 and -25 Pa s (0.53 and -0.19 mmHg). For the non-Newtonian fluids strong viscosity dependence is obvious. With increasing viscosity of the medium the

## 4 Results

difference between maximum and minimum relative pressure around the tablet increases ranging from 0.2 to -0.2, 0.9 to -0.9, and 24 to -25 kPa (1.68 to -1.51, 6.81 to -6.88, and 183 to -190 mmHg) for champignon soup, tomato soup, and the homogenized FDA meal, respectively.

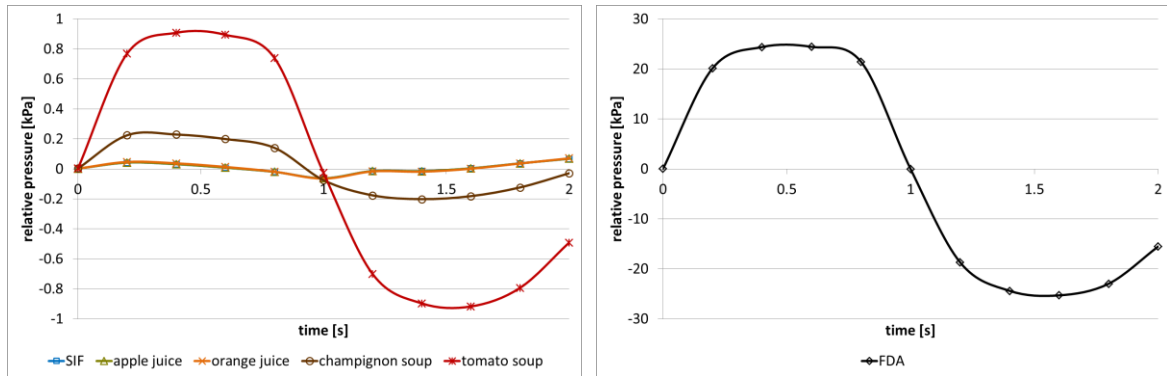


Figure 39: Relative pressure at the bottom of the tablet as a function of time (0-1 s: down movement; 1-2 s: up movement).

## 4.2 Modified disintegration test device

To be able to generate biorelevant hydrodynamics and mechanical forces, the compendial disintegration test apparatus was modified in terms of moving speed, moving profile and pressure forces (see materials and methods 3.1). Thereby, it is possible to simulate physiologically relevant fluid movements and the stomach's peristaltic contractions. The setup of the modified device is shown in Figure 40 a) and b). The basket is fixed to a holding device of the CNC drive, which is connected to the CNC controller. The moving of the basket is realized by the application of computerized numerical control (CNC). The program coding of the movement of the CNC drive is written in ProNC (isel Germany AG, Eichenzell, Germany). Although this work concentrates on the vertical movement of the basket, movement in all three dimensions is possible. Also, radial movement is possible.

The first step in the modification of the compendial device was the change of the moving profile and velocity. A major drawback of the compendial device is the restriction of the movement to the sinusoidal velocity profile (Figure 40 f, blue). Thus, the hydrodynamic conditions and forces are changing permanently during the moving cycle and the dosage form is exposed to a wide range of fluid velocities and forces. This limitation can be overcome using the modified device. In this work the influence of different moving speeds along the vertical axis on disintegration and dissolution was examined. Thereby, the moving velocity was constant resulting in the velocity profile exemplary shown in Figure 40 f) for moving velocities of 40 and 80 mm/s. The moving distance was 55 mm for all investigations. Therefore, the length of one moving cycle is dependent on the moving velocity. Due to this modification arbitrary moving velocities can be chosen and the hydrodynamic conditions become controllable.

Additionally, a new modified basket design was built in-house (Figure 40 c). The main difference to the compendial basket design with glass tubes is the mesh structure of the front and back side of the probe chamber. With this modification the fluid is no more restricted as in the glass tubes but two-sided fluid flow is occurring. Although, the three probe chambers of the modified basket are quadratic, their dimensions and volumes are similar to those of the circular glass tube of the compendial device. However, the modified device can be operated with both basket designs. Thus, it is possible to investigate the influence of basket design on disintegration times.

Furthermore, the modified basket can be equipped with balloons to simulate the movement of the stomach wall by inflation and deflation (Figure 40 d) and e). Inflation and deflation are regulated by a computerized pressure-vacuum unit (see 8.2) that is controlled by an open-

## 4 Results

source computer board (Arduino), programmed in C++. Different scenarios can be programmed by varying the applied pressure and the time between the inflations.

The advantage of the modified setup is its simplicity making it attractive for routine testing. The application of several other biorelevant devices, like the TIM and the DGM, is limited to their complexity and cost and time intensive measurements.

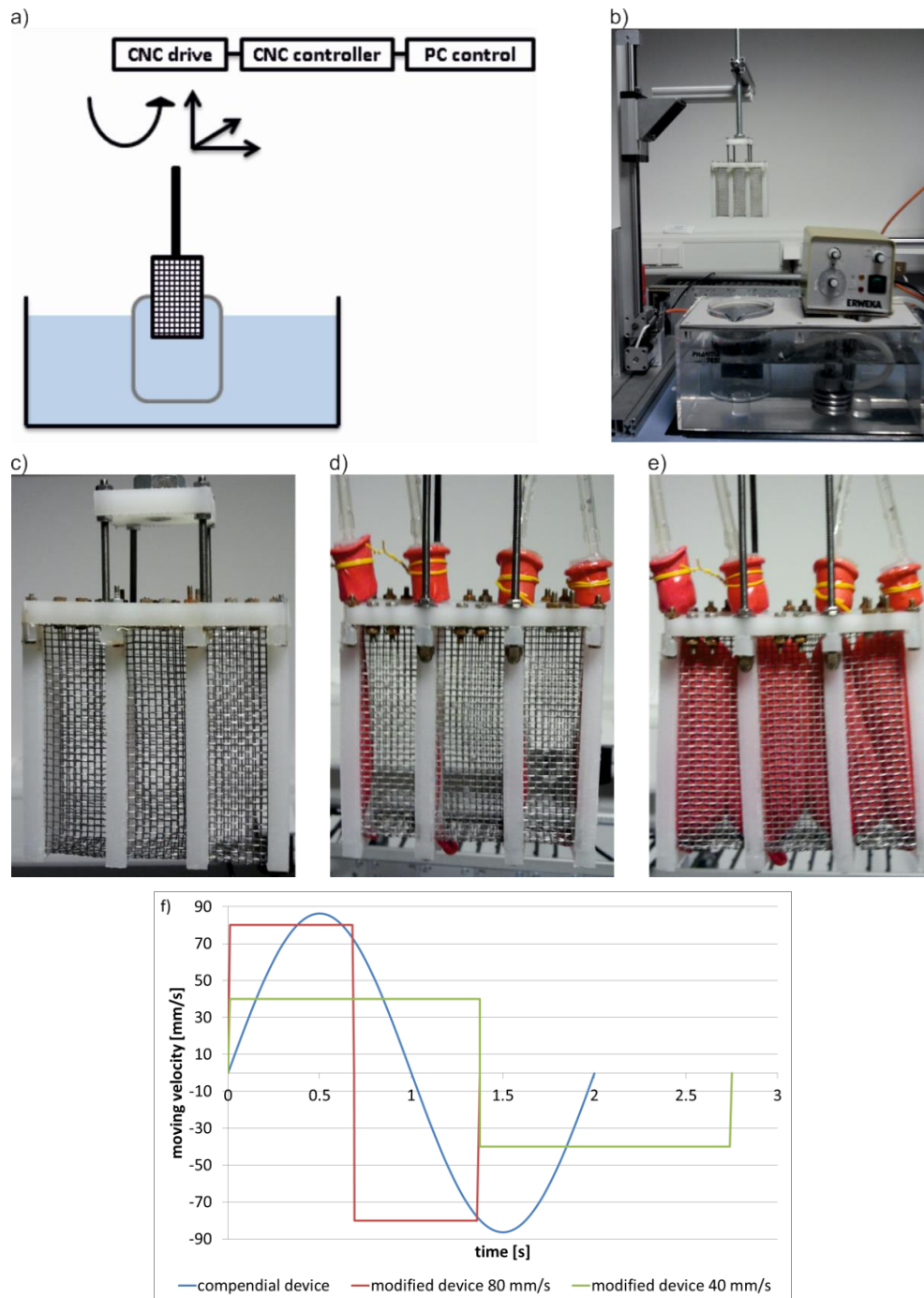


Figure 40: Prototype of modified disintegration test device. a) Schematic representation of setup, b) laboratory setup including water bath, thermostat, moving rail, and new basket, c) modified basket for investigation of different moving speeds, d) new pressure unit basket (deflated), e) new pressure unit basket (inflated), f) profile of moving velocity of the compendial device (blue) and the modified (red and green) disintegration test device of one moving cycle (moving distance 55 mm for both devices; modified device operating at 40 and 80 mm/s).

## 4.3 Characterization of the hydrodynamics in the modified disintegration test device

In this chapter the results of a computational fluid dynamics (CFD) analysis of the fluid flow and forces in the modified disintegration test device and the modified basket design without balloons are presented. Although vertical, horizontal, and radial movement of the basket are possible with the modified disintegration test device, the simulations and experiments in this work concentrated on vertical movement only. Furthermore, simulations and experiments in this work were performed with constant moving velocity of different magnitude. The predictions presented in this chapter were calculated for a moving speed of 0.08 m/s. Results of the 'what if' analysis with different moving speeds are presented in 4.4. Since the results for the up and down movement are similar, only the predictions for the down movement are shown.

### 4.3.1 Fluid flow field

Figure 41 shows the CFD predicted velocity contour plots for SGF, 1.4 % HPMC, and mashed FDA meal for the modified disintegration test device with the new basket design without balloons. Since the modified device is moved with constant moving speed the velocity field and magnitude are not time dependent as they are for the compendial device. Nevertheless, a short time span after direction change is required to reach equilibrium conditions. However, as this time is short compared to the duration of one down movement, only the results at 0.6875 s are presented (end point of down movement).

The flow field on the vertical cross section through the probe chamber is characterized by maximum fluid velocity in the center of the probe chamber. Towards the solid boundaries of the probe chamber the fluid velocity decelerates reaching minimum values at the solid walls. As already observed for the compendial basket design (Figure 29 and Figure 30) the tablet represents an obstacle for the fluid forcing it aside. The top face of the tablet is exposed to a sheltered region with no fluid movement. This sheltered region is more pronounced for the non-viscous SGF than for the 1.4 % HPMC solution and the mashed FDA meal.

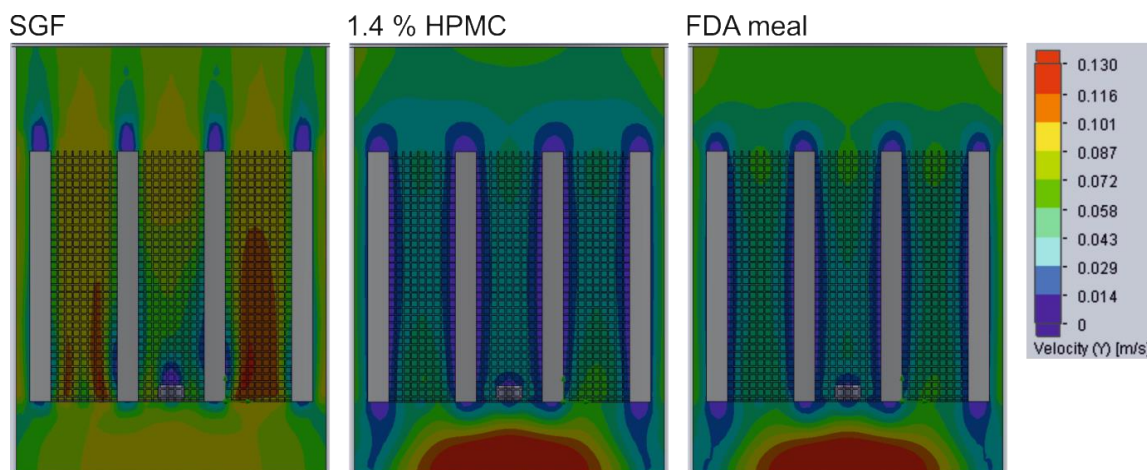


Figure 41: CFD predicted contour plots of velocity on a vertical cross section through the middle of the basket for SGF, 1.4% HPMC, and mashed FDA meal. The middle chamber contains a tablet. The fluid flow is directed upwards and velocity magnitude is color coded (blue: low velocity, red: high velocity).

The fluid flow velocity is a vector quantity in the three dimensional space specified by the three components in x-, y-, and z-direction. To illustrate the contribution of each component, a horizontal cross section was drawn at the middle height of the tablet (plane 1 in Figure 42). Figure 42 shows the velocity vector (a), as well as the contribution of its components in x-, y- and z-direction (b, c, d) on this horizontal cross section. The magnitude and direction along plane 1 are represented by the color code.

Large differences in terms of velocity field are observed between Newtonian and non-Newtonian fluids (Figure 42 a). For SGF highest velocity is observed in direct vicinity of the tablet. In contrast, only little fluid flow is predicted around the tablet for 1.4 % HPMC solution and mashed FDA meal. For all fluids the vertical y-component of fluid velocity is much higher in magnitude than the x- and z-component. While for SGF high y-velocities are predicted in direct vicinity of the tablet, high y-velocities are reached outside the probe chambers for 1.4 % HPMC solution and mashed FDA meal (Figure 42 c).

The x- and z-component represent the horizontal fluid flow (Figure 42 b) and d). Depending on the direction of flow, they can accept positive and negative values. Positive values indicate flow from the left to the right (x-component) and from the back to the front (z-component). Negative values indicate flow from the right to the left (x-component) and from the front to the back (z-component). Fluid motion in x-direction is generated by the solid walls of the probe chambers pushing the fluid towards the tablet. Fluid flow in z-direction is oriented away from the tablet pushing the fluid through the mesh. The higher the fluid viscosity the lower is the fluid velocity in x- and z-direction in direct vicinity to the tablet.

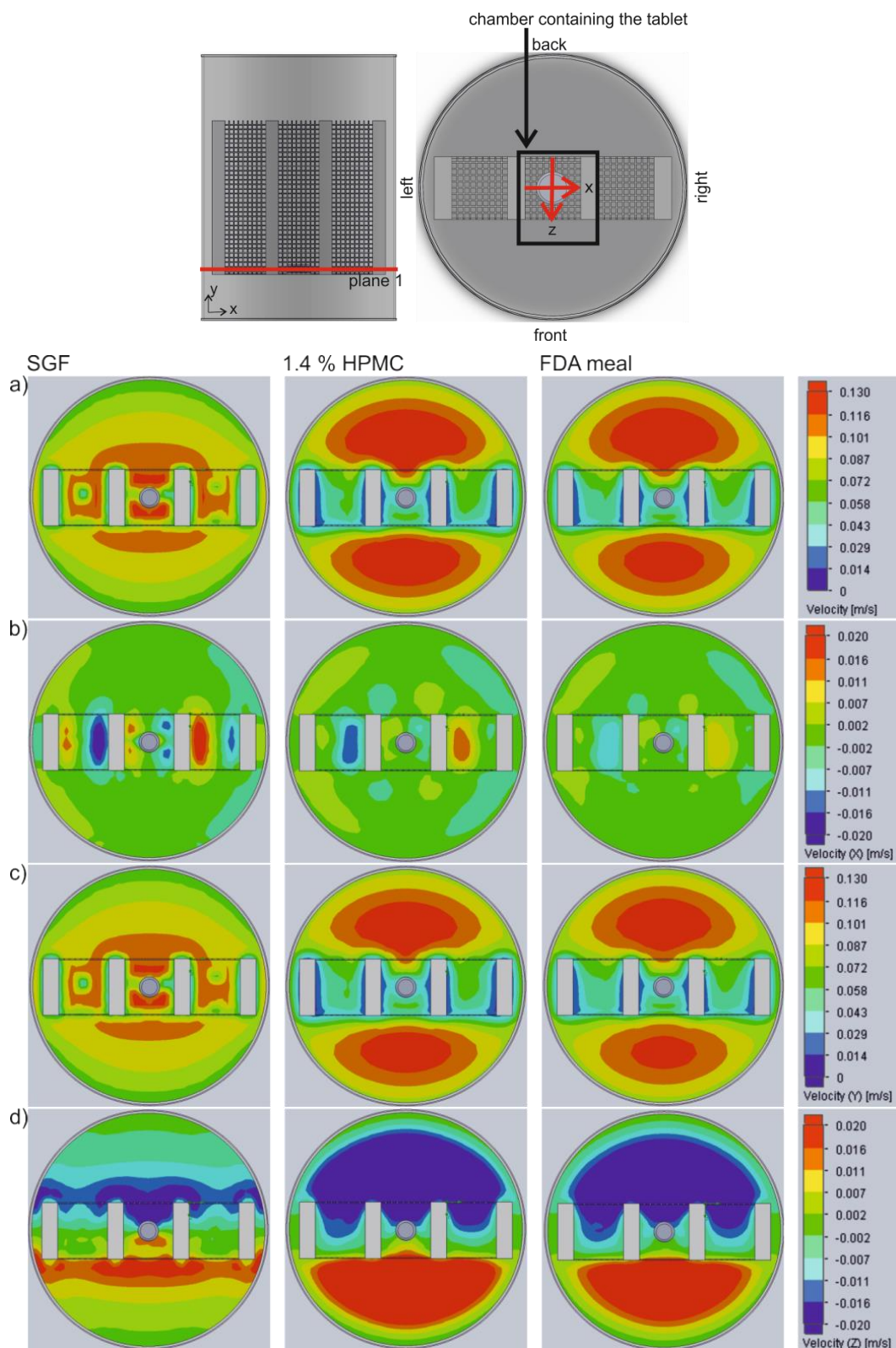


Figure 42: CFD predicted contour plots of velocity magnitude on a horizontal cross section at the middle of the tablet (plane 1) for SGF, 1.4 % HPMC solution, and mashed FDA meal. a) Magnitude of velocity vector. b) Magnitude of the x-component of the velocity vector. The x-component is directed from the left to the right (see top). Thus, positive values (green to red color) indicate fluid flow from the left to the right and negative values (light green to blue color) indicate fluid flow from the right to the left. c) Magnitude of the y-component of the velocity vector. The y-component is directed upwards and shows only positive values. d) Magnitude of the z-component of the velocity vector. The z-component is directed from the back to the front (see top). Thus, positive values (green to red color) indicate fluid flow from the back to the front and negative values (light green to blue color) indicate fluid flow from the front to the back.

The overall fluid flow field in the beaker is very different from that predicted for the compendial basket (Figure 31). In the compendial design the fluid is trapped in the solid glass tubes and only little fluid flow occurs outside the tubes. Thus, the fluid flow is highest inside the tubes of the compendial basket. Due to the open mesh design of the probe chambers of the new basket design, two-sided fluid flow becomes possible. The fluid is no more restricted and fluid flow occurs throughout the beaker.

### 4.3.2 *Effect of viscosity on velocity magnitude*

To investigate the effect of medium viscosity on velocity magnitude, the velocity vector components were plotted along the x- and z-axis going through the chamber containing the tablet illustrated by the red arrows in Figure 42. Thereby the y-component of the velocity vector points upwards in the direction of flow and is shown on both axes (Figure 43 a) and b)). The x-component (Figure 43 c)) represents horizontal fluid motion to the left or the right along the x-axis and the z-component (Figure 43 d)) shows horizontal fluid motion to the front and the back along the z-axis. Depending on the direction of movement, the x-and z-component can accept positive or negative values.

As already observed for the compendial basket design the y-component has the largest contribution to the velocity vector (compare Figure 32). However, in contrast to the compendial basket design, two-sided fluid flow is possible. Therefore, the y-velocity component along the x-axis is not axisymmetrically to the y-velocity component along the z-axis. Furthermore, large differences for the magnitude are observed between SGF and both non-Newtonian fluids for the y-velocity along the x-axis (0.08 m/s for SGF and 0.035 m/s for non-Newtonian fluids) and z-axis (0.12 m/s for SGF and 0.06 m/s for non-Newtonian fluids).

The fluid movement between the solid walls of the probe chambers and the tablet is represented by the x-component (Figure 43 c)). The x-velocity exhibits positive values by approaching the tablet and negative values by moving off the tablet towards the wall indicating that the fluid is pushed towards the tablet. The x-velocity magnitude is higher for SGF compared to 1.4 % HPMC solution and mashed FDA meal.

Since the probe chamber is limited by the permeable mesh to two sides, fluid motion through the mesh is possible, which is represented by the z-component. The change from negative to positive values along the z-axis indicates fluid flow off the tablet through the mesh towards the beaker walls. The z-component is higher for the non-Newtonian fluids reaching values of 0.05 m/s compared to 0.02 m/s for SGF.

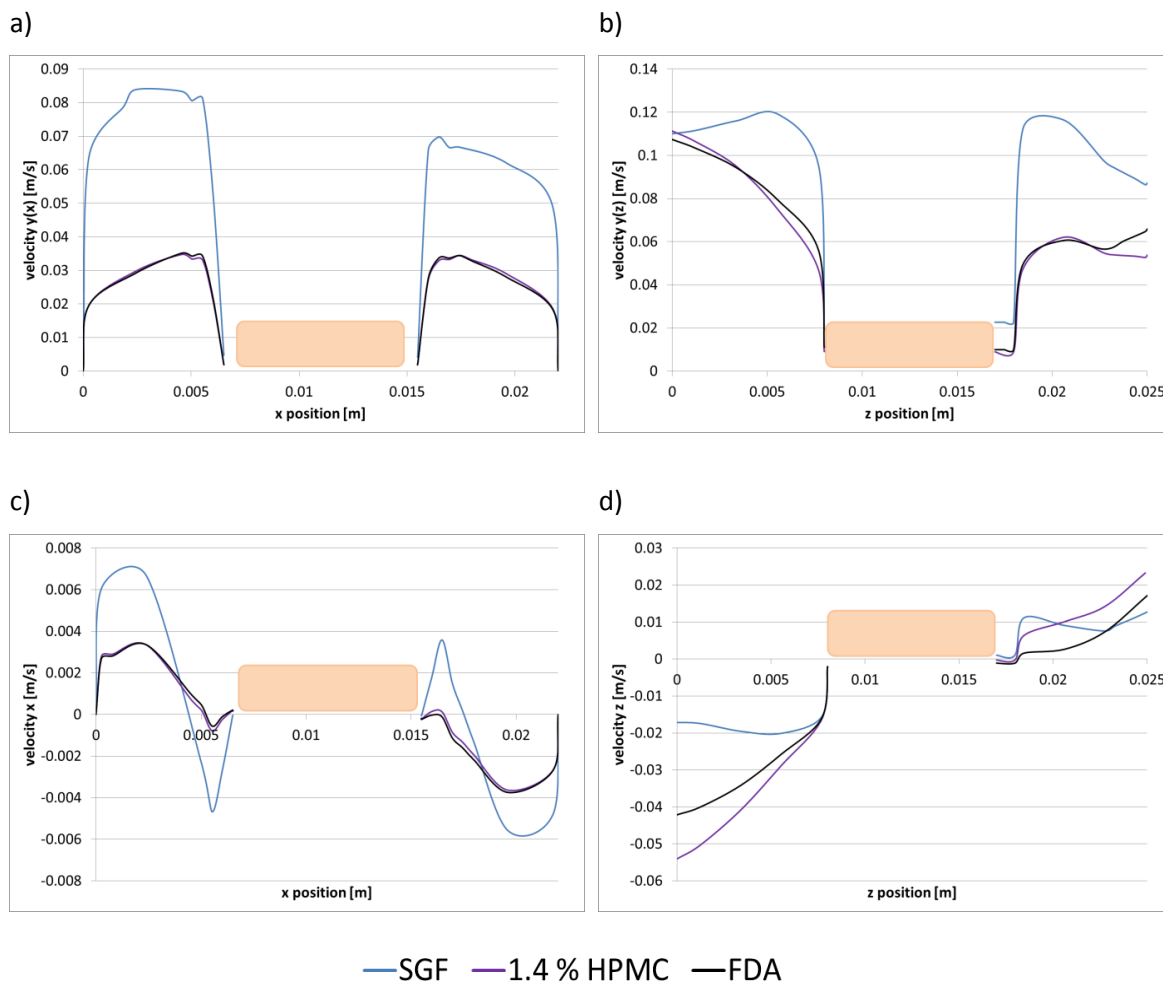


Figure 43: Velocity profiles on a horizontal cross section at the middle of the tablet (plane 1) for SFG, 1.4 % HPMC solution, and the mashed FDA meal. a) Velocity profile of the y-component (directed upwards) of the velocity vector along the x-axis (directed from the left to the right). b) Velocity profile of the y-component (directed upwards) of the velocity vector along the z-axis (directed from the back to the front). c) x-component of the velocity vector along the x-axis (directed from the left to the right). Positive values indicate fluid flow from the left to the right and negative values indicate fluid flow from the right to the left. d) z-component of the velocity vector along the z-axis (directed from the back to the front). Positive values indicate fluid flow from the back to the front and negative values indicate fluid flow from the front to the back. For illustration of plane 1 and x- and z-axis see Figure 42.

### 4.3.3 Shear rate and viscosity

Non-Newtonian fluids are characterized by a shear rate-viscosity dependence. Shear rate and dynamic viscosity are important to consider since they cause shear stress facilitating disintegration and erosion. Figure 44 shows the CFD predicted contour plots of shear rate and dynamic viscosity on a vertical cross section through the middle of the basket in direct vicinity of the tablet as well as the range of dynamic viscosity along the x-axis on a horizontal cross section through the middle of the tablet height.

Highest shear rates are observed adjacent to the base height of the tablet reaching values of  $40 \text{ s}^{-1}$  (Figure 44 a). These high shear rates are related to low dynamic viscosities in this region (Figure 44 b) The range of dynamic viscosity on the horizontal cross section along the x-axis

expands from 0.6 to 0.8 Pa\*s and 27 to 74 Pa\*s for 1.4 % HPMC solution and mashed FDA meal, respectively. Both non-Newtonian fluids exhibit high dynamic viscosities compared to the viscosity of SGF (0.0007 Pa s) (Figure 44 c). Compared to the shear rates generated in the compendial basket design at t=0.5 s, shear rates generated in the modified design are lower (compare Figure 34).

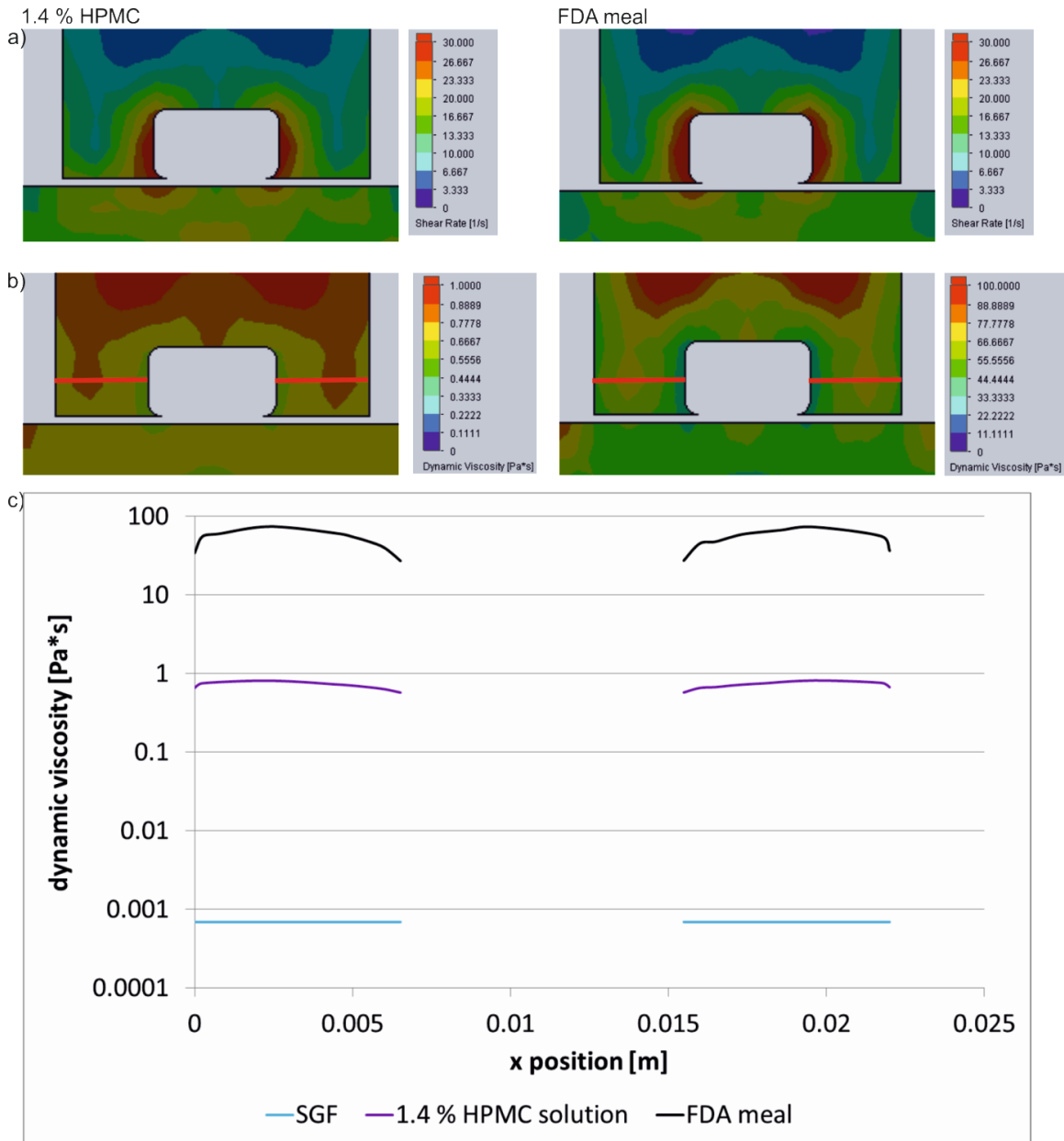


Figure 44: CFD predicted contour plots of a) shear rate and b) dynamic viscosity on a vertical cross section through the middle of the basket for 1.4 % HPMC solution and mashed FDA meal and c) range of dynamic viscosity along the red horizontal sketch shown in b) for SGF, 1.4 % HPMC solution, and mashed FDA meal. The viscosity of non-Newtonian fluids is dependent on the shear rate. High shear stress, occurring especially near the base height indicated by the red color, lowers the viscosity in this region. In c) the viscosity of SGF is shown in blue for comparison purpose.

#### 4.3.4 Shear stress on tablet surface

Figure 45 shows the local shear stress on the tablet surface (a) and the range of shear stress (b). For both fluids highest shear stress is predicted in the middle of the base height. At the bottom and the top of the tablet lower shear stress is predicted. The range of shear stress is very small extending from 0 to 1 Pa for SGF. By increasing the viscosity of the medium the range of shear stress as well as the local magnitude increases. While the range of shear stress exceeds from 1 to 50 Pa for 1.4 % HPMC solution, the range for mashed FDA meal is much higher spanning from 61 to 2115 Pa. The average shear stress is also viscosity dependent reaching values of 0.16, 20, and 1051 Pa for SGF, 1.4 % HPMC solution, and mashed FDA meal, respectively.

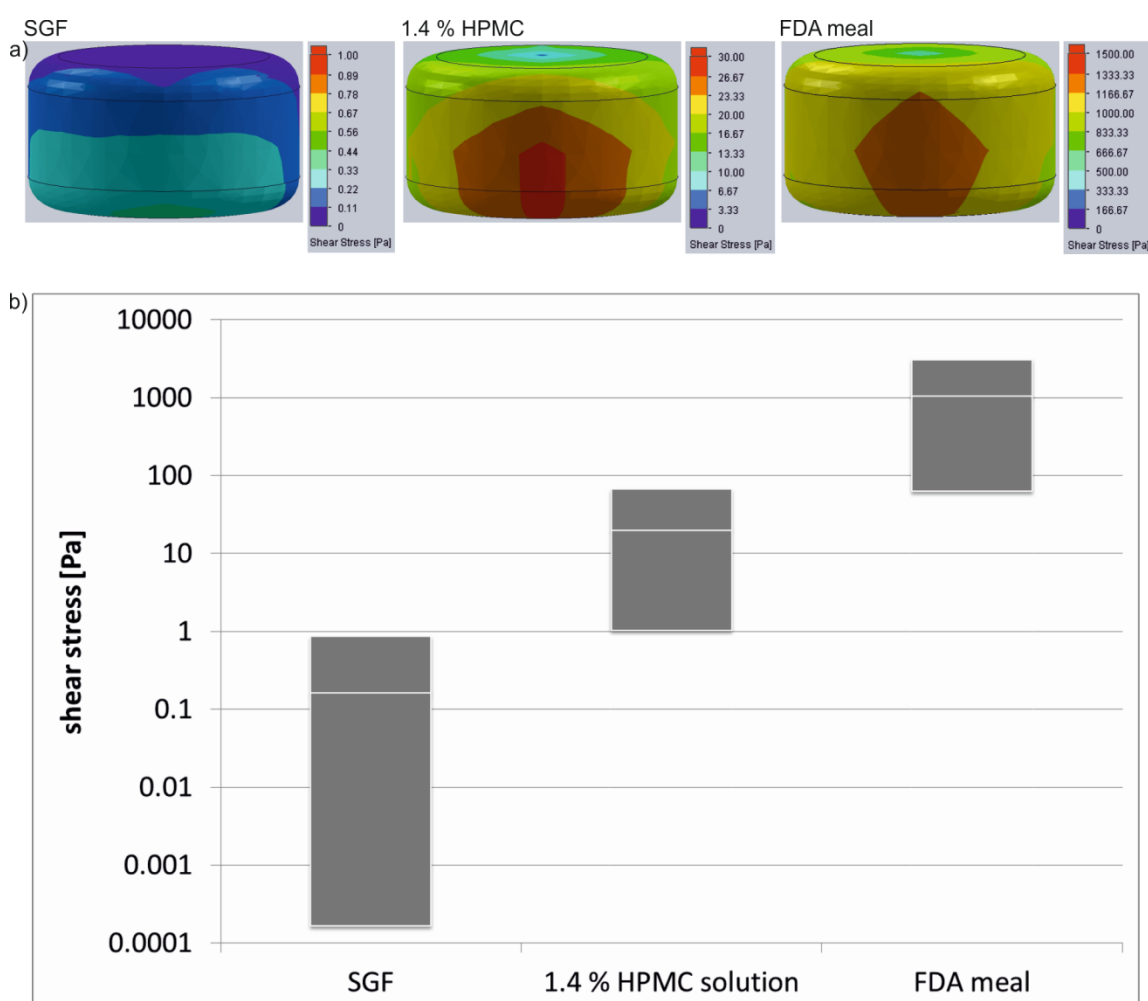


Figure 45: Shear stress on tablet surface for SGF, 1.4 % HPMC solution, and mashed FDA meal. a) Local shear stress on tablet surface increases dramatically in the presence of high viscous media. b) Range of local shear stress on tablet surface calculated from the difference between minimum and maximum shear stress. Average shear stress on tablet surface, indicated by the white line, is calculated from local shear stress weighed by area.

## 4.4 What if study

In a 'what if' analysis the effect of different moving speeds and tablet diameter on hydrodynamics and forces was investigated for SGF and 1.4 % HPMC solution. The specific objective of this investigation was to quantify the changes in velocity fields and magnitudes as well as in average shear stress on tablet surface when the moving speed or tablet size are altered.

### 4.4.1 Effect of moving speed on velocity magnitude

Figure 46 and Figure 47 show the velocity components along the x- and z-axis going through the chamber containing the tablet (illustration of axes see Figure 42) on a horizontal cross section through the middle of the tablet for SGF and 1.4 % HPMC solution, respectively (tablet diameter 9 mm). Thereby, the y-component of the velocity vector points upwards in the direction of flow and is shown on both axes (Figure 46 and Figure 47 a) and b). The x-component (Figure 46 Figure 47 c) represents the horizontal fluid motion to the left or the right along the x-axis. The z-component (Figure 46 and Figure 47 d) represents the horizontal fluid motion to the front and the back along the z-axis. Depending on the direction of movement, the x- and z-component can accept positive or negative values.

In both fluids the profiles of the velocity components are similar for all moving speeds but differ in magnitude. The y-velocity component along the z- and x-axis reaches its maximum in the middle of the gap between tablet and solid boundary or the mesh boundary of the probe chamber. However, the y-velocity component along the z-axis is higher than that along the x-axis. The x-velocity component reaches a maximum positive peak velocity adjacent to the tablet and a negative peak velocity off the tablet indicating that the fluid is pushed towards the tablet from both sides. In contrast, the z-velocity component exhibits a negative peak velocity close to the tablet and a positive peak velocity off the tablet indicating that the fluid is pushed out of the probe chamber through the mesh towards the beaker wall. Clearly, the y-velocity component is the dominating one, while the x-component is rather small.

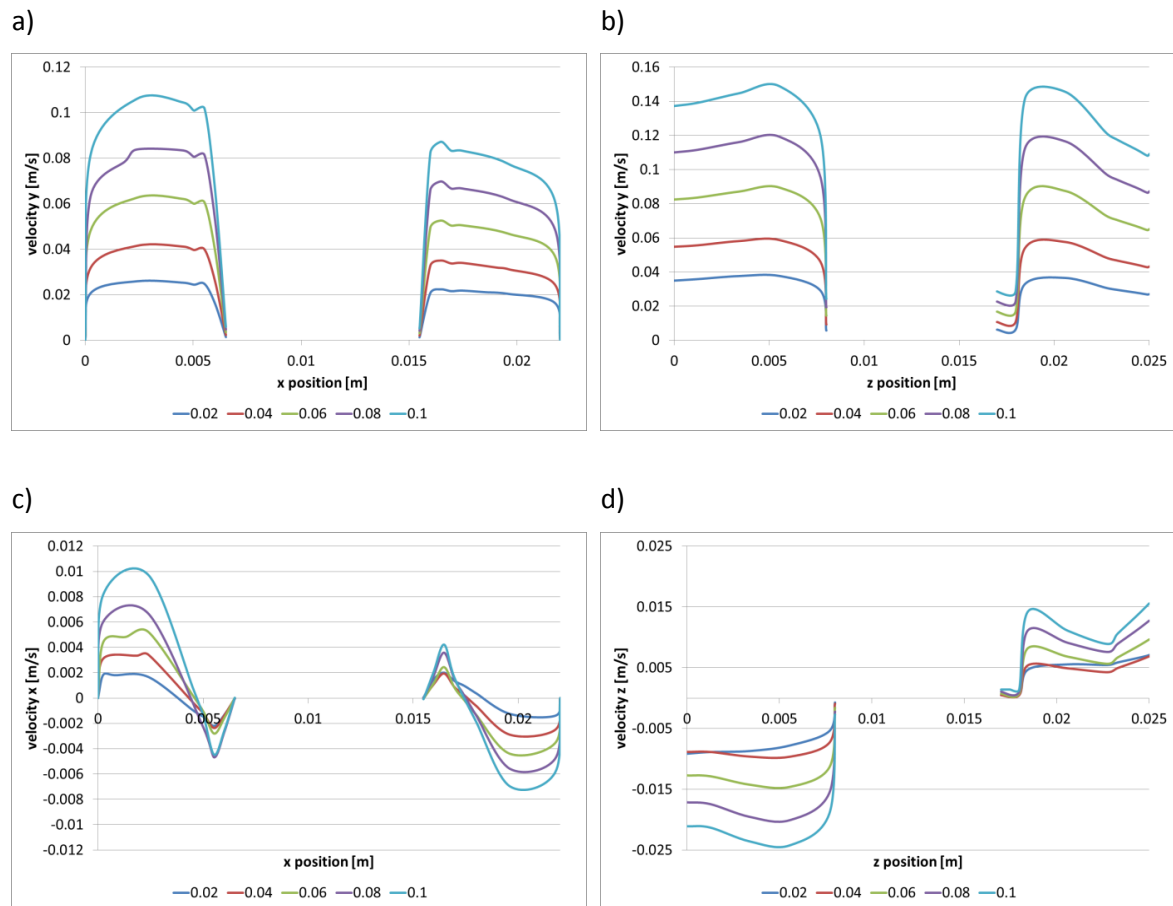


Figure 46: Influence of moving velocity (varied from 0.02 to 0.1 m/s) on fluid velocity magnitude on a horizontal cross section at the middle of the tablet (plane 1) for SFG. a) Velocity profile of the y-component (directed upwards) of the velocity vector along the x-axis (directed from the left to the right). b) Velocity profile of the y-component (directed upwards) of the velocity vector along the z-axis (directed from the back to the front). c) x-component of the velocity vector along the x-axis (directed from the left to the right). Positive values indicate fluid flow from the left to the right and negative values indicate fluid flow from the right to the left. d) z-component of the velocity vector along the z-axis (directed from the back to the front). Positive values indicate fluid flow from the back to the front and negative values indicate fluid flow from the front to the back. For illustration of plane 1 and x- and z-axis see Figure 42. Tablet diameter was constant (9 mm).

The influence of moving speed on the magnitude of the velocity components is different for SGF and 1.4 % HPMC solution. In SGF largest values of y-velocity along the x-axis, y-velocity along the z-axis, x-velocity, and z-velocity are between 105 %, 150 %, 8 %, and 25 % of moving velocity for all five different moving speeds. This implies that increasing the moving velocity results in a proportional increase in the velocity magnitude for each component. In 1.4 % HPMC solution such proportionality between moving speed and magnitude is not observed. Certainly, higher moving velocities produce higher velocity magnitudes. But the ratio between moving velocity and peak velocity becomes higher by increasing the moving velocity. For all moving speed the magnitude of the y-component along the x-axis and the x-component are higher for SGF than for 1.4 % HPMC solution. The magnitude of the z-component is lower in SGF compared to 1.4 % HPMC solution and the magnitude of the y-component along the z-axis is similar for both fluids.

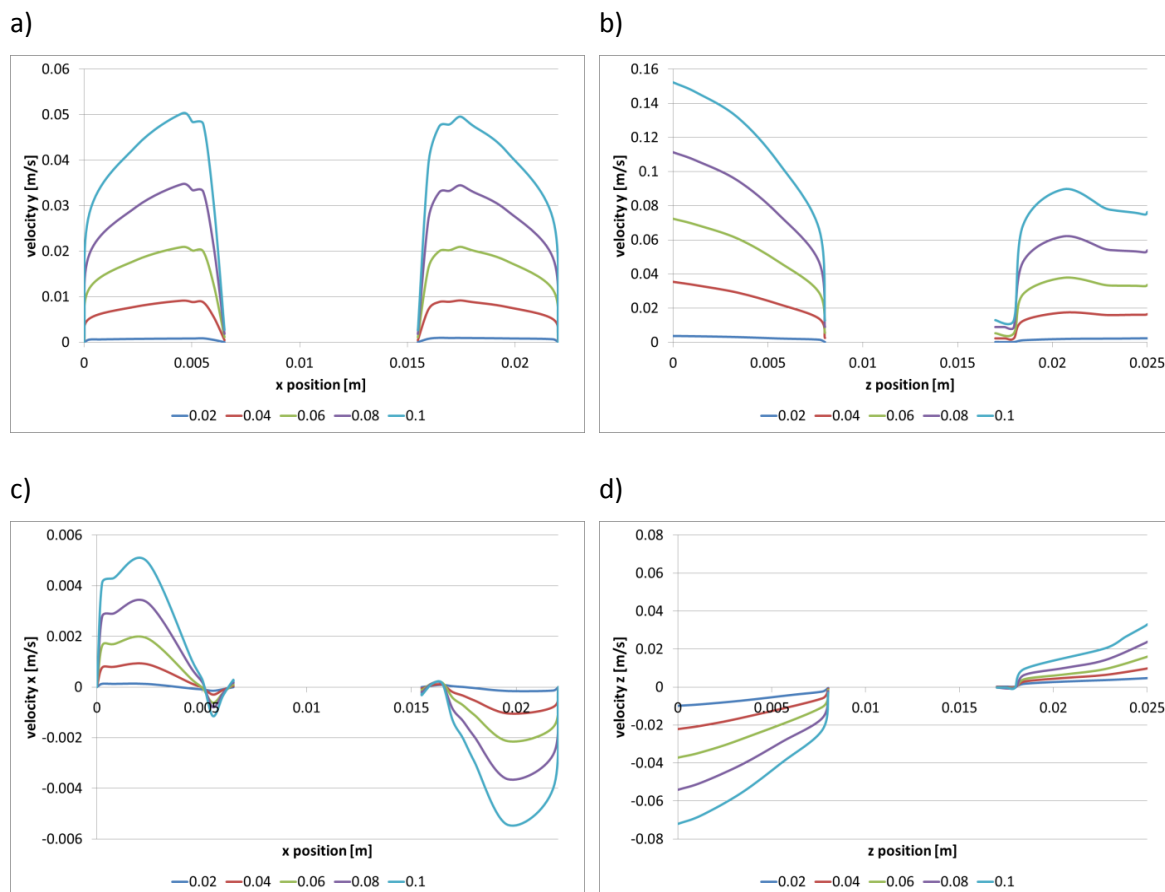


Figure 47: Influence of moving velocity (varied from 0.02 to 0.1 m/s) on fluid velocity magnitude on a horizontal cross section at the middle of the tablet (plane 1) for 1.4 % HPMC solution. a) Velocity profile of the y-component (directed upwards) of the velocity vector along the x-axis (directed from the left to the right). b) Velocity profile of the y-component (directed upwards) of the velocity vector along the z-axis (directed from the back to the front). c) x-component of the velocity vector along the x-axis (directed from the left to the right). Positive values indicate fluid flow from the left to the right and negative values indicate fluid flow from the right to the left. d) z-component of the velocity vector along the z-axis (directed from the back to the front). Positive values indicate fluid flow from the back to the front and negative values indicate fluid flow from the front to the back. For illustration of plane 1 and x- and z-axis see Figure 42. Tablet diameter was constant (9 mm).

#### 4.4.2 Effect of tablet size on velocity magnitude

Figure 48 and Figure 49 show the influence of the change in tablet diameter on the velocity magnitude of velocity vector components for SGF and 1.4 % HPMC solution. The tablet diameter was varied from 5 to 13 mm while the moving velocity was constant (0.08 m/s).

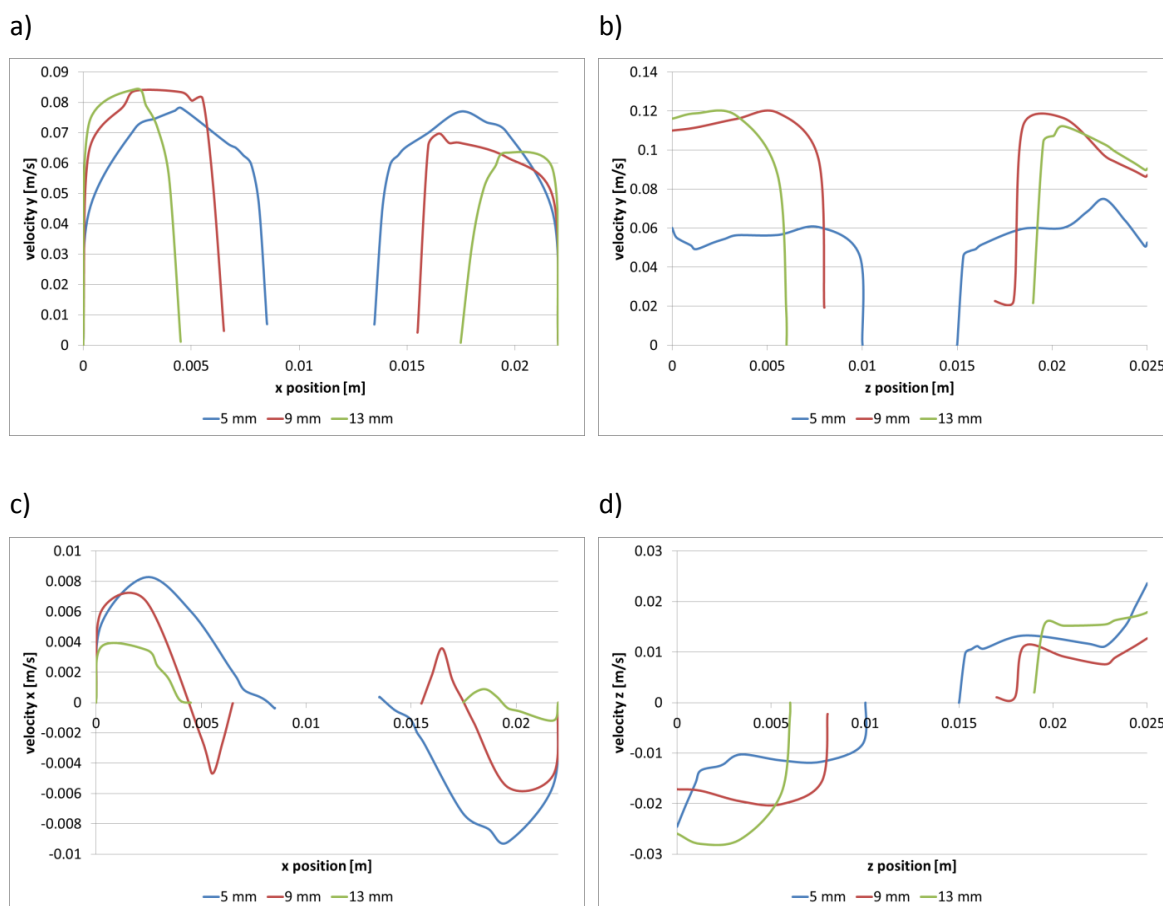


Figure 48: Influence of tablet diameter (varied form 5 to 13 mm) on fluid velocity magnitude on a horizontal cross section at the middle of the tablet (plane 1) for SGF. a) Velocity profile of the y-component (directed upwards) of the velocity vector along the x-axis (directed from the left to the right). b) Velocity profile of the y-component (directed upwards) of the velocity vector along the z-axis (directed from the back to the front). c) x-component of the velocity vector along the x-axis (directed from the left to the right). Positive values indicate fluid flow from the left to the right and negative values indicate fluid flow from the right to the left. d) z-component of the velocity vector along the z-axis (directed from the back to the front). Positive values indicate fluid flow from the back to the front and negative values indicate fluid flow from the front to the back. For illustration of plane 1 and x- and z-axis see Figure 42. Moving velocity was constant (0.08 m/s).

For SGF as well as for 1.4 % HPMC solution the magnitude of the velocity components is influenced by the tablet size. However different effects are observed for the two fluids. Using SGF the magnitude of the y-velocity component along the x-axis is nearly unaffected by a change in tablet diameter but the magnitude of the y-velocity along the z-axis and the two other velocity components are affected (Figure 48). An increase in tablet diameter results in an increase in velocity magnitude for the y-velocity component along the z-axis (b) and the z-

velocity component (d). In contrast, the x-velocity magnitude is decreased by increasing the tablet diameter (c).

Using 1.4 % HPMC solution the only unaffected component is the x-velocity (Figure 49 c). No clear trend is observed for the y-velocity component along the x-axis (a). By increasing the diameter from 5 to 9 mm the y-velocity along the x-axis increases. But by further diameter increase to 13 mm the y-velocity magnitude decreases. The magnitude of the y-velocity component along the z-axis and the z-velocity component increase by increasing the tablet diameter from 5 to 9 mm (b and d). However the magnitude is similar for a diameter of 9 and 13 mm.

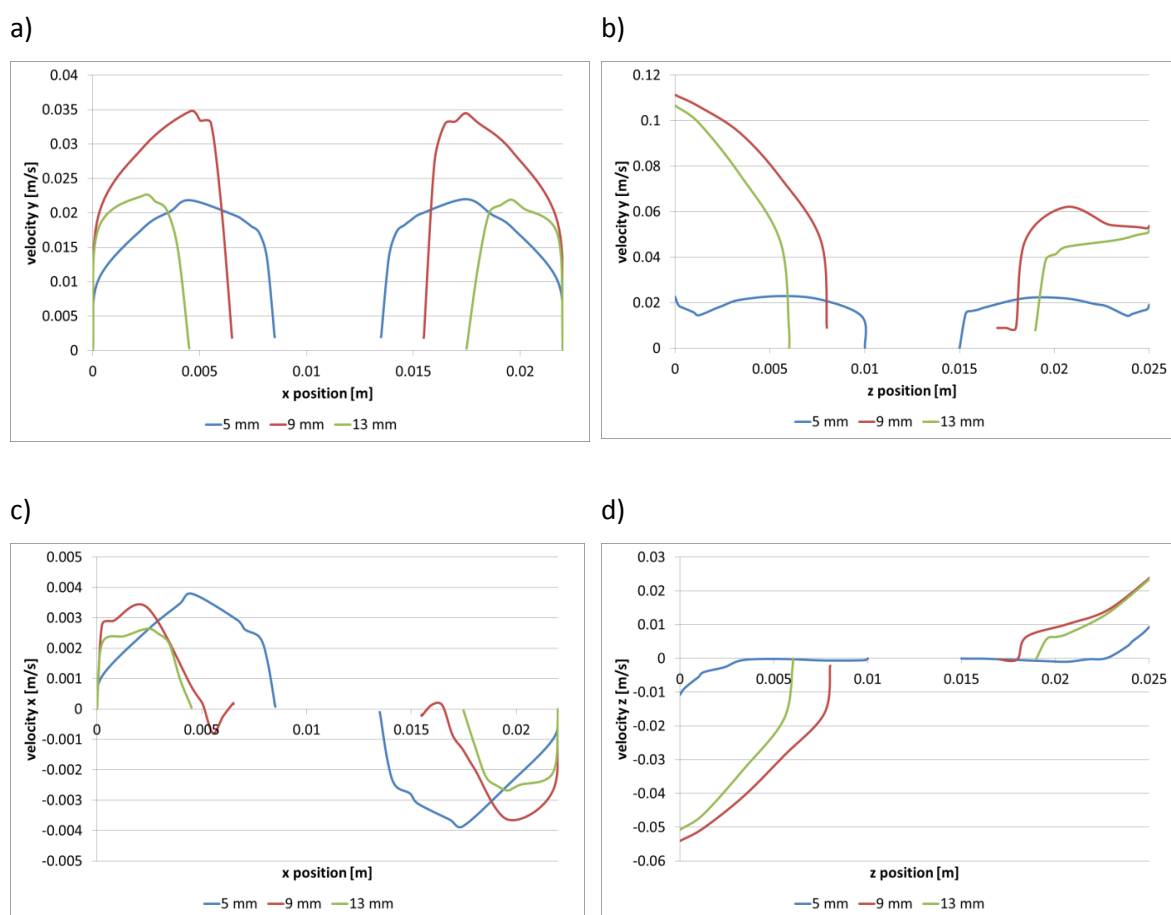


Figure 49: Influence of tablet diameter (varied from 5 to 13 mm) on fluid velocity magnitude on a horizontal cross section at the middle of the tablet (plane 1) for 1.4 % HPMC solution. a) Velocity profile of the y-component (directed upwards) of the velocity vector along the x-axis (directed from the left to the right). b) Velocity profile of the y-component (directed upwards) of the velocity vector along the z-axis (directed from the back to the front). c) x-component of the velocity vector along the x-axis (directed from the left to the right). Positive values indicate fluid flow from the left to the right and negative values indicate fluid flow from the right to the left. d) z-component of the velocity vector along the z-axis (directed from the back to the front). Positive values indicate fluid flow from the back to the front and negative values indicate fluid flow from the front to the back. For illustration of plane 1 and x- and z-axis see Figure 42. Moving velocity was constant (0.08 m/s).

#### 4.4.3 Effect of moving speed and tablet size on average shear stress on the tablet surface

Increasing the moving velocity causes an increase in average shear stress on tablet surface in SGF as well as in 1.4 % HPMC solution (Figure 50). However, the relation between both parameters is different in the two fluids. While in SGF an exponential relation is predicted, in 1.4 % HPMC solution a linear correlation is observed. The tablet diameter also influences the average shear stress on the tablet surface. By increasing the diameter from 5 to 9 mm the average shear stress increases for all moving velocities. But by further increasing the diameter to 13 mm the average shear stress decreases.

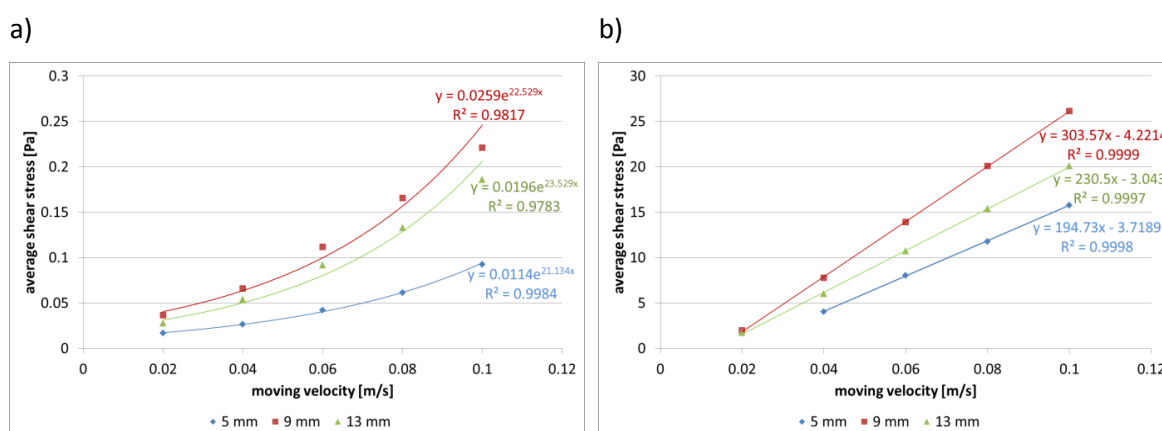


Figure 50: Influence of moving velocity and tablet diameter (color coded) on the average shear stress on the tablet surface for a) SGF and b) 1.4 % HPMC solution.

## 4.5 Disintegration of immediate release tablets under varying hydrodynamics and forces

This chapter summarizes the results of disintegration studies with immediate release (IR) tablets under varying hydrodynamic conditions. Therefore, the modified disintegration test device was utilized (setup see 3.1 and 4.2) and the vertical moving velocity was varied. The modified device was equipped with the compendial as well as with the modified basket design to investigate the influence of basket design on disintegration times.

An IR formulation (composition see 3.4) was compressed at different compression forces to obtain tablet batches with different hardness and disintegration times. Figure 51 shows the relationship between compression force and hardness of the tablets. The range of compression forces varied from 1 t to 4 t and yielded tablets with breaking strength in the range of 40 to 212 N. A linear relationship between compression force and hardness is observed for the chosen formulation.

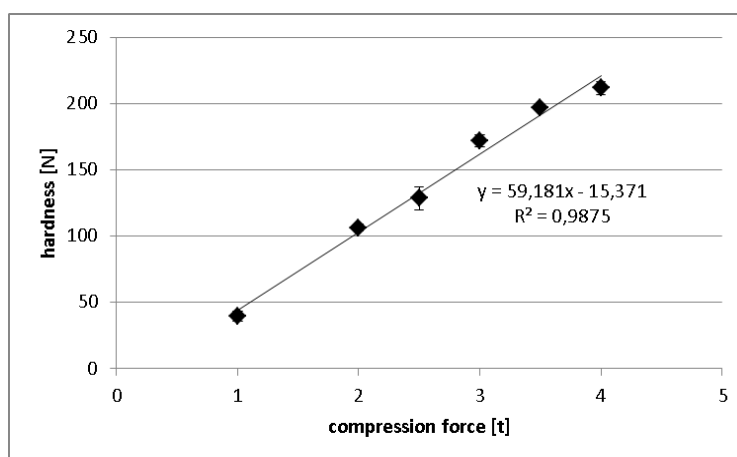


Figure 51: Relationship between compression force and hardness obtained for the immediate release formulation (mean $\pm$ SD, n=3).

With a design of experiments (DoE) the influence of moving speed of the basket, viscosity of the medium, and compression force on the disintegration time was investigated using the modified disintegration test device operating with both, the compendial and the modified basket. The data were fitted with MODDE using the multilinear regression (MLR) giving a model with high  $R^2$  (goodness of fit of the model) and  $Q^2$  (goodness of prediction of the model) for both baskets (Figure 52). The reproducibility is also very high for both basket designs. For very good models ( $Q^2 < 0.9$ , true for these models) the model validity is known to be very low due to the high sensitivity and extremely good reproducibility.

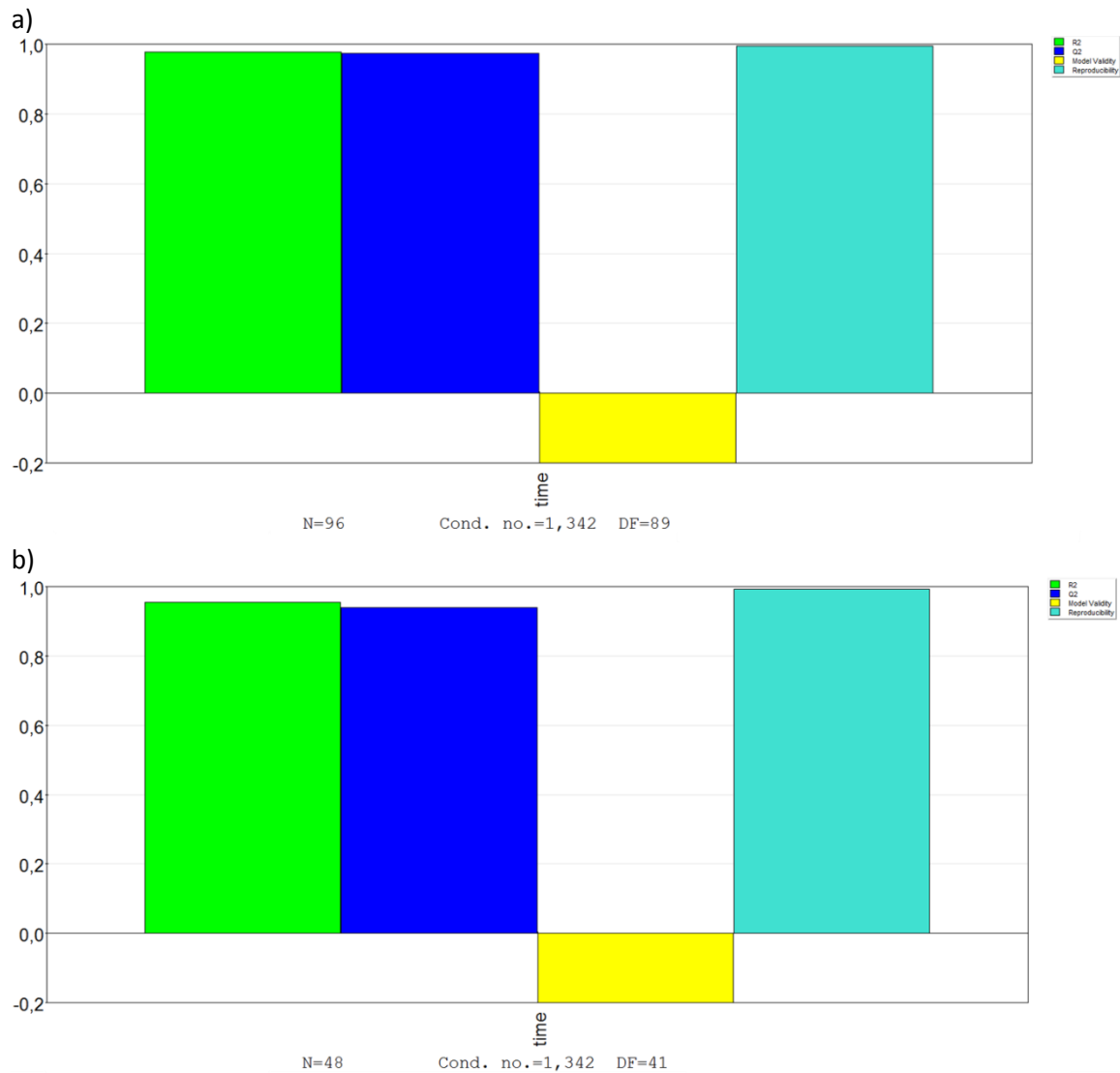


Figure 52: Summary plot for the response disintegration time for the a) compendial basket design and b) modified basket design. For both basket designs the response disintegration time is excellent fitted (high  $R^2$  of 0.978 and 0.955 for the compendial and modified basket design, green) and predicted (high  $Q^2$  of 0.974 and 0.939 for the compendial and modified basket design, blue) by the model. Model validity (yellow) is low due to the extremely high  $Q^2$  values. Reproducibility (cyan) is high for both models (0.99 for both).

The coefficient plot (Figure 53) is used to interpret the model and helps to identify the factors showing a significant effect on disintegration time. In case the coefficient bar (green) is smaller than the confidence interval, the influence of the factor is statistically insignificant. For both basket designs all factors (spe= moving speed, vis= viscosity, and com= compression force) exhibit a significant influence on disintegration time ( $p < 0.05$ ). For the compendial basket all interaction effects are significant ( $p < 0.05$ ). For the modified basket design the interaction of speed and compression force is significant ( $p < 0.05$ ). The interaction effect of viscosity and compression force is negligible for the modified basket design ( $p > 0.05$ ). The interaction of speed and viscosity is not significant ( $p = 0.07$ ) but may have a contribution.

## 4 Results

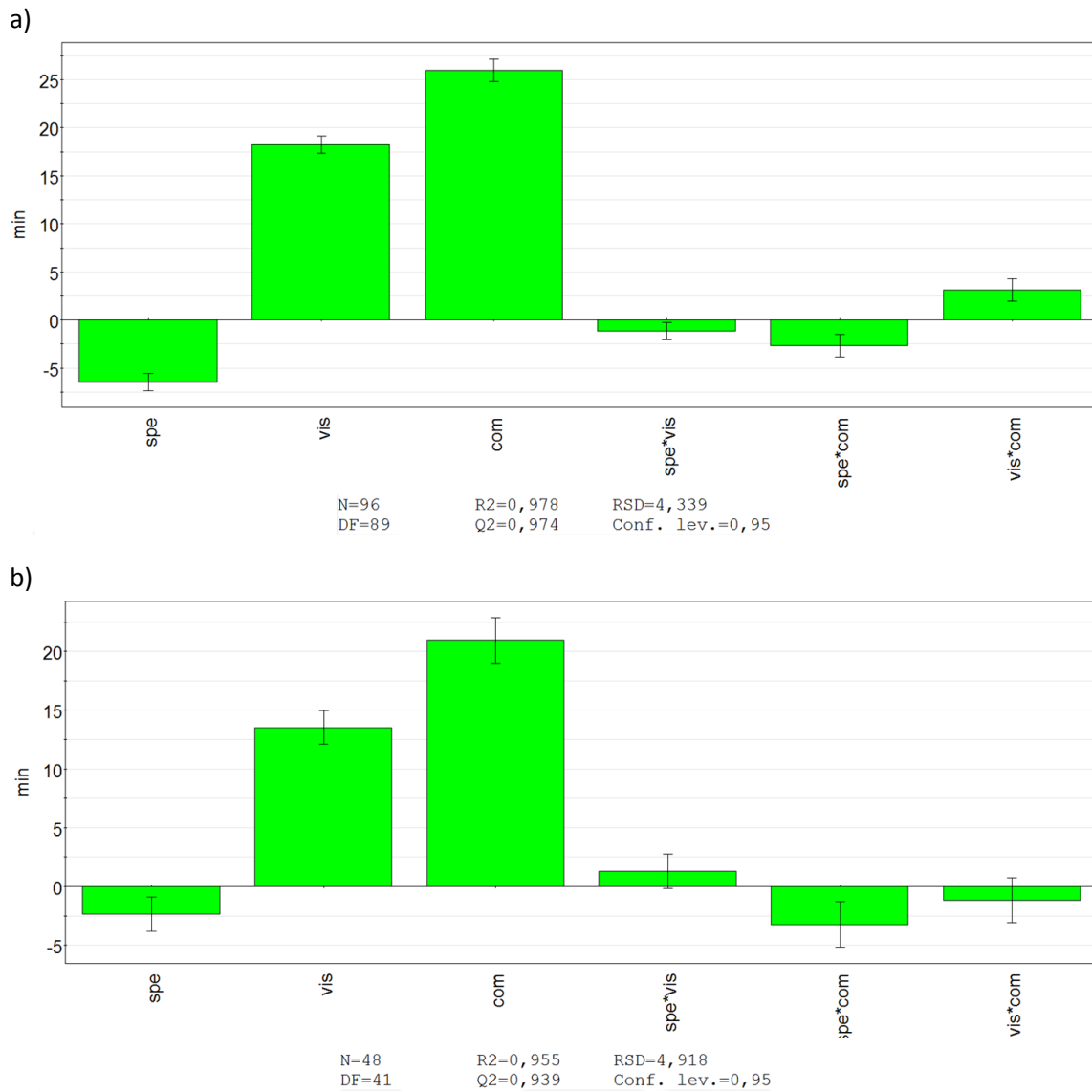


Figure 53: Coefficient plots for the disintegration time. a) Compendial basket, b) modified basket (factor abbreviations: spe= moving speed, vis= medium viscosity, com= compression force). The influence of the factors moving speed, medium viscosity, and compression force on disintegration time was investigated using the modified disintegration test device operating with both, the compendial and the modified basket design. The coefficient plot shows the regression coefficients (green bars) with their confidence intervals. In case the bar is smaller than the confidence interval the factor is not significant.

Figure 54 shows the influence of compression force, moving speed (40 vs. 80 mm/s), and medium viscosity (SGF and 1.4 % HPMC solution) on disintegration time for the compendial (a) and modified (b) basket design. All factors exhibit a significant influence on disintegration time ( $p < 0.05$ ). The strong trend of increased disintegration time with increased compression force is observed for both basket designs. As expected, disintegration times in 1.4 % HPMC solution are prolonged compared to those in SGF. The influence of moving speed on disintegration time is different for both designs. For the compendial basket in increase in moving speed leads to a decrease in disintegration time in SGF as well as in 1.4 % HPMC solution. For the modified basket design the influence of moving speed on disintegration time is much more pronounced in SGF compared to 1.4 % HPMC solution. While in SGF the disintegration time decreases with increasing moving speed the influence is negligible in 1.4 % HPMC solution. This observation is predicted in the coefficient plot where the interaction between moving speed and viscosity is evident. The strong interaction effect of compression force and moving speed predicted in the coefficient plot is recognizable for both baskets since the effect on moving speed becomes more pronounced at high tablet hardness, especially in SGF.

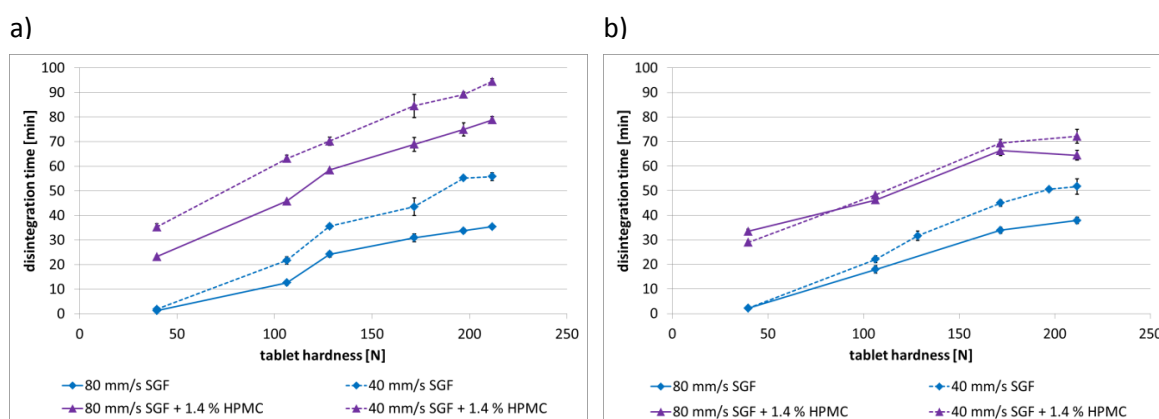


Figure 54: Influence of moving speed and medium viscosity on disintegration time (mean  $\pm$  SD,  $n=3$ ). Disintegration times of immediate release tablets were examined in SGF (blue) and 1.4 % HPMC solution (purple) using the modified disintegration test device operating at 40 (dashed line) and 80 (solid line) mm/s and equipped with both, the compendial basket (a) and the modified basket (b). Compression force, medium viscosity, as well as moving speed exhibit a significant influence on disintegration time ( $p < 0.05$ ).

To quantify the effects of moving speed and medium viscosity on disintegration time the ratios of 40 to 80 mm/s and fed to fasted disintegration times were calculated (Figure 55). For the modified basket design a clear trend is observed for the ratio of 40 to 80 mm/s disintegration times. By increasing the hardness of the tablet the ratio increases in SGF as well as in 1.4 % HPMC solution. For the compendial basket design different trends are obtained in SGF and 1.4 % HPMC solution. In SGF no trend can be recognized at all. The ratio is in the range of 1.3 to 1.8. In 1.4 % HPMC solution the ratio decreases with increasing tablet hardness, which is contrary to the trend observed with the modified basket design. This decrease indicates a less

pronounced effect of moving speed at higher compression forces in 1.4 % HPMC solution using the compendial basket. Even though the moving speed is increased by the factor of two, the ratio of disintegration times is below 2 for all fluid and both basket designs.

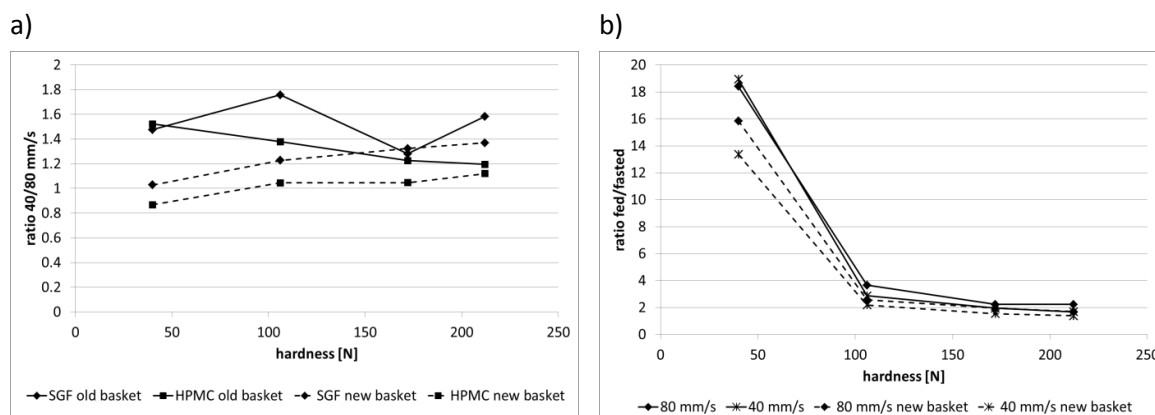
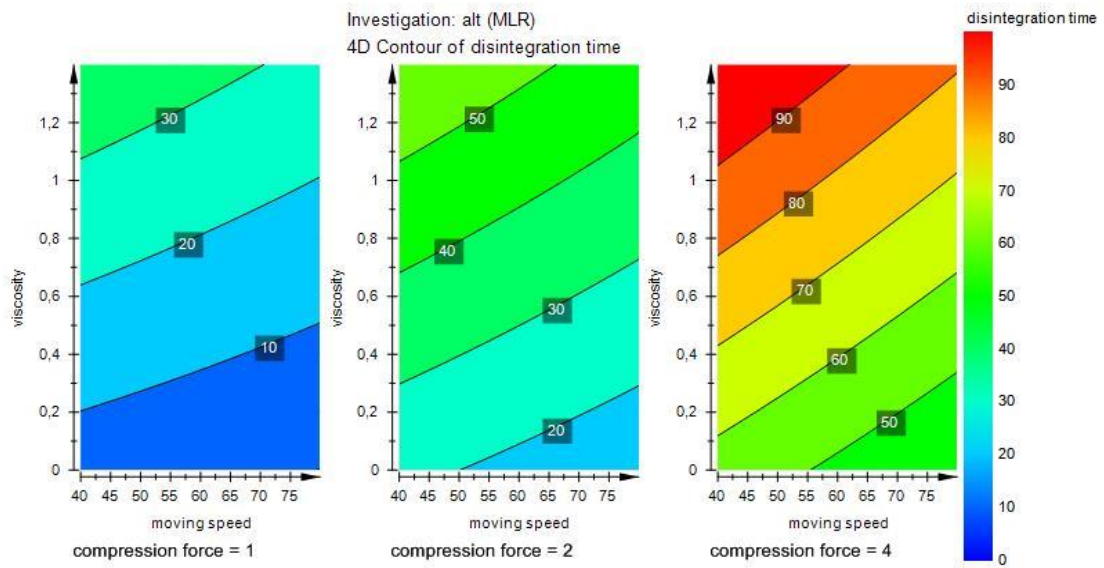


Figure 55: a) Ratio of disintegration times at 40 and 80 mm/s moving speed for SGF and 1.4 % HPMC solution in the compendial (solid line) and modified basket (dashed line) design and b) ratio of fed to fasted disintegration time for compendial (solid line) and new (dashed line) basket design operating at 40 and 80 mm/s. moving.

For the ratio of fed to fasted disintegration times the trend is consistent for both fluid and basket designs. By increasing the hardness of the tablet the ratio of fed to fasted disintegration times decreases. A significant change is present between 40 and 100 N tablet hardness. Minor changes in the ratio between 100 and 200 N are observed indicating a stabilization for tablets with high hardness.

Summarizing, Figure 56 shows the 4D response contour plots of disintegration time for the compendial basket design (a) and the modified basket design (b). Comprising, disintegration time is increased by increasing compression force or increasing medium viscosity for both basket designs. A change in moving velocity has different effects for the compendial and the modified basket. For the compendial basket an increase in moving speed leads to a decrease in disintegration time over the whole range of tablet hardness. This effect is observed only at high tablet hardness for the modified basket. At low hardness the effect of moving velocity on disintegration time is less pronounced. In general, longer disintegration times are observed for the compendial basket design compared to the modified basket design with the same settings in 1.4 % HPMC solution. Longest disintegration times of up to 90 min are measured for tablets with high hardness in 1.4 % HPMC solution and the low moving speed.

a)



b)

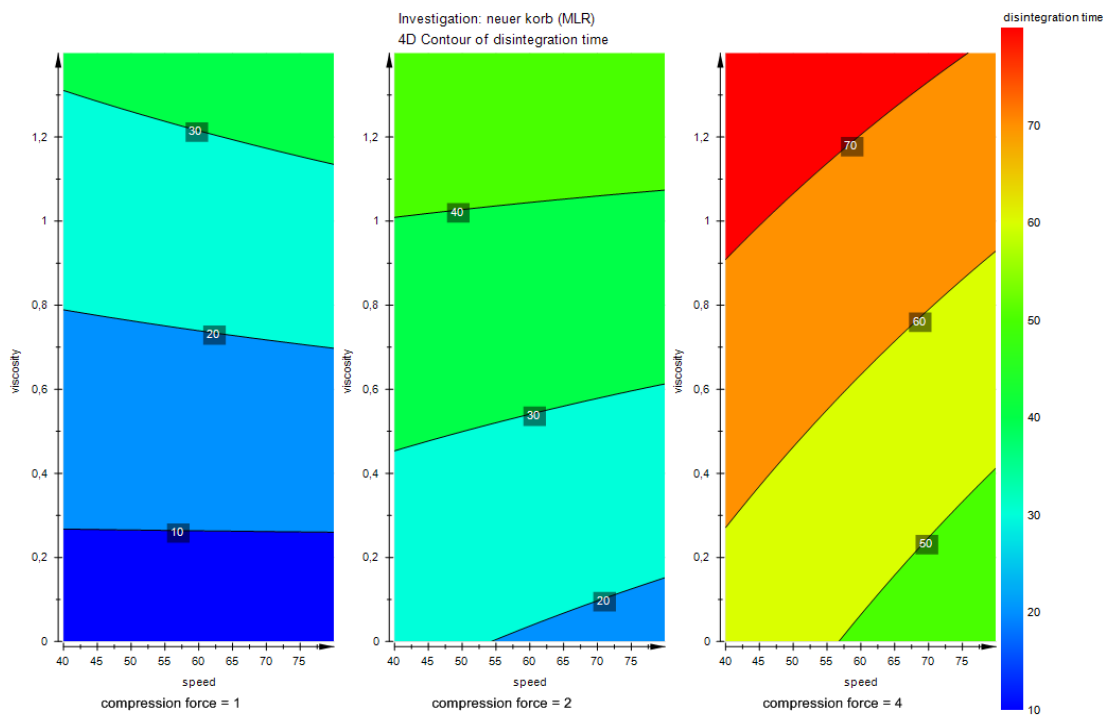
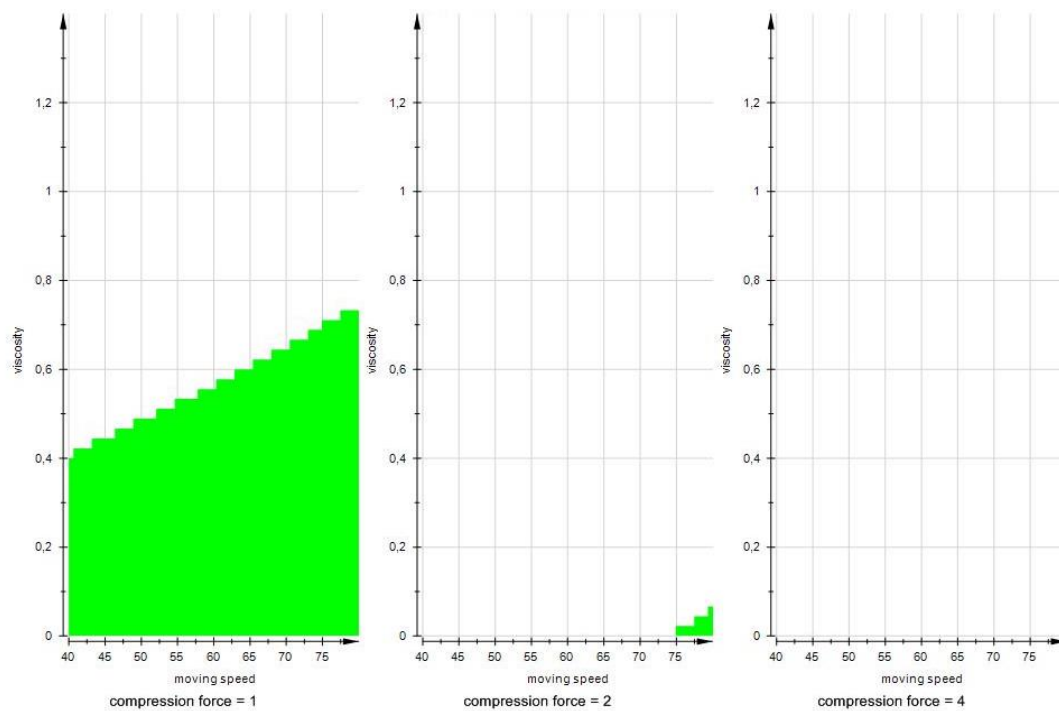


Figure 56: Response contour plot of disintegration time. Results are shown for disintegration studies using the modified disintegration test device equipped with the compendial basket (a) and the modified basket (b). The response contour plot summarizes the influence of the variables viscosity (y-axis; in % HPMC), moving speed (x-axis; in mm/s), and compression force (columns; in tons) on disintegration time (color coded).

## 4 Results

The PhEur demands a disintegration time of  $\leq 15$  min for non-coated immediate release tablets. This requirement is reached only for tablets exhibiting low tablet hardness as indicated by the green region in Figure 57. Furthermore, the viscosity of the test medium must not exceed the viscosity of a 0.6 % HPMC solution. Harder tablets investigated under various conditions will fail the pharmacopeia test white regions in Figure 57).

a)



b)

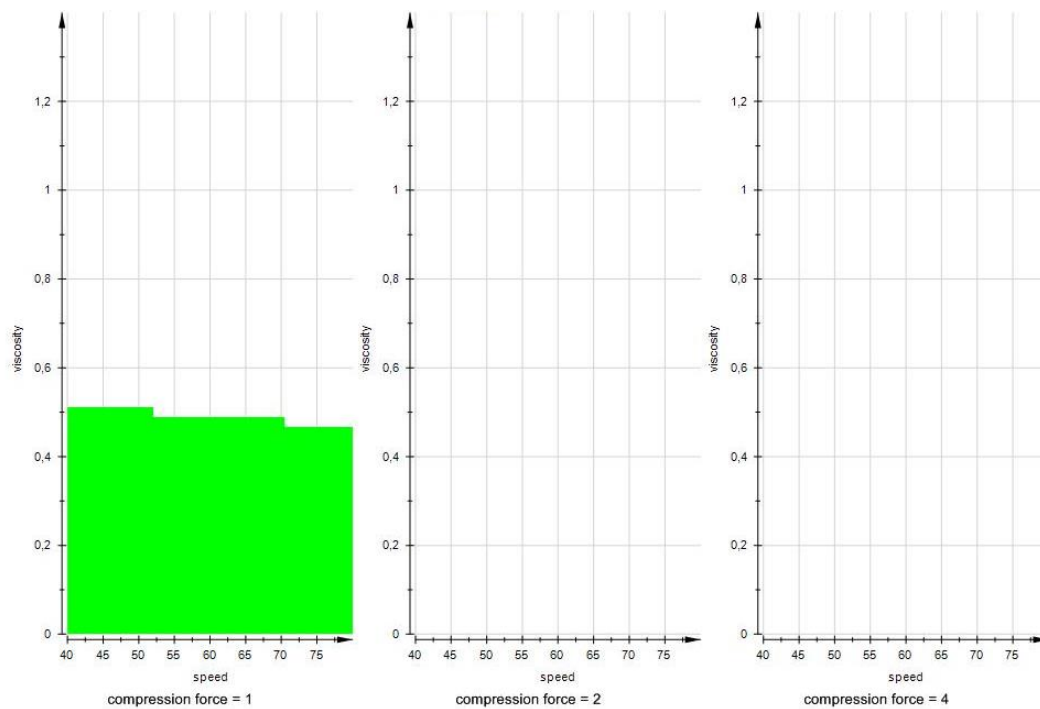


Figure 57: Sweet spot plot showing the parameter settings with which disintegration times  $\leq 15$  min are achieved (green regions) for a) the compendial basket design and b) the modified basket design.

The disintegration times in SGF of tablets compressed at 2 t and 3 t (corresponding to a hardness of 106 and 172 N) were further investigated at moving speeds of 20, 60 and 100 mm/s using the modified device with the modified basket. An exponential correlation between disintegration time and moving speed was observed (Figure 58, blue). Correlating the disintegration times with the average shear stress at the corresponding moving speed predicted from CFD simulations (see Figure 50, for a tablet diameter of 13 mm) an exponential relationship is observed as well (Figure 58, red).

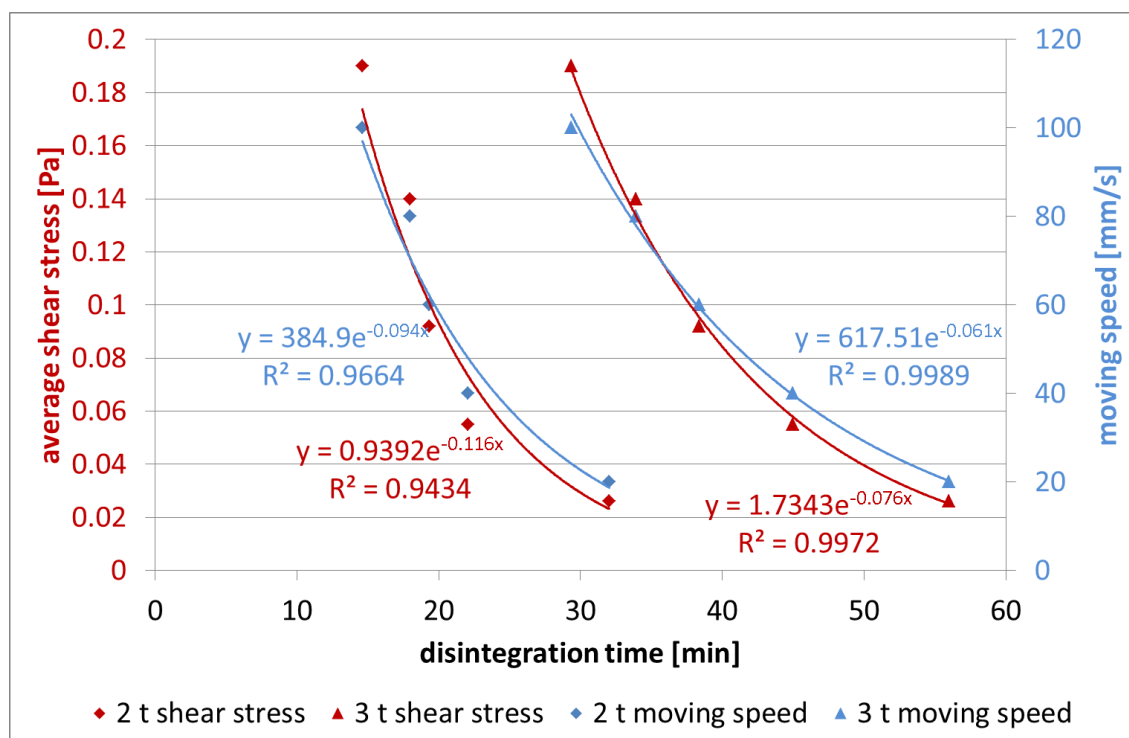


Figure 58: Correlation between disintegration time in SGF and moving speed and disintegration time and average shear stress. Disintegration times were measured using the modified disintegration device with the modified basket at different moving speeds. Disintegration times were correlated to the corresponding moving velocity and the CFD predicted average shear stress at the corresponding moving velocity.

The effect of moving speed and medium viscosity on disintegration time was also examined for commercial available lactose calibrator tablets. The results were compared to the immediate release tablets compressed at 4 t (corresponding to a hardness of 212 N) since both formulations exhibit similar hardness (Figure 59). The comparison shows that the effects of moving speed and medium viscosity are formulation dependent. While the immediate release tablets are sensitive to both moving speed and medium viscosity, the calibrator tablets are not sensitive to moving speed but medium viscosity. The ratio of fed to fasted disintegration time is 1.5 and 1.7 at 40 mm/s and 80 mm/s, respectively and similar to that calculated for the immediate release tablets (1.7 and 2.2 for 40 and 80 mm/s, respectively).

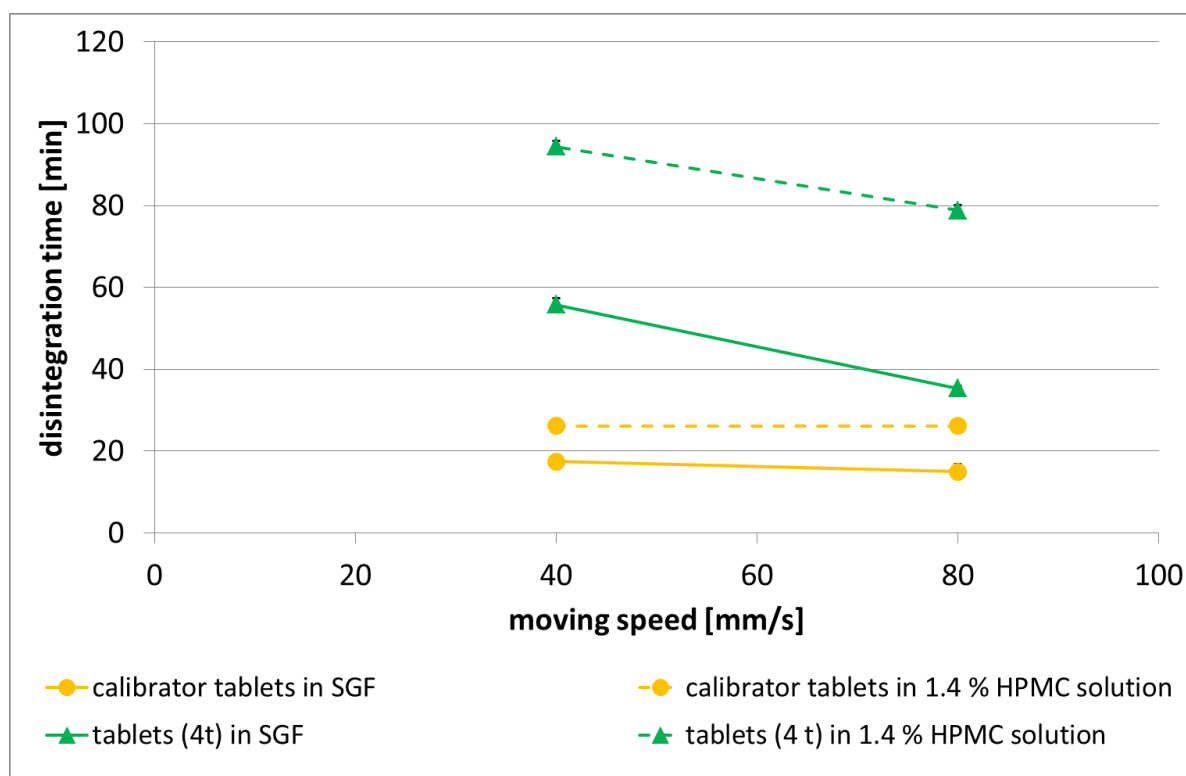


Figure 59: Comparison of the influence of moving speed and medium viscosity on disintegration time between manufactured immediate release tablets (green) and marked calibrator tablets (yellow) (mean $\pm$ SD, n=3). Disintegration times were measured using the modified disintegration test device with the compendial basket at 40 and 80 mm/s moving velocity in SGF (solid lines) and in 1.4 % HPMC solution (dashed lines).

The influence of applied pressure on disintegration time was investigated using the modified basket design equipped with the balloons (described in 3.1 and 4.2) to simulate the contraction of the stomach wall. Tablets compressed at 2 and 4 t (corresponding to a hardness of 106 and 212 N) were investigated. Figure 60 shows the results in SGF and 1.4 % HPMC solution at moving speeds of 40 mm/s (b) and 80 mm/s (a). In SGF the inflation of the balloons every 10 s has negligible influence on the disintegration time for both moving speeds. In 1.4 % HPMC solution the inflation of the balloons results in an increase in disintegration time. It was visually observed, that the tablet was not touched by the balloon. In contrast, by inflation of the balloons the tablet was pushed downwards the bottom due to the squeezing out of the fluid between the balloons and arising downward directed fluid flow. Hence, the observed influence on disintegration time was not due to applied pressure but to changed hydrodynamic conditions.

To prove this observation, a small bench was constructed of mesh material and inserted to the bottom of each probe chamber. Thereby, the tablet cannot escape the impact of the balloons. As expected, a decrease in disintegration time was measured. With this setup high local force are acting on the tablet due to the balloons contacting the tablet and pressing it at the mesh.

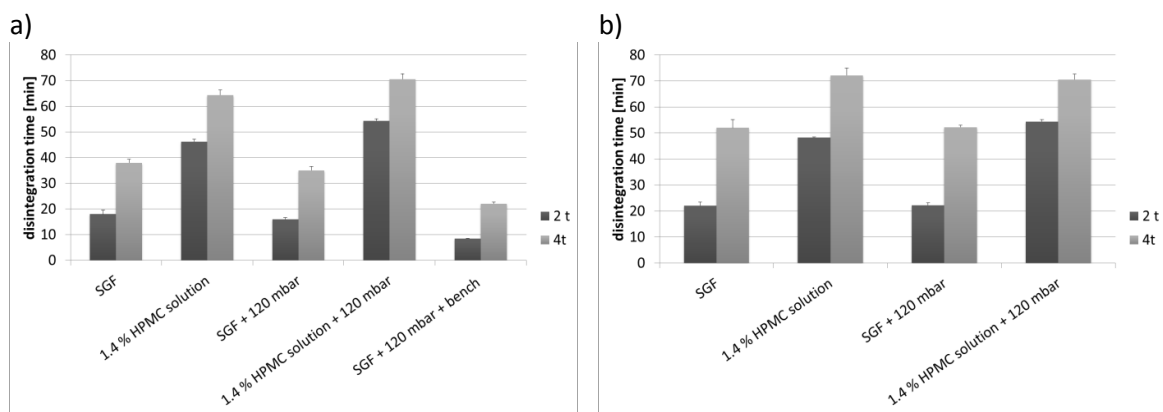


Figure 60: Influence of applied pressure on disintegration time in SGF and 1.4 % HPMC (mean $\pm$ SD, n=3). Disintegration times of tablets compressed at 2 and 4 t were investigated using the modified disintegration test device operating at a) 80 mm/s moving speed, and b) 40 mm/s moving speed.

## 4.6 Development and *in vitro* characterization of a gastroretentive drug delivery system

This chapter describes the development and *in vitro* characterization of a gastroretentive drug delivery system (GRDDS). The approach of an *in situ* polyelectrolyte complex was evaluated for applicability. The matrices were investigated in terms of complex formation (FT-IR), density, degree of swelling, mechanical stability, and drug release.

### 4.6.1 FT-IR measurements

The polyelectrolyte complex is formed by electrostatic interaction between the deprotonated  $\text{SO}_3^-$  groups of carrageenan and the protonated  $\text{NH}_3^+$  groups of chitosan as soon as they are exposed to the test medium or the stomach content. This electrostatic interaction was confirmed by FT-IR spectroscopy. Figure 61 shows exemplarily the obtained FT-IR spectra of chitosan 80/1000, carrageenan 379, the freeze dried complex, and trospium chloride. The spectrum of the complex was obtained after 24 h dissolution testing and subsequent freeze drying of the remaining complex (see material and methods 3.5.2.2). The spectrum of chitosan exhibits the characteristic bands at  $1651\text{ cm}^{-1}$  and  $1589\text{ cm}^{-1}$  which are assigned to amide I (free primary amino group) and amide II (acetylated amino group), respectively (Tapia et al., 2004; Grenha et al., 2010; Araujo et al., 2014). The spectrum of carrageenan shows several characteristic peaks, of which the one at  $1219\text{ cm}^{-1}$  is of particular interest representing the sulfate group (Araujo et al., 2014; Grenha et al., 2010). The peaks at  $926\text{ cm}^{-1}$  and  $848\text{ cm}^{-1}$  are typical for the 3,6-anhydrogalactose unit and the galactose-4-sulfate unit, respectively (Grenha et al., 2010). The disappearance of the characteristic peaks of the primary amide group of chitosan at  $1651\text{ cm}^{-1}$  and the sulfate group of carrageenan at  $1219\text{ cm}^{-1}$  in the spectrum of the freeze dried complex proofs the ionic interaction between the two polymers. Additionally, a new peak arises at  $1512\text{ cm}^{-1}$  further proofing the interaction. The peaks of the 3,6-anhydrogalactose unit and the galactose-4-sulfate unit are conserved in the spectrum of the complex. All three spectra show the characteristic absorption band for the glycosidic link at  $1026\text{ cm}^{-1}$ . None of the peaks characteristic for trospium chloride is observed in the freeze dries complex, indicating that all drug has been released.

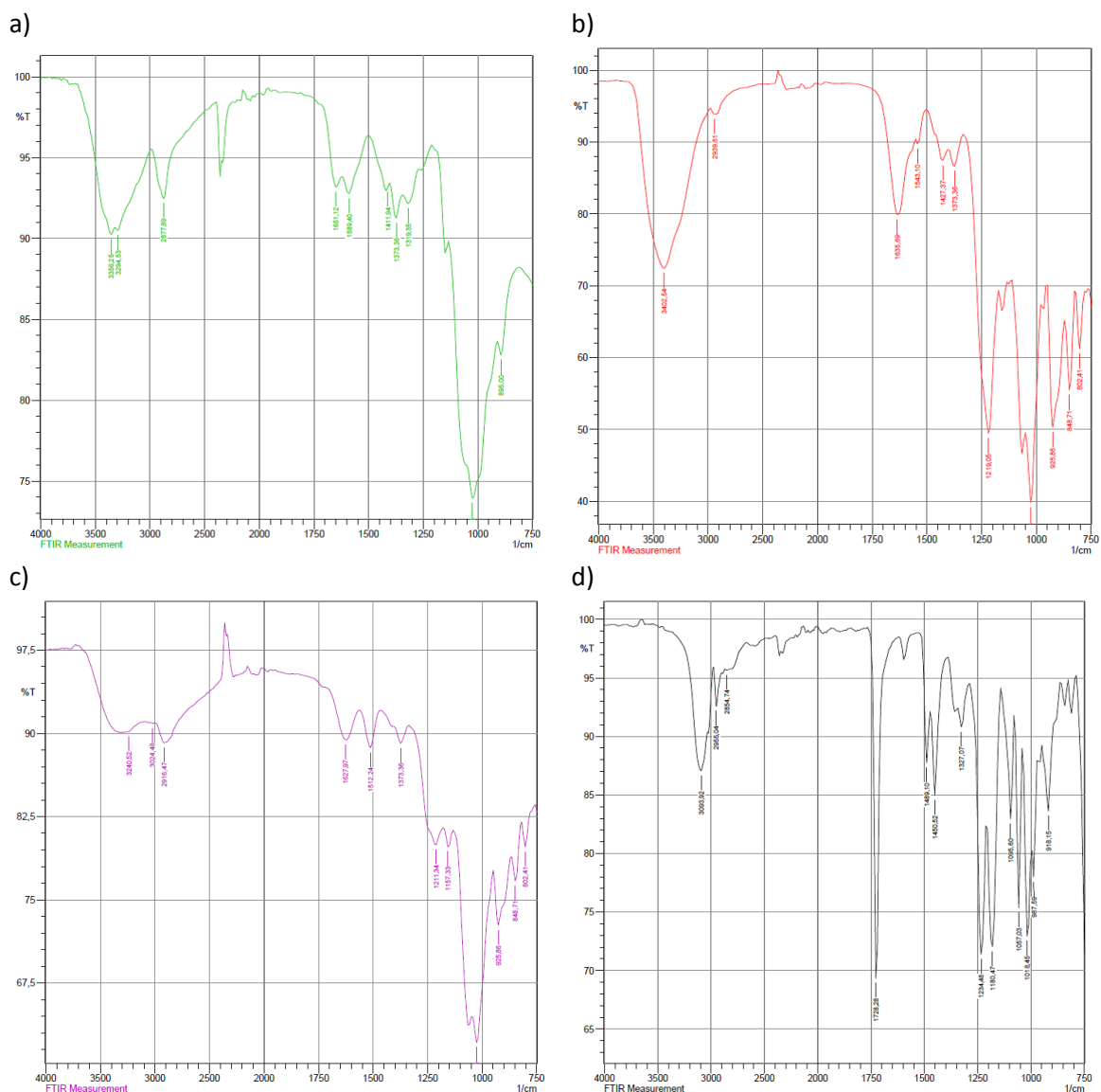


Figure 61: FT-IR spectra of a) chitosan 80/1000, b) carrageenan 379, c) freeze dried complex, and d) tropism chloride.

#### 4.6.2 Density

The ability of a gastroretentive delivery system to float on the gastric contents is determined by its density. While systems with a density  $< 1 \text{ g/cm}^3$  are supposed to float, densities of approximately  $2.5 \text{ g/cm}^3$  are necessary to sink down to the antrum (Bardonnet et al., 2006). The calculated densities after immersion in SGF for 0.5 and 8 h are summarized in Table 17.

Table 17: Densities (mean $\pm$ SD, n=3) of the complexes after immersion in SGF for 0.5 and 8 h.

Polyelectrolytes	Ratio	Density [g/cm <sup>3</sup> ] 0.5 h	Density [g/cm <sup>3</sup> ] 8 h
80/1000:379	1:8	0.89 $\pm$ 0.02	0.75 $\pm$ 0.21
80/1000:379	1:1	0.69 $\pm$ 0.08	0.71 $\pm$ 0.09
80/500:379	1:8	0.90 $\pm$ 0.47	0.98 $\pm$ 0.08
80/500:379	1:1	0.56 $\pm$ 0.11	0.74 $\pm$ 0.20
95/500:379	1:8	0.97 $\pm$ 0.16	0.90 $\pm$ 0.00
95/500:379	1:1	0.83 $\pm$ 0.31	0.60 $\pm$ 0.05
80/1000:209	1:1	0.53 $\pm$ 0.01	0.65 $\pm$ 0.10
80/500:209	1:1	0.54 $\pm$ 0.20	0.72 $\pm$ 0.20
95/500:209	1:1	0.75 $\pm$ 0.03	0.60 $\pm$ 0.05

When placing the capsules in the beaker immediate floating of all systems was observed. This observation is proofed by the calculated densities after 0.5 h immersion in SGF which range from 0.53 to 0.97 g/cm<sup>3</sup> indicating the ability of all systems to float on gastric contents immediately after being exposed to it. Even after 8 h of immersion in SGF, all systems maintain their floating ability indicated by the densities, which are below 1 g/cm<sup>3</sup> for all systems. Comparing complexes of chitosan and the iota-carrageenan 379 at different ratios (1:1 and 1:8), the densities are lower when mixing the polymers in the ratio 1:1.

#### 4.6.3 Matrix swelling

Sufficient swelling of the matrix is important to prevent the systems from being emptied from the stomach. It is generally accepted that objects >15 mm in diameter are retained in the stomach (Bardonnnet et al., 2006).

The maximum degree of swelling for the various formulations is shown in Figure 62. When testing capsules containing chitosan only, no matrix formation was observed and the chitosan dissolved immediately after the shell was dissolved due to the protonation of the amino groups. For capsules containing carrageenan only, matrix formation was observed. The maximum degree of swelling was low reaching 153 % and 324 % for lambda (209)-and iota (379)-carrageenan, respectively. Using both oppositely charged polyelectrolytes leads to much higher degrees of swelling. Highest maximum degrees of swelling in the range of 1554 % and 1718 % are observed in acetate buffer pH 4.5 for the formulations 80/1000:209 1:1 and 80/1000:379

1:8, respectively. In general, maximum matrix swelling is higher for formulations containing the iota-carrageenan 379 as anionic polyelectrolyte compared to the lambda-carrageenan 209.

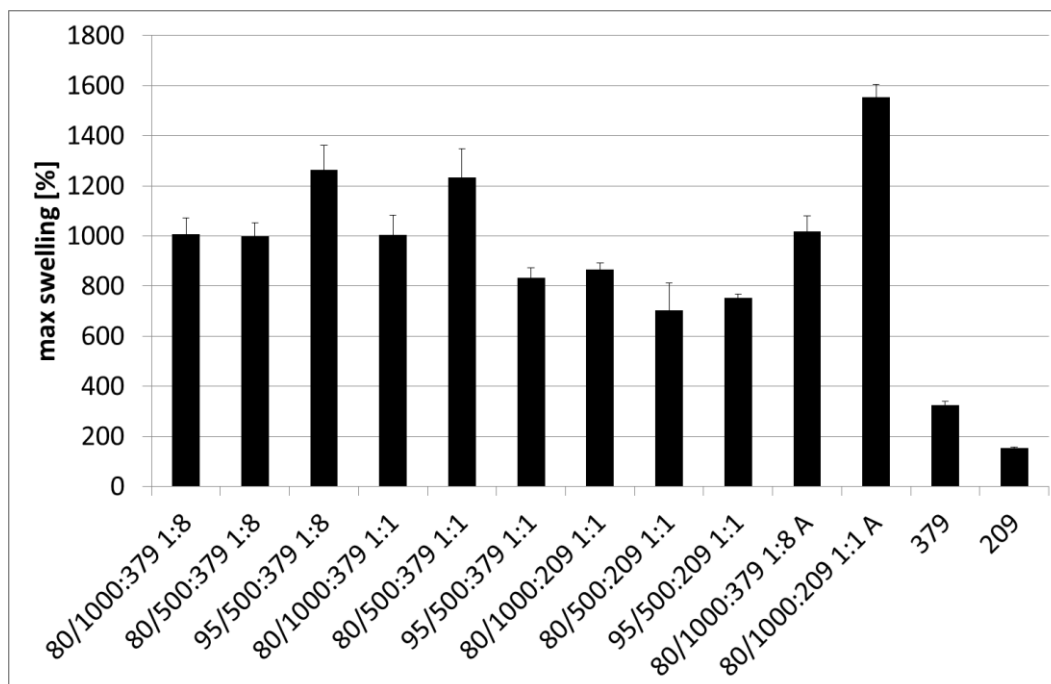


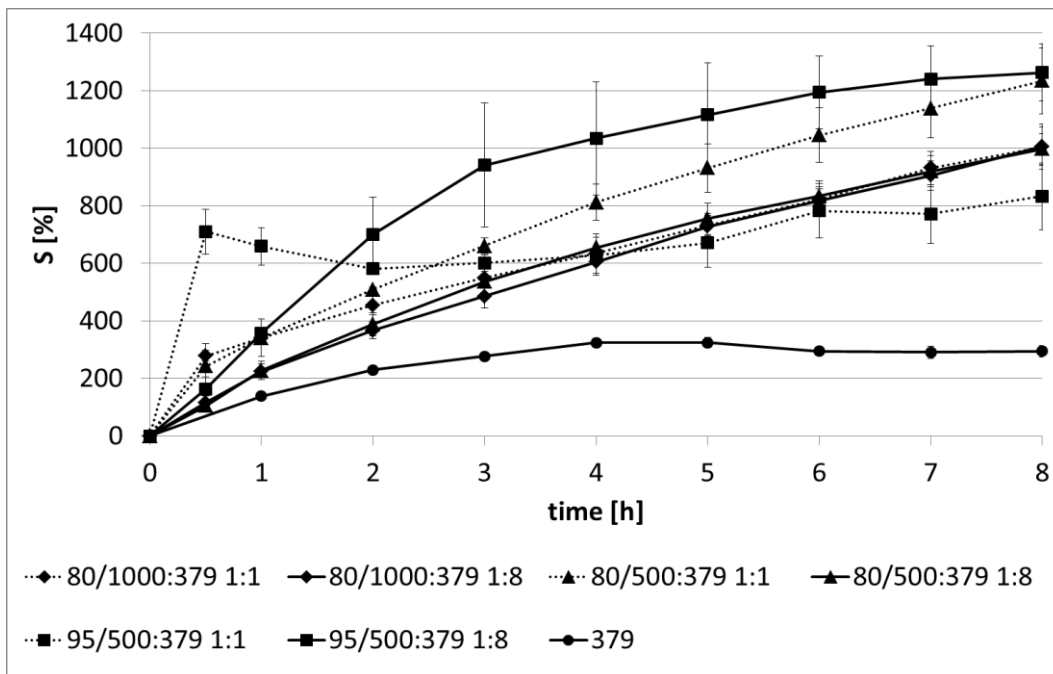
Figure 62: Maximum degree of swelling (mean $\pm$ SD, n=3) for all formulations in SGF and for formulations 80/1000:379 1:8 and 80/1000:209 1:1 in acetate buffer pH 4.5 (indicated by A).

The degree of swelling in SGF as a function of time for various formulations containing different types of chitosan and carrageenan is shown in Figure 63. Capsules prepared from carrageenan only showed a slight increase in weight after 1h. The matrices composed of the lambda-carrageenan 209 disintegrated rapidly during 3 h. In contrast, the matrices from the iota-carrageenan 379 swelled to 324% in the first 4 h of the experiment and maintained this weight for the last 4 h of the experiment. However, matrices composed of both oppositely charged polymers swelled to an even greater extent. Furthermore, swelling continued for the whole duration of the experiment and did not reach equilibrium as observed for the iota-carrageenan 379.

Figure 63 clearly shows that the degree of swelling is strongly dependent on the properties of the polyelectrolytes as well as on their ratio. All formulations containing chitosan: iota-carrageenan 379 in the ratio 1:1 show an initial burst in swelling followed by a decrease in swelling rate (Figure 63 a). When using the polymers in the ratio 1:8 this initial burst is not observed. Formulation 95/500:379 1:1 shows an extraordinary high initial swelling in the first 30 min followed by a decrease in degree of swelling. After 5 h the degree is slightly rising reaching a saturation at 6 h for the rest of the experiment. For the two other formulations of ratio 1:1 (80/1000:379 and 80/500:379) neither decrease nor saturation of swelling is observed.

Swelling increases continuously during the whole experiment. While formulations 80/1000:379 1:8 and 80/500:379 1:8 exhibit nearly the same swelling behavior, formulation 95/500:379 1:8 shows a much higher degree of swelling.

a)



b)

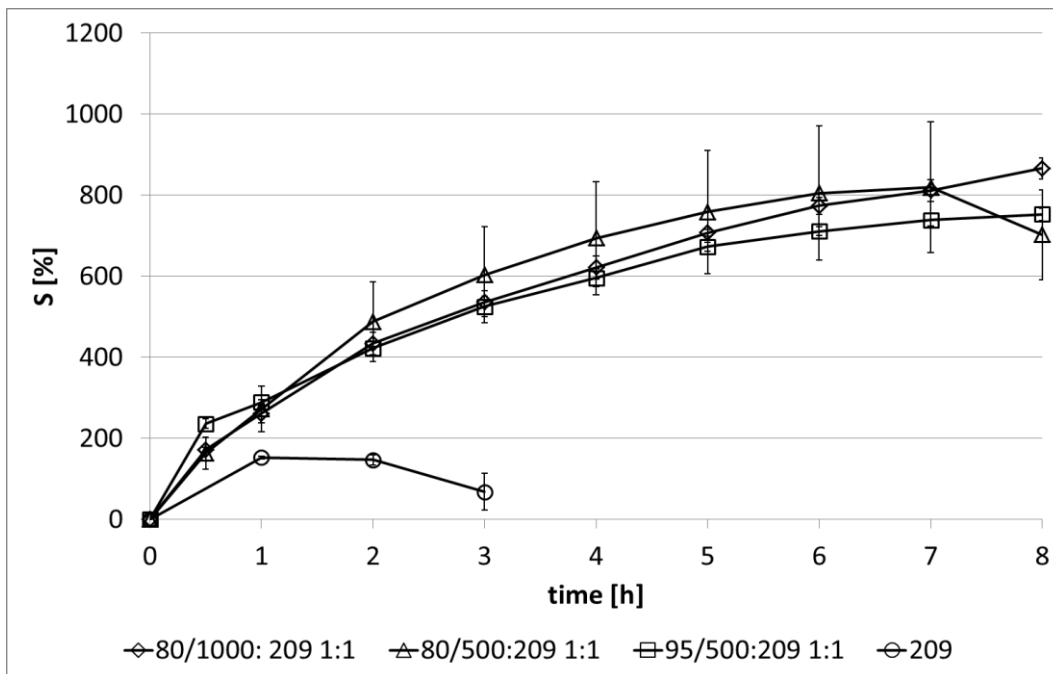


Figure 63: Degree of swelling (mean±SD, n=3). a) Effect of polymer ratio on degree of swelling in SGF for formulations containing chitosan and iota carrageenan, b) Degree of swelling in SGF for formulations containing chitosan and lambda-carrageenan.

Comparing the swelling of the matrices containing iota (379)-or lambda (209)-carrageenan, the degree of swelling is lower for formulations containing the lambda-carrageenan 209. This difference could be associated to their different amount of charged sulfate groups per monomer unit, which is higher for the lambda-carrageenan 209 compared to the iota-carrageenan 379. The amount of charged anionic and cationic groups governs the interaction between the polymers and the resulting properties of the matrix.

As the pH of the stomach can vary between 1 and 6 during the day, depending on the prandial state (Kalantzi et al., 2006), the influence of pH on the degree of swelling was examined in SGF (pH 1.2) and acetate buffer (pH 4.5) (Figure 64). For the formulation 80/1000:379 1:8 no pH dependence was observed. In contrast, the formulation with the lambda carrageenan 80/1000:209 1:1 shows large pH dependence. In acetate buffer this matrix swelled to a greater extent reaching 1554 % compared to 866 % in SGF.

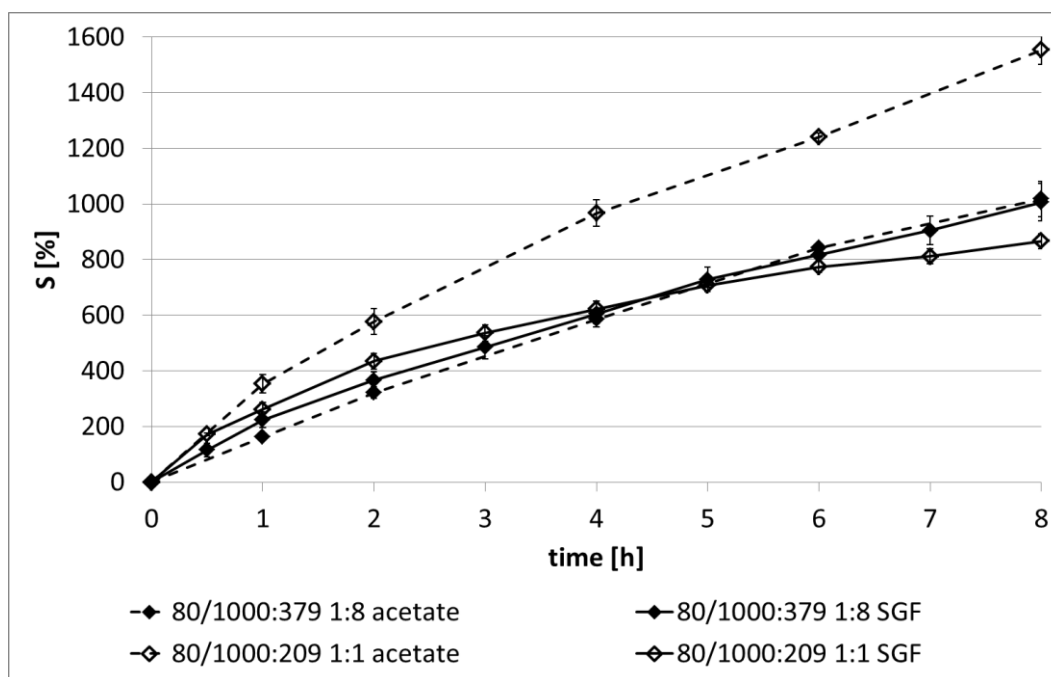


Figure 64: Effect of pH of medium on degree of swelling for formulations 80/1000:379 1:8 and 80/1000:209 1:1 (mean $\pm$ SD, n=3).

#### 4.6.4 Effect of hydrodynamics on degree of swelling

The influence of hydrodynamic stresses on the swelling of the matrices plays an important role. It is essential that the complexes withstand hydrodynamic forces to prevent breakage and emptying from the stomach associated with loss of gastroretention as well as loss of control of release. To investigate the systems ability to withstand hydrodynamic stress the degree of swelling was determined utilizing the PhEur disintegration test. The swelling profiles obtained using the disintegration device were compared to those obtained using the softly agitated beaker (Figure 65) (see section 3.5.2.4 and 3.5.2.5 for method description). While the tablets experience considerable hydrodynamic stress during the test using the disintegration test device, the softly agitated beaker represents an almost stress-free method.

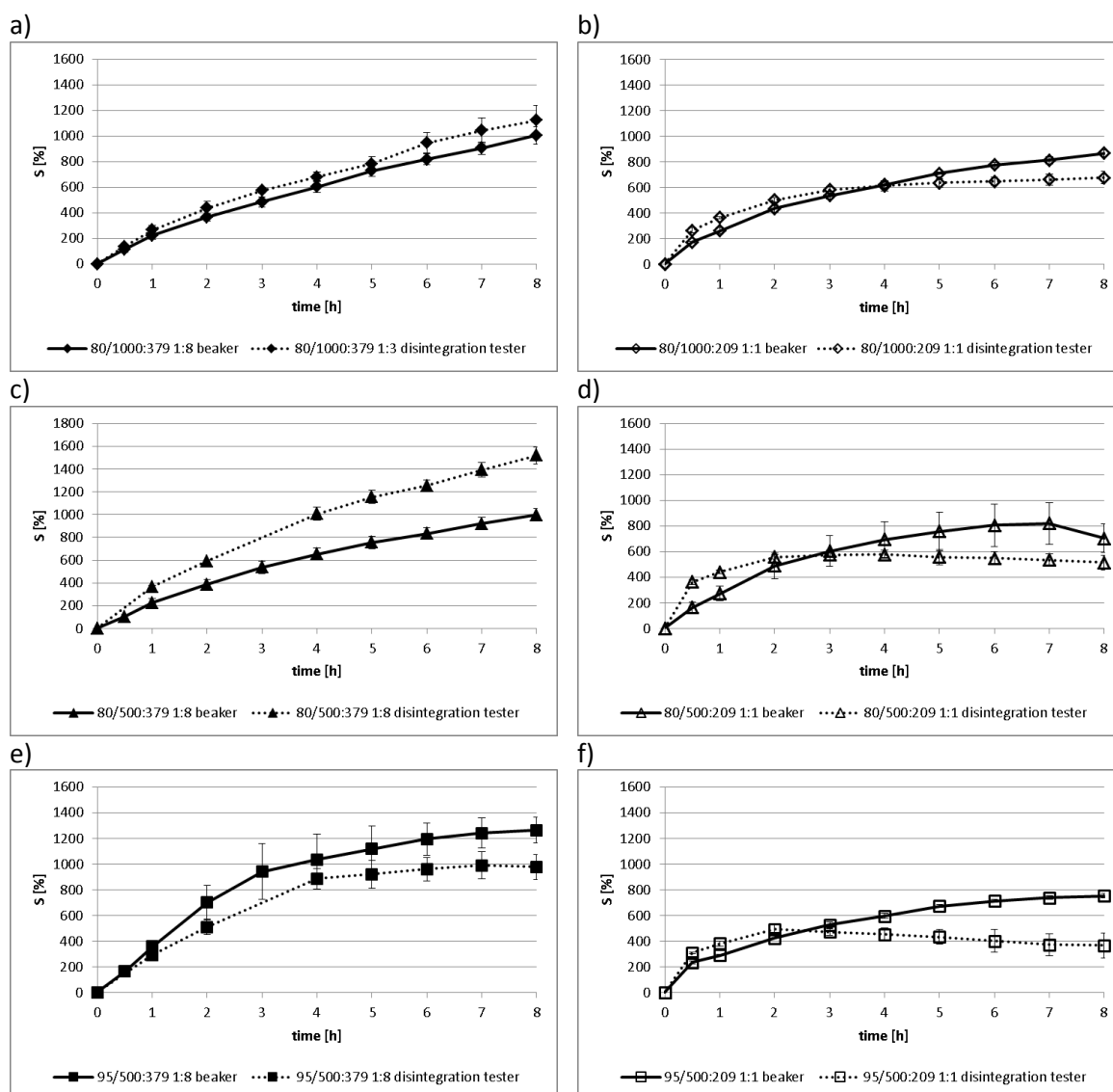


Figure 65: Effect of hydrodynamics on degree of swelling in SGF (mean $\pm$ SD, n=3). The degree of swelling was determined utilizing the softly agitated beaker (solid lines) and the disintegration tester (dashed lines). While the softly agitated beaker represents a test method without hydrodynamic stress, the tablet experiences considerable hydrodynamic stress in the PhEur disintegration test device.

While for formulations 80/1000:379 1:8 and 80/1000:209 1:1 hydrodynamic forces do not change the ability to swell (Figure 65 a) and b), they play an important role for the other formulations (Figure 65 c), d), e), f). Whereas the formulation of the iota-carrageenan 379 with chitosan 80/500 shows increased swelling under higher hydrodynamic forces, the formulation with chitosan 95/500 shows decreased swelling. The formulations with the lambda-carrageenan 209 exhibit a higher degree of the swelling under higher hydrodynamics during the first three hours followed by a decrease of swelling indicating erosion of the matrix. While formulation 95/500:379 1:8 shows the highest degree of swelling under low hydrodynamic stress (1263 %), formulation 80/500:379 1:8 exhibits the highest degree of swelling under high hydrodynamic stress reaching 1518 %. Formulation 95/500:209 1:1 shows the lowest ability to swell under low and high hydrodynamic forces.

The pH dependence of the degree of swelling under hydrodynamic stress was examined in SGF (pH 1.2) and acetate buffer (pH 4.5) (Figure 66). As already observed for the degree of swelling without hydrodynamic stress, formulations with the lambda-carrageenan 209 exhibit high pH dependence while formulations with the iota-carrageenan 379 are only slightly influenced by pH variation. For formulation 80/1000:209 1:1 the degree of swelling dramatically increases with increasing pH.

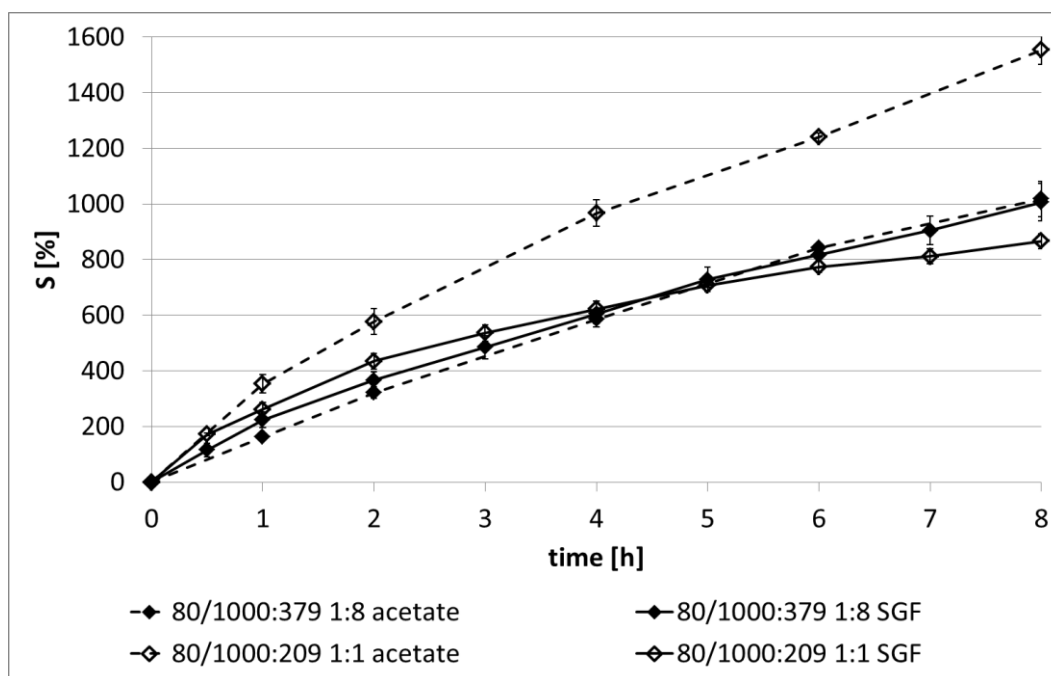


Figure 66: Effect of pH of the medium on degree of swelling for formulations 80/1000:379 1:8 and 80/1000:209 1:1 determined utilizing the PhEur disintegration test device (mean $\pm$ SD, n=3).

#### 4.6.5 Physicomechanical strength

To evaluate the physicomechanical strength of the complexes, they were exposed to an externally applied pressure utilizing the texture analyzer. Matrix resilience (MR), matrix hardness (MH), and deformation energy (DE) were evaluated from the force-time and force-distance profiles, respectively (see materials and methods 3.5.2.6). While MH represents the force required to deform a matrix, DE represents the energy required to withstand an external applied force (Ngwuluka et al., 2013). MR displays the ability of the matrix to recover its shape and size after being exposed to deformational force (Bawa et al., 2011). The measurement of these physicomechanical parameters is employed to estimate the matrices stability in the stomach and their ability to withstand the destructive forces present in the stomach. Furthermore, MH and MR refer to medium penetration into the matrices and drug release from the matrices. Figure 67 shows exemplarily the force-distance (a) and force-time (b) profiles of formulation 80/1000:379 after 2, 4, 6, and 8h immersion in SGF.

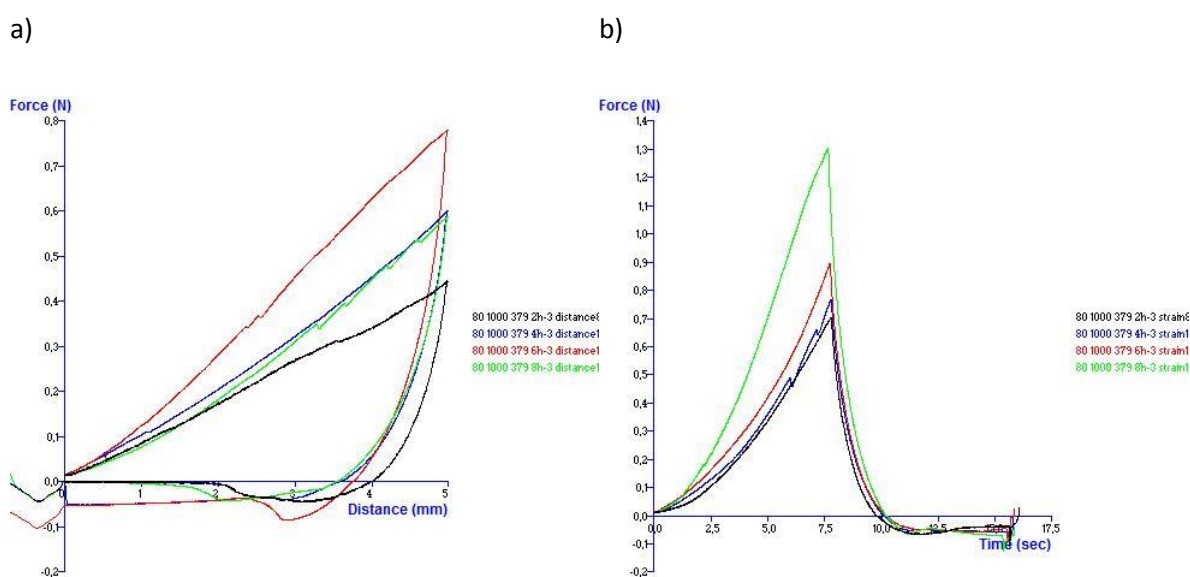


Figure 67: Typical a) force-distance and b) force-time profile after 2, 4, 6, and 8 h immersion in SGF. Exemplarily shown for formulation 80:1000:379 1:8.

Table 18 summarizes the calculated values for MR, MH, and DE. Extraordinary high values for MH and DE are reached for the formulation of chitosan 95/500 and carrageenan 209 in the range of 0.21 to 0.96 N/mm and 1.73 to 4.86 N\*mm for MH and DE, respectively. High forces are required to deform the matrix. These high values indicate a very dense packing with few voids resulting in slow medium penetration and drug release. All other formulations show similar matrix hardness and deformation energies in the range of 0.08 to 0.25 N/mm and 1.06 to 2.25 Nmm, respectively. Although the formulation 95/500:209 1:1 shows this high values for

MH and DE it exhibits with 10-13 % the lowest values for MR compared to the other formulations indicating a very poor ability of the matrix to recover its size and dimensions after exposure to external force. All formulations containing carrageenan 209 as anionic polymer exhibit lower values of MR compared to those containing carrageenan 379. In general, higher values of MR are found during the first 4 hours of the experiment. Afterwards the MR starts to decrease. Formulation 80/500:379 1:8 exhibits the highest MR at 6 hours reaching 27 %.

Table 18: Texture analysis results (mean $\pm$ SD, n=3). MH was calculated from the force distance profile and represents the force required to deform the matrix. De was also calculated from the force-distance profile and represents the energy required to withstand an external applied force. MR was calculated from the force-time profile and represents the ability of a matrix to recover its shape after being exposed to deformational force.

Formulation	t [h]	MR [%]	MH [N/mm]	DE [N*mm]
80/1000:379 1:8	2	17.96 $\pm$ 3.33	0.11 $\pm$ 0.03	1.60 $\pm$ 0.47
	4	22.04 $\pm$ 3.63	0.10 $\pm$ 0.02	1.21 $\pm$ 0.22
	6	22.04 $\pm$ 4.23	0.12 $\pm$ 0.03	1.41 $\pm$ 0.45
	8	20.63 $\pm$ 4.56	0.10 $\pm$ 0.02	1.28 $\pm$ 0.18
80/1000:209 1:1	2	14.00 $\pm$ 0.72	0.17 $\pm$ 0.04	1.83 $\pm$ 0.47
	4	16.52 $\pm$ 1.87	0.13 $\pm$ 0.02	1.18 $\pm$ 0.17
	6	14.55 $\pm$ 1.86	0.18 $\pm$ 0.05	1.77 $\pm$ 0.63
	8	12.82 $\pm$ 1.53	0.16 $\pm$ 0.08	1.37 $\pm$ 0.70
80/500:379 1:8	2	17.15 $\pm$ 0.91	0.19 $\pm$ 0.05	2.16 $\pm$ 0.33
	4	26.48 $\pm$ 4.26	0.15 $\pm$ 0.06	2.24 $\pm$ 1.00
	6	27.23 $\pm$ 0.97	0.15 $\pm$ 0.04	1.88 $\pm$ 0.54
	8	22.98 $\pm$ 2.14	0.08 $\pm$ 0.04	1.06 $\pm$ 0.61
80/500:209 1:1	2	16.09 $\pm$ 0.89	0.19 $\pm$ 0.06	1.88 $\pm$ 0.51
	4	18.52 $\pm$ 1.75	0.18 $\pm$ 0.03	1.59 $\pm$ 0.26
	6	16.63 $\pm$ 1.54	0.24 $\pm$ 0.04	2.25 $\pm$ 0.53
	8	14.39 $\pm$ 2.53	0.25 $\pm$ 0.08	2.09 $\pm$ 0.67
95/500:379 1:8	2	23.49 $\pm$ 9.43	0.15 $\pm$ 0.03	1.58 $\pm$ 0.54
	4	24.58 $\pm$ 10.77	0.18 $\pm$ 0.03	2.25 $\pm$ 0.16
	6	26.88 $\pm$ 4.86	0.14 $\pm$ 0.02	1.83 $\pm$ 0.50
	8	16.40 $\pm$ 4.14	0.15 $\pm$ 0.02	1.97 $\pm$ 0.96
95/500:209 1:1	2	13.39 $\pm$ 1.39	0.21 $\pm$ 0.08	1.73 $\pm$ 0.76
	4	11.17 $\pm$ 4.01	0.41 $\pm$ 0.04	3.30 $\pm$ 0.51
	6	10.31 $\pm$ 1.58	0.96 $\pm$ 0.80	4.86 $\pm$ 2.59
	8	9.76 $\pm$ 0.47	0.69 $\pm$ 0.29	2.89 $\pm$ 0.61

#### 4.6.6 *In vitro* drug release from polyelectrolyte complexes

The *in vitro* release of trospium from various matrices differing in composition and ratio was investigated in SGF using USP apparatus II operating at 50 rpm (Figure 68). Additionally, release testing was performed in acetate buffer (pH 4.5) for selected formulations (Figure 69).

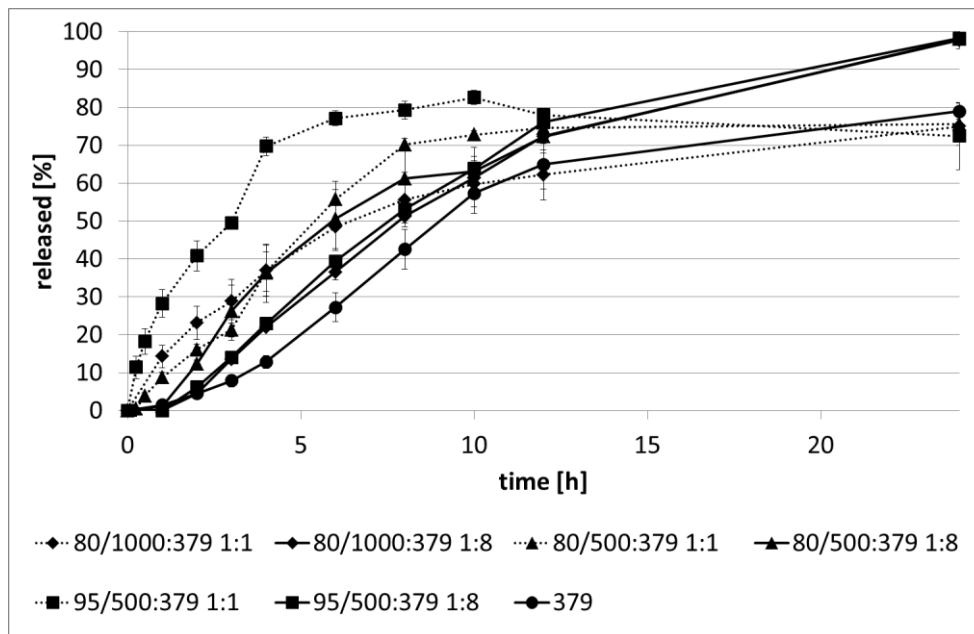
As already observed for the degree of swelling, the release of trospium is strongly dependent on the polymer properties as well as on their mixing ratio (Figure 68). While the release from formulations of chitosan and iota-carrageenan 379 at the ratio 1:1 follows a 1<sup>st</sup> order kinetic, the profiles of formulations at the ratio 1:8 are described by a sigmoidal curve indicating a lag time before onset of dissolution of the drug (Figure 68 a). Furthermore, release from matrices at the ratio of 1:1 is incomplete after 24 h reaching approximately 75 %. In contrast, release from formulations at the ratio 1:8 is complete after 24 h. For comparison purpose the release profile from a matrix comprised of iota-carrageenan 379 only is also shown. Compared to the profiles from the polyelectrolyte matrices the release from iota-carrageenan 379 is retarded. Nevertheless, this matrix is not suitable for gastroretentive drug delivery due to its low swelling and insufficient stability. Release from matrices containing chitosan only was rapid and complete release was reached after approximately 4 h (data not shown). The same is true for matrices of lambda-carrageenan 209.

The release from matrices of chitosan and lambda-carrageenan 209 at the ratio 1:1 is incomplete after 24 h with only about 60 % trospium released (Figure 68 b). No further release is observed when measurement is extended to 48 h (data not shown). The release pattern from matrices of chitosan and lambda-carrageenan 209 is linear up to 10 h followed by a decrease in release rate.

Table 19 lists the results of the fitting of the dissolution data to different kinetic models. None of the curves fits to the Higuchi model. As Higuchi describes the drug dissolution as a diffusion process based on Fick's law, the low  $R^2$  indicate a dissolution process that is not governed by diffusion. A better fit for most formulations is achieved by using the Hixson-Crowell model, which can be applied to formulations where drug release is governed by diminishing of the dosage form surface indicating an erosion controlled release mechanism. To better understand the release mechanism the dissolution data were fitted to Korsmeyer-Peppas model where the release exponent  $n$  indicates the mechanism of drug transport. For all formulations containing iota-carrageenan 379  $n > 0.89$  indicating super case II transport that refers to erosion of the polymeric chains. Calculated  $n$  values for all formulations containing lambda-carrageenan 209,

except 95/500:209 1:1, are in the range of  $0.45 < n < 0.89$  indicating anomalous transport that is release is controlled by both, diffusion and erosion. The release from formulation 95/500:209 1:1 is controlled by erosion only ( $n > 0.89$ ).

a)



b)

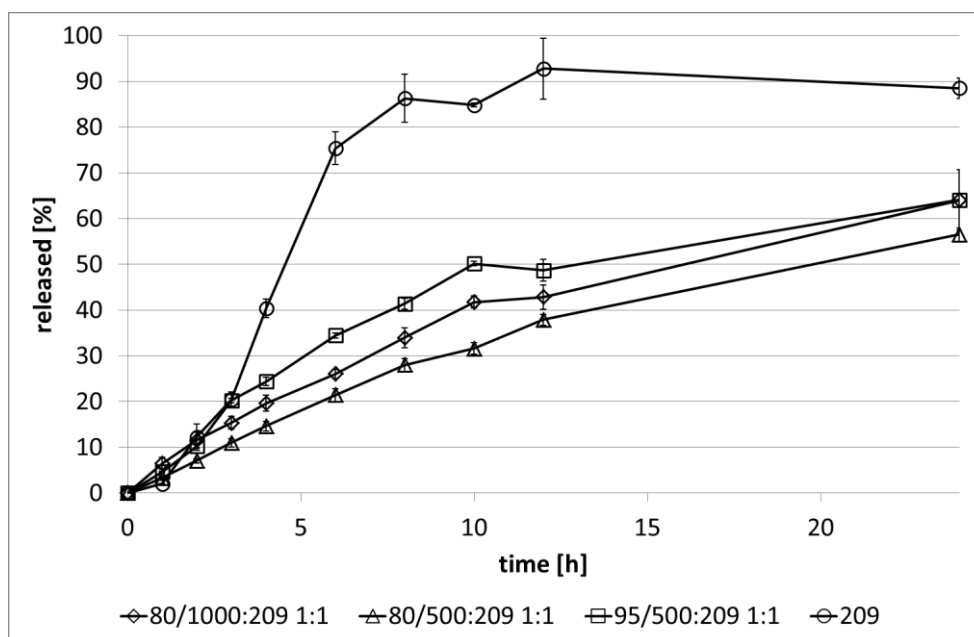


Figure 68: *In vitro* drug release profiles (mean  $\pm$  SD,  $n=3$ ). a) Effect of polymer ratio on the release of trospium in SGF for formulations containing chitosan and iota carrageenan 379, b) release of trospium from formulations containing chitosan and lambda-carrageenan 209.

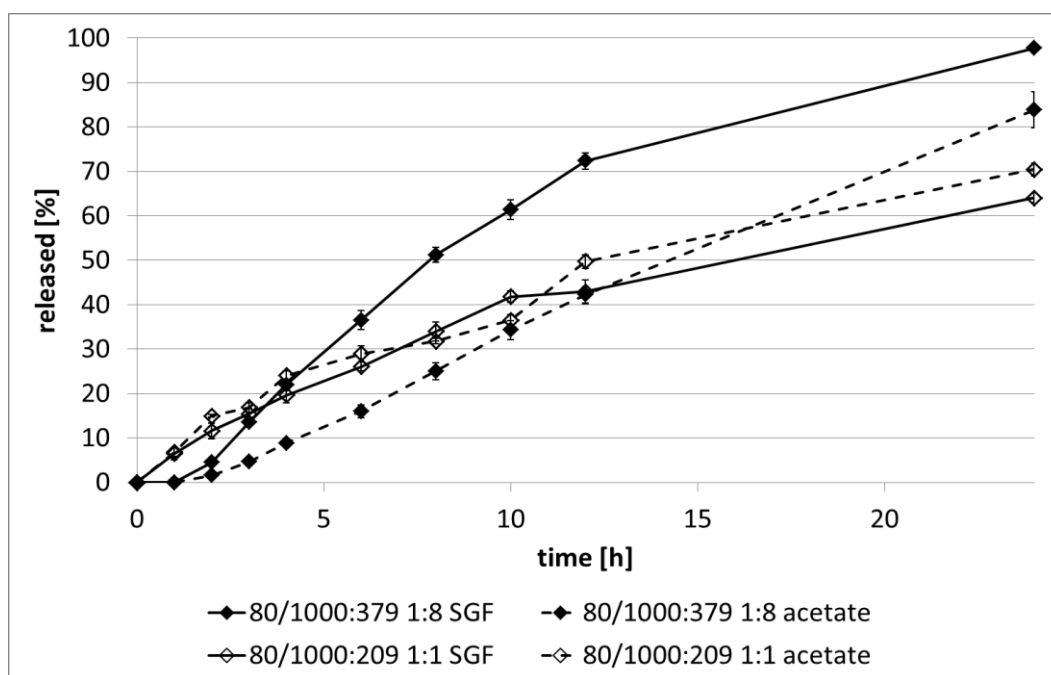


Figure 69: Release of trospium form formulations 80/1000:379 1:8 and 80/1000:209 1:1 in SGF (pH 1.2) and acetate buffer (pH 4.5) (mean±SD, n=3).

Figure 69 shows the effect of dissolution medium pH on release of trospium form two selected formulations. While for formulation 80/1000:209 1:1 no effect of pH on drug release is observed ( $f_2= 0.69$ ), the release profiles of formulation 80/1000:379 1:8 are not similar ( $f_2= 0.37$ ). At the higher pH the release from formulation 80/1000:379 1:8 is retarded compared to the release in SGF. After a lag time of 2 h the release at pH 4.5 is nearly linear. This observation is contrary to the results obtained for the pH dependence of the degree of swelling where formulation 80/1000:209 1:1 showed a pH dependency and formulation 80/1000:379 1:8 not.

Table 19: Fitting parameters of drug release data.

Formulation	zero		first		Higuchi		Korsmeyer-Peppas			Hixson-Crowell	
	$K_0$	$R^2$	$K_1$	$R^2$	$K_H$	$R^2$	$K_{KP}$	$n$	$R^2$	$K_{HC}$	$R^2$
80/1000:379 1:8	6.026	0.9785	0.094	0.9150	16.722	0.7794	1.710	1.7071	0.9519	0.027	0.9459
80/500:379 1:8	6.793	0.9338	0.107	0.9728	19.200	0.8843	1.751	2.1331	0.4133	0.030	0.9729
95/500:379 1:8	7.817	0.9362	0.143	0.9352	22.338	0.8473	3.031	1.7294	0.8751	0.038	0.9574
80/1000:209 1:1	4.048	0.9574	0.051	0.9888	11.501	0.9334	6.577	0.7794	0.9919	0.016	0.9818
80/500:209 1:1	3.295	0.9903	0.039	0.9981	9.227	0.8889	4.855	0.7528	0.9584	0.012	0.9973
95/500:209 1:1	4.833	0.9345	0.064	0.9795	13.734	0.9137	5.523	0.9669	0.9219	0.019	0.9703
80/1000:379 1:8 A	3.213	0.9460	0.039	0.9057	8.725	0.7032	0.721	1.6311	0.9758	0.012	0.9209
80/1000:209 1:1 A	4.206	0.9115	0.053	0.9506	12.037	0.9372	7.801	0.7199	0.9685	0.016	0.9405

## 4.7 Characterization of the gastroretentive drug delivery system under varying hydrodynamic conditions

For gastroretentive drug delivery systems it is very important that they withstand the hydrodynamic and mechanical forces to which they are exposed in the stomach. Thus controlled drug release is ensured and dose dumping is avoided. Therefore, the influence of different hydrodynamic conditions on the degree of swelling and drug release profile was examined utilizing the modified disintegration test device described in 3.1 and 4.2 operating with the compendial basket design. These investigations were performed with formulation 80/1000:379 1:8. This formulation is regarded as the optimized formulation in terms of degree of swelling, mechanical stability, and drug release based on the results of chapter 4.6.

### 4.7.1 Swelling behavior

The degree of swelling in SGF was measured using the softly agitated beaker method (3.5.2.4), the PhEur disintegration test device (3.5.2.5), and the modified disintegration test device operating at two different speeds (40 and 80 mm/s) and equipped with the compendial basket. The obtained swelling profiles were compared (Figure 70).

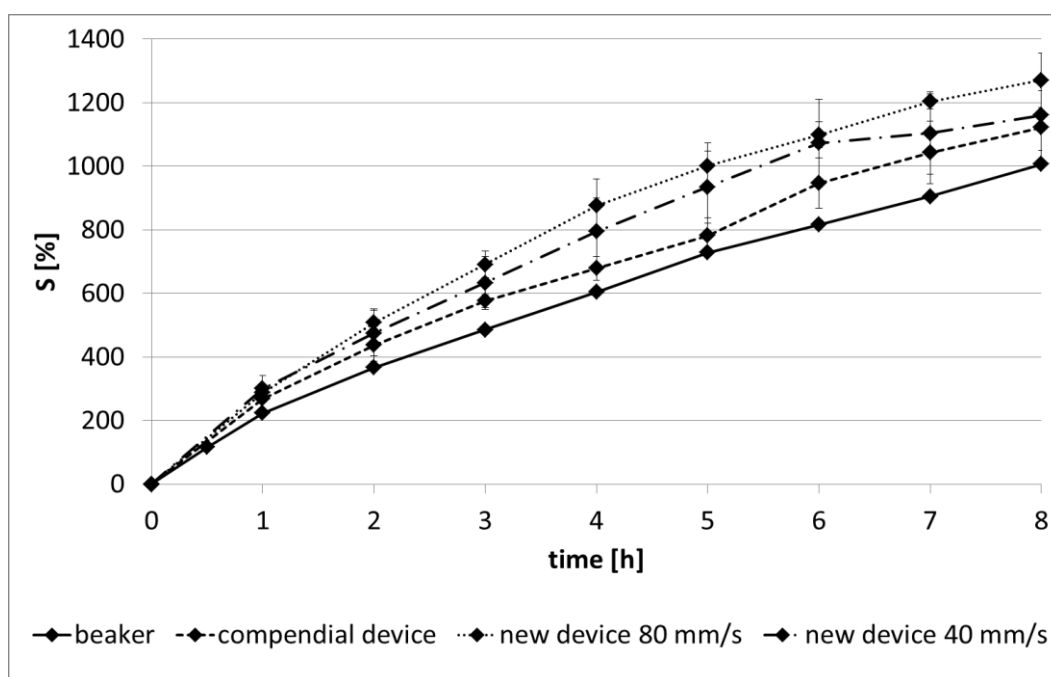


Figure 70: Swelling profiles of optimized gastroretentive formulation 80/1000:379 1:8 in SGF under varying hydrodynamic conditions (mean $\pm$ SD, n=3). The degree of swelling was investigated using the softly agitated beaker method, the PhEur disintegration test device, and the modified disintegration test device operating at 40 and 80 mm/s.

The degree of swelling is largely influenced by the hydrodynamic stress. In the softly agitated beaker the matrices experience nearly no hydrodynamic stress. Operating the modified disintegration at 80 mm/s the matrices are exposed to harsh hydrodynamic conditions. The higher the hydrodynamic stress the higher the degree of swelling. The degree of swelling is about 300 % higher at 80 mm/s compared to the degree of swelling in the softly agitated beaker.

#### 4.7.2 Drug release profile

The release profiles from the gastroretentive drug delivery system 80/1000:379 = 1:8 under varying hydrodynamic conditions are shown in Figure 71. The profile obtained using the USP paddle apparatus (50 rpm) is compared to the profiles obtained using the modified disintegration test device operating at 40 and 80 mm/s and equipped with the compendial basket.

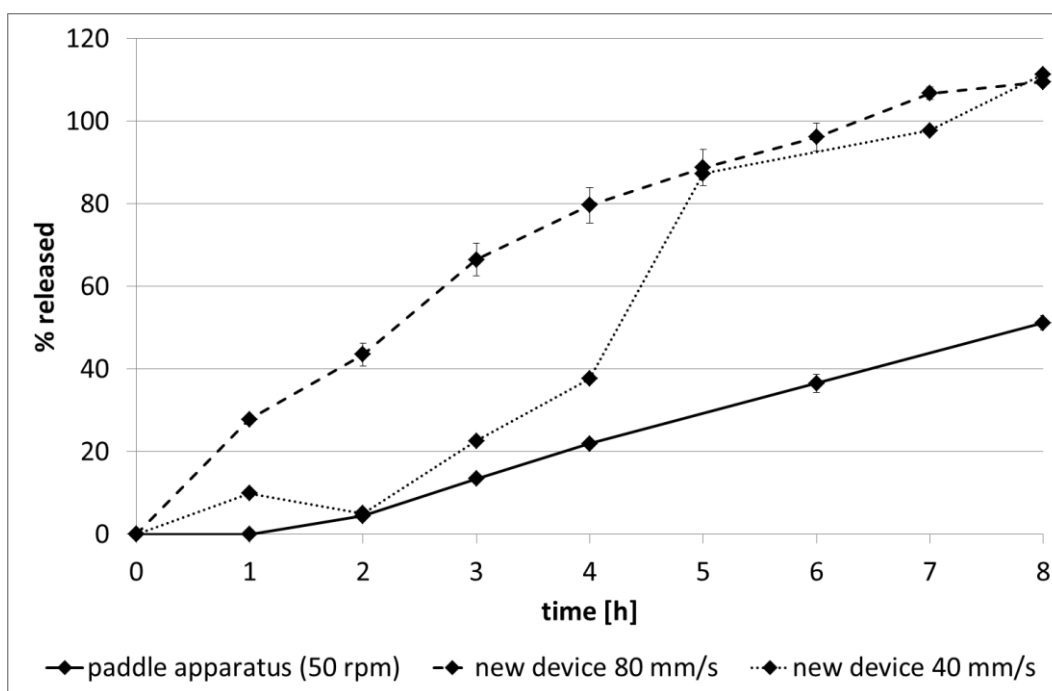


Figure 71: Release profiles of tropsium in SGF under varying hydrodynamic conditions obtained for the optimized gastroretentive formulation 80/1000:379 1:8 in SGF. Release was tested utilizing the USP paddle apparatus operating at 50 rpm (mean $\pm$ SD, n=3) and the modified disintegration tester operating at 40 and 80 mm/s (for 80 mm/s mean $\pm$ SD of three measurements with one capsule per trial is reported. Due to the low SD, three capsules per trial were measured at 40 mm/s and mean is reported).

The different hydrodynamic conditions significantly influence the drug release from the polyelectrolyte complex (Figure 71). All three release profiles are not similar ( $f_2 < 50$ ). Using the paddle apparatus, the system floats on top of the medium and rotates with the fluid. It experiences nearly no hydrodynamic stress and hence drug release is slow compared to the

release when tested in the disintegration device under considerable stress. Additionally, the moving velocity of the device influences drug release from the systems. By increasing the moving velocity the drug release is faster. At a moving speed of 80 mm/s no lag phase is observed.

#### 4.7.3 Correlation between drug release and degree of swelling

It is claimed that the degree of swelling determines the rate of drug release from swellable hydrophilic matrices (Colombo, 1993). This expectation was validated by correlating the degree of swelling at time  $t$  with the drug released at time  $t$  at 40 and 80 mm/s (Figure 72). A linear correlation was obtained for both moving speeds. However, the different slopes of the two correlations indicate that drug release is not only governed by the swelling. Initially, at low swelling, a higher percentage of drug is released at 80 mm/s compared to 40 mm/s. At higher moving speeds surface erosion is higher which might accelerate drug release. Secondly, fluid flow through the gel layer is higher at 80 mm/s, possibly liberating API from the polymeric network.

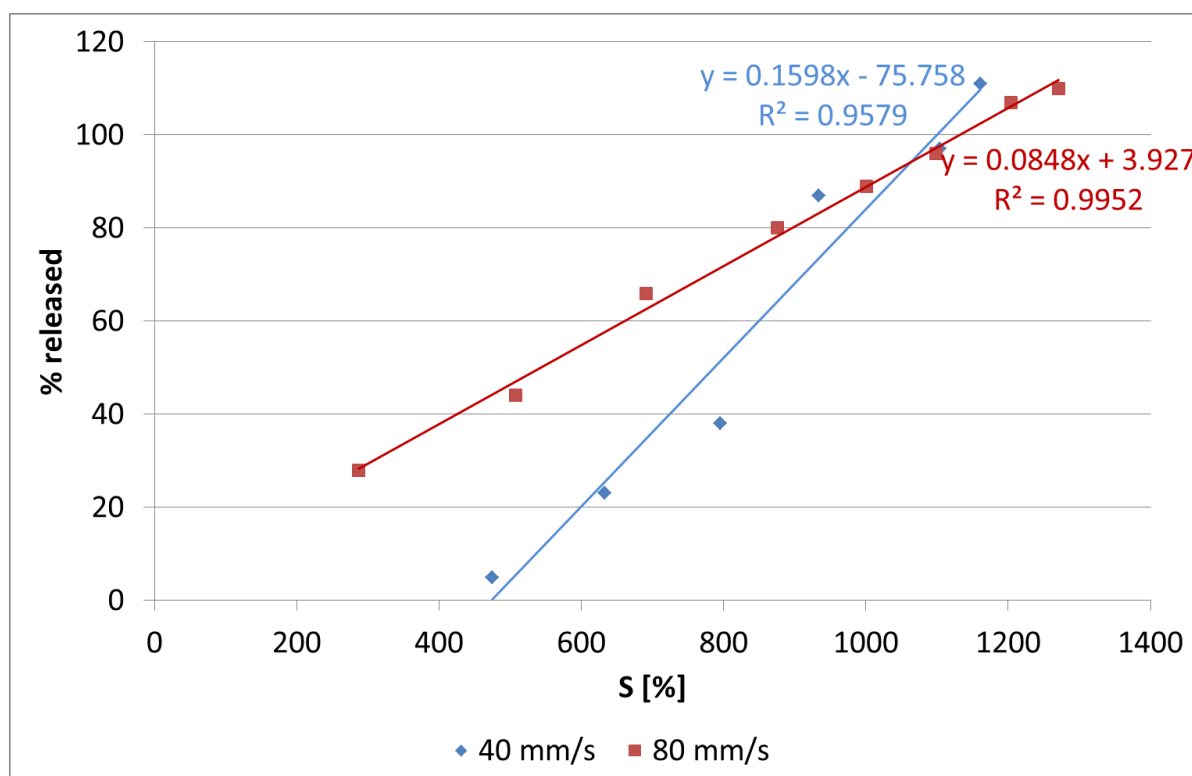


Figure 72: Correlation between drug release and degree of swelling at 40 and 80 mm/s in SGF for formulation 80/1000:379 1:8. Drug release and degree of swelling were measured utilizing the modified disintegration test device operating at 40 and 80 mm/s.

## 5 Discussion

Understanding the role of hydrodynamics and pressure forces for disintegration/dissolution of oral solid dosage forms can help to improve disintegration testing and the predictive power of the *in vitro* test. This study provides a deep insight into the hydrodynamics and forces in the PhEur/USP disintegration test device. With an in-house built modified disintegration test device, the influence of different hydrodynamic conditions on tablet disintegration was investigated. Furthermore, the influence of hydrodynamic forces on swelling and drug release from gastroretentive drug delivery systems was evaluated.

### 5.1 Development of a modified disintegration test device

The modified disintegration test device is derived from the compendial PhEur/USP test device. It enables the investigation of the influence of hydrodynamic conditions and mechanical stresses on dosage form disintegration. The alterations made comprised three steps: 1) movement of the basket by a computer controlled computerized numerical control (CNC), 2) development of a modified basket design that enables two-sided fluid flow, and 3) simulation of physiologically relevant pressure forces on the dosage form by inflation and deflation of balloons. The influence of all factors can be examined separately. The application of computer control and CNC technology enables to examine the influence moving speed and moving profile on disintegration times. Simple as well as complex moving profiles can be applied simulating different conditions in different part of the human stomach. Due to its lateral open mesh structure the modified basket design allows two-sided fluid flow. Due to the fact that the modified device can be equipped with both baskets, the compendial and the modified, the influence of the different designs can be investigated. Forces on the dosage form can be applied by a computer controlled balloon system. Travelling through the stomach, a solid oral dosage form will be exposed to different hydrodynamic and mechanical conditions. Entering the fundus, the dosage form will experience little movement and low stress (Koziolek et al., 2013). The residence in this part of the stomach can be simulated by low moving speed and sparse or no inflation of the balloons, by which the pressure conditions can be varied. By settling down to the antrum the hydrodynamic and mechanical conditions become harsher (Koziolek et al., 2013). This can be simulated by higher moving speed and more frequent inflation of the balloons. The whole path through the different parts of the stomach can be simulated by varying hydrodynamic and

mechanical conditions during the test. A later development towards a test device for intestinal delivery systems is possible.

Investigations in this work were limited to the vertical movement of the basket. However, horizontal as well as radial movement is possible. The influence of moving direction on disintegration time remains to be investigated. Especially a unidirectional radial movement is a promising approach, since turning points can therefore be avoided. These turning points occur by change in direction when moving the basket vertically or horizontally, but are not likely observed *in vivo*.

A pressure unit was constructed to simulate mechanical aspects within the human stomach. Therefore, balloons were clamped to the solid walls of the modified basket design. By inflation of the balloons it should be possible to exert mechanical stress on the tablet. The results showed that this design is not yet suitable to serve its purpose. The balloons did not touch the tablet which was situated at the bottom of the mesh in the region that was not reached by the balloons. Furthermore, it can be assumed that the hydrodynamics are changed completely by inflation of the balloons. They block the fluid's path and force it aside. Thereby, hydrodynamic forces on the tablet cannot be well controlled. However, simulation of physiological relevant pressure forces during *in vitro* testing is highly important. The importance of gastrointestinal pressure forces for the release behavior from MR dosage forms has recently been shown (Garbacz et al., 2008). In this study, the irregular absorption profiles observed for diclofenac extended release tablets could be predicted using the stress test apparatus designed to generate physiologically relevant pressure forces.

The modified device was primarily established to investigate the influence of hydrodynamics and pressure forces on disintegration times of solid oral dosage forms. Such investigations are of importance for immediate release (IR) as well as for modified release (MR) delivery systems. IR dosage forms are intended to disintegrate fast after ingestion to achieve an instantaneous onset of the therapeutic effect. In contrast, MR dosage forms are exposed to the hydrodynamics and forces present in the GIT for a prolonged period of time and need to withstand them. After administration of high caloric meals gastric residence times of more than 4 h have been reported for non-disintegrating tablets and capsules (Weitschies et al., 2010; Weitschies et al., 2008). The mechanisms of retardation comprise the formation of diffusion barriers, the modification of the dissolution process of the dosage form, and the controlled erosion of the matrix. All these mechanisms are supposed to be sensitive to hydrodynamic stress and pressure forces. The modified disintegration test device may be used to investigate the stability of such systems against physiological relevant mechanical stresses.

The aspect of stability against mechanical forces becomes especially important for enteric coated dosage forms. During testing according to the pharmacopeia, the systems are exposed to 0.1 N HCl pH 1.2 for 2 h with subsequent testing in phosphate buffer pH 6.8. In 0.1 N HCl the dosage forms must not disintegrate, whereas in phosphate buffer they have to disintegrate within 60 min to fulfill the test. If the conditions *in vitro* are too gentle compared to the *in vivo* situation, the systems will pass the test *in vitro* but fail *in vivo*. A damage of the coating can have wide-ranging consequences comprising loss of drug release control and dose dumping.

## **5.2 Comparison of hydrodynamics in the compendial and modified basket design**

Computational fluid dynamics (CFD) studies were performed to characterize the hydrodynamics and forces in both basket designs: the compendial design of the PhEur/USP disintegration test device and the modified, in-house built basket design. The simulations were performed with different fluids and pasty foods to investigate the influence of viscosity on the fluid flows and forces (results see 4.1, 4.3, and 4.4).

The predicted fluid flow field is very different for the two designs (Figure 73). Horizontal as well as vertical fluid movement generates hydrodynamic stress on the tablet surface contributing to the dosage form disintegration. These fluid motions are different for the two basket designs. In the compendial basket the fluid is restricted to the glass tubes. This leads to a circular horizontal fluid movement where the fluid is pushed towards the tablet, which generates compressional forces on the surface. Due to the open mesh boundary of the modified basket design, the fluid is no more restricted but two-sided fluid flow is possible. This leads to a fluid motion pointing away from the tablet. Furthermore, the peak velocities of the vertical fluid movement (y-component of velocity vector) are much higher for the compendial design compared to the modified design (Table 20). Due to these different fluid motions and fluid velocities, the frictional and erosional forces on the tablet surface are different for the two designs. In the compendial basket approximately three times higher average shear stress on the tablet surface is predicted compared to the modified basket design (Table 20). It needs to be considered, that the reported values for the compendial device are instantaneous forces and velocities at  $t=0.5$  s of the movement cycle. Throughout the movement cycle, hydrodynamics and forces are changing continually. However, the values are comparable to those obtained for the modified device operated at 0.08 m/s due to comparable velocity of the compendial device at  $t=0.5$  s.

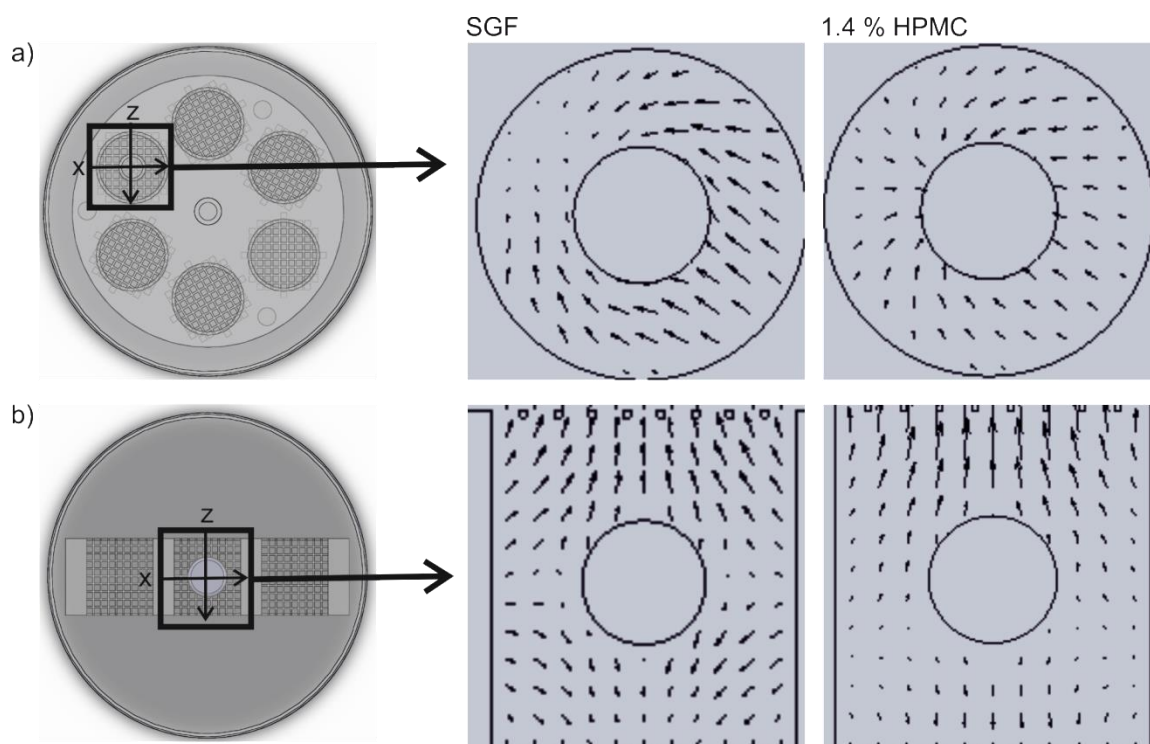


Figure 73: Velocity vector field on a horizontal cross section across the tablet for the a) compendial basket design and b) modified basket design. a) Shows the velocity vector field for the compendial basket design at  $t=0.5$  s of the movement cycle, which is the point of maximum moving velocity (approximately 0.08 m/s). b) Shows the velocity vector field at a moving velocity of 0.08 m/s.

Table 20: Comparison of velocity magnitude and average shear stress in the compendial (at  $t=0.5$  s of the movement cycle where moving velocity reaches 0.085 m/s) and modified basket design (moving velocity=0.08 m/s). The y-component represents the vertical fluid motion. The x- and z-component represent the horizontal fluid motion. Direction of x- and z-axis is illustrated in Figure 73.

	Compendial		Modified	
	SGF	1.4 % HPMC	SGF	1.4 % HPMC
Max velocity in y-direction along x-axis [m/s]	0.22	0.18	0.085	0.035
Max velocity in y-direction along z-axis [m/s]	0.21	0.17	0.12	0.11
Max velocity in x-direction along x-axis [m/s]	0.03	0.02	0.007	0.003
Max velocity in z-direction along z-axis [m/s]	0.017	0.019	0.02	0.04
Average shear stress [Pa]	0.53	48	0.16	20

### 5.3 Comparison of simulated hydrodynamic conditions with literature data

Table 21 gives an overview of the predicted dynamic viscosity, velocity, pressure and forces in the vicinity of the tablet simulated for the different beverages, viscous meals, and model fluids. Simulations were performed for the compendial as well as for the modified disintegration test device (results see 4.1 and 4.3). For the compendial device the inlet velocity was defined to follow the sinusoidal velocity profile described by eqn. ( 2 ). This equation describes the cycle of down and up movement with a maximum moving velocity of 0.085 m/s. One cycle last 2 s. Results discussed in this section are referred to  $t=0.1$  s, which is the beginning of the down movement, and  $t=0.5$  s, which is the time of maximum moving velocity during the down movement. Furthermore, these results are compared to the predictions obtained for the modified disintegration device equipped with the modified basket design and operating at 0.08 m/s. Since the moving speed of the compendial device at  $t=0.5$  s is similar to that of the modified device operating at 0.08 m/s comparison of results is possible.

The viscosity of the Newtonian fluids is independent on the shear rate and constant throughout the cycle and device. In contrast, the viscosities of the non-Newtonian fluids are dependent on the shear rate. The dynamic viscosity of the non-Newtonian fluids in the two devices is not constant throughout the beaker but dependent on the shear rate generated by the fluid flow (see Figure 33 and Figure 44). Around the tablet values of 0.18 Pa s for champignon soup up to 27 Pa s for the homogenized FDA meal are predicted for the modified device at  $t=0.5$  s. At this time of the moving cycle the moving velocity is maximum and shear rates are maximum too. With increasing shear rate the dynamic viscosity decreases. Thus, dynamic viscosities at  $t=0.5$  s are the lowest during the movement cycle. Dynamic viscosities at all other time point during the down movement are expected to be lower due to lower moving velocity and lower shear rates. The dynamic viscosity of the mashed FDA meal around the tablet predicted for the modified disintegration test device operating at a moving velocity of 0.08 m/s is even higher reaching 50 Pa s. The dynamic viscosity predicted for the compendial device at  $t=0.5$  s for the model fluid 1.4 % HPMC solution is 0.54 at  $t=0.5$  s, which is similar to that predicted for the modified device operating at 0.08 m/s (0.69 Pa s). Compared to *in vivo* results, which are reported in the range of 0.01 to 0.2 Pa s for the fed stomach (Abrahamsson et al., 2005), the viscosity around the tablet is too high when using the homogenized FDA meal to simulate the fed state. This may be due to the fact that either the FDA meal *in vivo* is diluted due to a secretion of gastric fluids or that the shear rate *in vivo* is higher than in the disintegration device. When using 1.4 % HPMC

solution, which is proposed as model medium representing the fed state, values of dynamic viscosity around the tablet are in the range of those reported *in vivo*. No information about fasted state fluid viscosity *in vivo* is available.

The vertical velocity component (y-component) is higher compared to the horizontal velocity components (x- and z-component) for both designs (see Figure 31 and Figure 42). For the compendial basket design highest velocities are reached between the tablet and the tube wall. Right above and below the tablet, depending on the direction of movement, no fluid movement is predicted and a sheltered region occurs. During the movement cycle the tablet experiences a wide range of fluid velocities reaching maximum values of about 0.2 m/s at  $t=0.5$  s. Only small differences are predicted when comparing the media of different viscosities. However, the calculated average vertical velocity across the tube diameter at  $t=0.5$  s is smaller (0.06 m/s for all simulated fluids). For the modified basket design the predicted maximum is 0.12 and 0.11 m/s for SGF and 1.4 % HPMC solution, respectively. Average vertical velocity across the chamber length for SGF is 0.079 m/s which is higher compared to that predicted for the compendial design at  $t=0.5$  s. For 1.4 % HPMC solution and the mashed FDA meal the average vertical velocity across the chamber length is 0.053 m/s which is lower compared to that predicted for the compendial device at  $t=0.5$  s. Only little is known about the fluid velocities and flow fields in the human stomach. Using magnetic resonance imaging, Boulby *et al.* (1999) reported antral fluid velocities in the range of 0.029 to 0.05 m/s for different nutrient meals. Earlier, Hausken *et al.* (1992) measured velocities one order of magnitude higher than those of Boulby *et al.* They used duplex sonography to measure the movement of luminal contents after ingestion of a meat soup and found maximal velocities during retropulsion of 0.2 m/s and peak velocities of 0.6 m/s. Besides *in vivo* measurements CFD was used to investigate fluid flow in the human stomach (Ferrua and Singh, 2010; Ferrua *et al.*, 2011; Kozu *et al.*, 2010; Pal *et al.*, 2004). In all studies strongest fluid motions were predicted in the lower part of the stomach while only little fluid motion is predicted in the upper part. These predictions are consistent with experimental observations (Hausken *et al.*, 1992). The flow field in the antroduodenal region is characterized by two main flow structures: a jet-like motion and zones of recirculating fluid (eddies). However, the predicted values for maximum retropulsive jet velocities are not consistent. Pal *et al.* reported highest jet velocities of 0.0075 m/s for a liquid with a viscosity of 1 Pa s using a two-dimensional model (Pal *et al.*, 2004). Using a three-dimensional model Ferrua *et al.* predicted maximum jet velocities of 0.076 m/s and 0.119 m/s for liquids of a viscosity of 0.001 and 1 Pa s, respectively (Ferrua and Singh, 2010; Ferrua *et al.*, 2011). Our simulated peak velocities in the modified basket are consistent with the peak jet velocities predicted from the latter CFD study. Predicted peak velocities in the compendial device are consistent with the

peak velocities reported by (Hausken et al., 1992). Calculated average velocities for both devices are of the same order of magnitude of the experimental data measured by Boulby et al. Peak velocities reported by Hausken et al. are highest (0.6 m/s). Such high velocities are neither reached for the compendial nor for the modified basket design operating at the specified conditions. A comparison of simulated velocities and *in vivo* data is hindered by the diverging results between the two existing *in vivo* studies which differ approximately by one order of magnitude (Boulby et al., 1999; Hausken et al., 1992).

The flow pattern around the tablet is characterized by the Reynold's number (eqn. (24)). For  $Re$  around 100 the flow above the tablet surface opposite to the fluid stream is thought to start to oscillate back and forward indicating the formation of eddies (recirculating flow structures). Calculations of the Reynold's number for the flow around the tablet revealed values  $> 100$  for SGF in the compendial as well as in the modified basket design (834 and 876 for the compendial and modified device, respectively). Values for 1.4 % HPMC solution and the homogenized FDA meal are  $< 100$  for both basket designs (1.05 and 0.86 for 1.4 % HPMC solution in the compendial and modified device, respectively and 0.02 and 0.009 for the mashed FDA meal for the compendial and modified device, respectively). Reynold's numbers observed *in vivo* around a tablet of a diameter of 1 cm are in the range of 0.01 to 30 (Abrahamsson et al., 2005). Thus, the values calculated for SGF seem high but currently lack *in vivo* comparative data. Nevertheless, the values calculated for the homogenized FDA meal and the 1.4 % HPMC solution in both *in vitro* disintegration devices are at the lower end of these determined by *in vivo* studies.

For Newtonian fluids the predicted relative pressures at the bottom of the tablet are very small in the range of 71 to -32 Pa (0.53 to -0.24 mm Hg) for both basket designs. For the non-Newtonian fluids a strong viscosity dependence of the relative pressure is predicted. Especially when using the FDA meal the tablet experiences a very large range of relative pressures during one cycle using the compendial device. Maximal values of 24664 Pa (185 mm Hg) are predicted. The relative pressure around the tablet is much smaller when using FDA meal in combination with the modified basket design (5333 Pa, 40 mm Hg). For 1.4 % HPMC solution relative pressure around the tablet is about one order of magnitude smaller in the modified basket design compared to the compendial. Different manometric studies detected fasting intragastric pressures in the range of 600 to 1333 Pa (4.5 to 10 mm Hg) (Desipio et al., 2007; Janssen et al., 2012; Kwiatek et al., 2009; Pauwels et al., 2014). Several studies (Janssen et al., 2011; Janssen et al., 2012; Kwiatek et al., 2009; Pauwels et al., 2014) investigated also the influence of infusion and ingestion of nutritional drinks on intragastric pressure. They found that the postprandial

increase in intragastric pressure is not higher than 867 Pa (6.5 mm Hg). Our simulation results indicate that when using high viscous mashed FDA meal relative pressure around the tablet is much higher than those pressures observed *in vivo* after ingestion of nutritional drinks. When using soups or 1.4 % HPMC solution the relative pressure is low compared to fed state values *in vivo*. For the fasted state, represented by SGF, relative pressures are ten fold lower compared to *in vivo* data.

Average shear stress on the tablet surface is smaller in the modified device compared to the compendial one. However, for both a marked viscosity dependence is observed. Note that for the predictions it is assumed that the tablet is fixed at the wire mesh contrary to the *in vivo* situation where it would be taken with the fluid experiencing less shear stress. In practice the tablet will be carried with the fluid when the drag force is larger than the weight force. For a 500 mg tablet this is the case for all used non-Newtonian soups and pasty foods. However, it is not the case for 1.4 % HPMC solution which is proposed as model fluid representing the fed state. So far, precise *in vivo* measurements of forces experienced by a tablet are rare.

Furthermore, shear stress, which acts tangential to the tablet surface, needs to be distinguished from pressure forces, which act perpendicular to the surface of the tablet. While tangential stress will mainly cause surface erosion, perpendicular forces will more likely be responsible for rupture and breakage of the tablet. Some approaches have been demonstrated to measure the different forces *in vivo*. Vassallo *et al.* (1992) used a balloon catheter to measure the axial forces during emptying of liquid and solid meals. The forces experienced by the balloon were reported to be 6.0 N for emptying of the liquid meal and 22.0 N for the solids. As the balloon is larger than a conventional pill and additionally tethered, the results cannot easily be transferred to tablets. Marciani *et al.* (2001a) used echo-planar imaging to assess antral grinding of a low viscous and a high viscous liquid meal containing agar gel beads with a range of fracture strengths. The gel beads accumulated in the antral region where they were exposed to antral axial forces between 0.53 and 0.78 N. Using a destruction force dependent release system, Kamba *et al.* (2000) reported the destructive force to be 1.50 N in the fasted state and 1.89 N in the fed state. These two measurements represent indirect determination of destructive forces as they did not measure the force on the dosage forms but observed the breakage visually or quantified the release of an API, respectively. Laulicht *et al.* (2010) measured gastric forces on a gastric pill directly using high-resolution pill tracing. They reported values of average human gastric emptying force of 414 dynes (0.00414 N) for the fasted state and 657 dynes (0.00657 N) for the fed state. Much higher forces were observed during the migrating motor complex (MMC) of the fasted state with highest forces of 2481, 3014, and 1236 dynes (0.02481, 0.03014,

and 0.1236 N). Comparing the simulation results with these data, it is obvious that the forces in the *in vitro* disintegration tester are much smaller. For SGF, representing the fasted state test medium, average shear forces of 0.00010 N and 0.000032 N for the compendial and modified basket design are predicted, which are about 3 orders of magnitude lower than those observed during MMC. This large difference could be due to the fact that *in vivo* hydrodynamic fluid flow and shear forces are generated by peristaltic contractions of the stomach wall, which are lacking *in vitro*. The compendial device is not able to reproduce these forces generated by moving walls as it consists of static glass tubes. This might be a major limitation of the PhEur/ USP test device considering the prediction of tablet disintegration *in vivo*. The same is true for the modified basket design. But this limitation should be overcome through the usage of the pressure unit. By inflation of the balloons, the peristaltic contractions of the stomach walls might be simulated. Predicted average shear stress in the fed state (1.4 % HPMC solution) is of the same order of magnitude as the values reported by Laulich et al (2010). Comparison of predicted values with *in vivo* data is difficult since the reported values are very inconsistent and largely dependent on the method used for determination.

In summary, it can be concluded that the compendial device for measuring solid dosage form disintegration is not optimally designed to reproduce the *in vivo* situation in terms of relative pressures and forces. Regarding a comparison of fluid velocities *in vitro* versus *in vivo* it turns out to be limited by the few and diverging *in vivo* data available. The modified disintegration test device seems to be able to generate physiologically relevant hydrodynamics by the selection of appropriate operating conditions. In contrast to the compendial device, that is limited to the vertical movement following the sinusoidal velocity profile, various moving profiles can be generated using the modified device (4.2). Thus, a mechanistic investigation of the influence of fluid velocity and forces on tablet disintegration using the modified device seems justified.

Table 21: Summary of simulation results and literature data.

			SGF*	Apple juice	Orange juice	Champignon soup	Tomato soup	1.4 % HPMC solution	FDA meal*
Viscosity [Pa s]	compendial	0.1 s	$8.2 \cdot 10^{-4}$	$1.6 \cdot 10^{-3}$	$3.4 \cdot 10^{-3}$	0.57	2.1	0.77	58
		0.5 s	$8.2 \cdot 10^{-4}$	$1.6 \cdot 10^{-3}$	$3.4 \cdot 10^{-3}$	0.18	0.94	0.54	27
	new		$8.2 \cdot 10^{-4}$					0.69	50
Maximum velocity [m/s]	Abrahamsson et al., 2005								0.01- 2
	compendial		0.2	0.2	0.2	0.2		0.2	0.2
Average velocity in y-direction along z-axis [m/s]	new		0.1					0.1	0.1
	compendial	0.1 s	0.015	0.016	0.016	0.018	0.018	0.018	0.018
		0.5 s	0.064	0.064	0.069	0.070	0.064	0.063	0.063
Velocity [m/s]	new		0.079					0.053	0.053
	Boulby et al., 1999								0.029-0.05
	Hausken et al., 1992								0.2-0.6
	Pal et al., 2004								0.0075
Reynolds number	Ferrua and Singh, 2010 and Ferrua et al., 2011		0.076						0.119
	compendial	0.5 s	834					1.05	0.02
	new		867					0.69	0.009
Relative pressure [mmHg]	Abrahamsson et al., 2005								0.01-30
	compendial	0.1 s	0.30	0.33	0.35	1.5	4.6	2.28	118
		0.5 s	0.16	0.17	0.21	1.6	6.9	4.05	185
	new		-0.24					0.26	39.6
	Desipio et al., 2007; Janssen et al., 2011; Janssen et al., 2012; Pauwels et al., 2014		4.5-10						

Table 21 continued.

			SGF*	Apple juice	Orange juice	Champignon soup	Tomato soup	1.4 % HPMC solution	FDA meal*
Average shear stress [N]	compendial	0.1 s	$1.7 \cdot 10^{-5}$ **	$2.0 \cdot 10^{-5}$ **	$3.6 \cdot 10^{-5}$ **	$1.6 \cdot 10^{-3}$ **	$7.2 \cdot 10^{-3}$ **	$3.8 \cdot 10^{-3}$ **	0.20**
		0.5 s	$1.0 \cdot 10^{-4}$ **	$1.3 \cdot 10^{-4}$ **	$2.2 \cdot 10^{-4}$ **	$2.6 \cdot 10^{-3}$ **	0.012**	$9.6 \cdot 10^{-3}$ **	0.21**
	new		$3.2 \cdot 10^{-5}$ **					0.004**	0.21**
	Vassallo et al., 1992***		6.0						22.0
	Marciani et al., 2001a***								0.53-0.78
	Kamba et al., 2000***		1.5						1.89
	Laulicht et al., 2010***		0.00414						0.00657
Drag force [N]	compendial	0.1 s	$2.3 \cdot 10^{-3}$	$2.3 \cdot 10^{-3}$	$2.4 \cdot 10^{-3}$	$3.2 \cdot 10^{-3}$	$8.2 \cdot 10^{-3}$	$4.7 \cdot 10^{-3}$	0.17
		0.5 s	$3.9 \cdot 10^{-3}$	$3.9 \cdot 10^{-3}$	$4.3 \cdot 10^{-3}$	$5.7 \cdot 10^{-3}$	0.014	$1.2 \cdot 10^{-2}$	0.24
	new		$3 \cdot 10^{-3}$					$7.9 \cdot 10^{-3}$	0.25

\* Simulations were performed with SGF and mashed FDA meal as model fluids for the fasted and fed state. Values form *in vivo* studies listed in these columns are given for the fasted and fed state.

\*\* Values calculated from Pascal using the tablet surface of  $0.0002 \text{ m}^2$ .

\*\*\* Large differences in reported values could be due to different measurement techniques. Results of Marciani et al. (2001a) and Kamba et al. (2000) are from indirect measurement of gastrointestinal contractility, measured by destructive force dependent dosage forms. Results of Vassallo et al. (1992) represent the cumulative load experienced by a balloon over 30 min and 2 h during emptying of a liquid (representing fasted state) and solid (representing fed state) meal. Laulicht et al. (2010) report the translational components of force on a magnetic pill. Differences of reported values for the fasted state could additionally be due to measurement during different phases of the migrating motor complex characterized by different contractile strengths. In the fasted as well as in the fed state the contractile strength and thus shear stress also depends on the nature of gastric contents, which was different among the studies.

## 5.4 Limitations of computational fluid dynamics (CFD)

With the help of experimental particle image velocimetry (PIV) data it was proofed that the CFD approach is capable of predicting the hydrodynamics in the disintegration test device (section 4.1.1.) Nevertheless, the model is subjected to a few limitations.

In general, the accuracy of the predictions depends on the number of cells captured by the mesh. The more refined the mesh, the more accurate the results. However, with more cells of the mesh, the more computational power is needed to solve the project and the longer the calculation time. A reasonable compromise between accuracy and calculation time needs to be defined.

In this work it was assumed that the tablet is fixed on the wire mesh and no movement or floating occurs. This is contrary to the conditions observed in experiments. Depending on the moving velocity and medium viscosity, the tablet will be moved with the fluid. Thereby, forces on the tablet will change.

The process of tablet size reduction during disintegration testing was neglected in this study. Since a relationship between tablet size and average shear stress on tablet surface was found, the process of solid mass transfer from the tablet to the test medium needs to be considered.

However, the present study is, to our knowledge, the first investigation of hydrodynamics in the disintegration device using a CFD approach. Despite the limitations, the results help to understand the underlying hydrodynamics and shear stress within the compendial and modified disintegration test device.

## 5.5 Disintegration mechanisms

Tablet disintegration is a complex process comprising different mechanisms including surface erosion, fraction, rupture and dissolution of the drug and/or excipients (Figure 74). Solid oral dosage form disintegration is a result of an interaction of all these mechanisms.

Surface erosion is defined as the skimming of the tablet surface due to detachment of surface particles by the impinging fluid that causes friction and shear stress. Therefore, surface erosion is sensitive to hydrodynamic conditions. Surface erosion is the dominant mechanism when the applied stress is high and the water penetration is slow.

Fraction is the breakage of the tablet into large size particles and occurs when the applied stress is higher than cohesive forces of the tablet. It is also sensitive to hydrodynamics since they define the relative pressure field around the tablet and the pressure forces acting on the tablet. During disintegration testing the texture of the dosage form may change and become softer. This softening may shift the driving disintegration mechanism towards fragmentation.

The tablet may be reduced in size due to dissolution of the drug or the excipients. This process is mainly dependent on the dissolution rate and the solubility of the components. But it can also be influenced by the hydrodynamics by the formation of a boundary layer that limits the dissolution.

Rupture defines the process of bursting of the tablet due to solvent uptake and the action of the disintegrant. This mechanism is independent of the hydrodynamic conditions but dependent on the swelling kinetics, the water uptake rate, and the test medium composition. The effects of fluid composition and viscosity, water uptake, and water diffusivity on disintegration of solid oral dosage forms have been investigated previously (Abrahamsson et al., 2004; Anwar et al., 2005; Radwan et al., 2012; Radwan et al., 2013; Radwan et al., 2014). The results of these studies are summarized in the introduction (1.1.1).

All these disintegration mechanisms may occur simultaneously. Or, depending on the properties of the tablet and the fluid characteristics of the disintegration medium, one mechanism may dominate. A shift from one mechanism to another during disintegration due to changes in the texture of the tablet is also possible.

The following section concentrates on the discussion of the effect of hydrodynamic forces on disintegration and helps to understand the observations described in the results part investigating the influence of hydrodynamics on disintegration time of IR tablets (4.5).

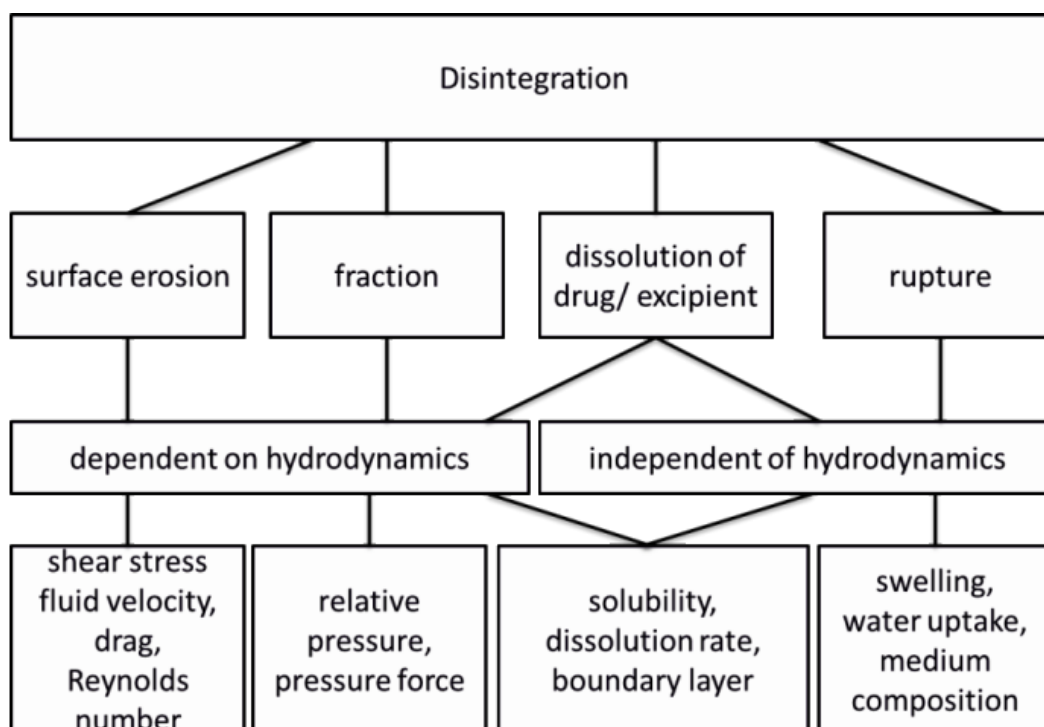


Figure 74: Disintegration mechanisms. Four major mechanism, namely surface erosion, fraction, dissolution of excipient/drug, and rupture, were identified to be responsible for solid oral dosage form disintegration. Among them, rupture is the only one independent of hydrodynamic conditions. It is dependent on swelling, water uptake, and the medium composition. Dissolution of the drug/excipient is both dependent and independent on the hydrodynamics. Dissolution as such is determined by the solubility and the dissolution rate, which are independent on hydrodynamics. Nevertheless, dissolution is dependent on the thickness of the boundary layer, which is dependent on hydrodynamics. Surface erosion and fraction are dependent on the hydrodynamic conditions since they determine shear stress, fluid velocity, drag forces, Reynold's number, and pressure forces.

## 5.6 Effect of hydrodynamics on disintegration times of immediate release tablets

A design of experiments study was performed to investigate the influence of moving velocity, medium viscosity, and tablet hardness on disintegration of immediate release (IR) tablets. The compendial as well as the modified basket design were utilized to additionally examine the influence of different fluid flow fields on disintegration times (results see section 4.5).

It was observed that an increase in tablet hardness results in an increase of disintegration time (Figure 54). The higher hardness was achieved by applying higher compression force to the same formulation. Due to the higher compression force the tablets with the higher hardness are supposed to exhibit a lower porosity compared to the tablet with the lower hardness. Due to the fewer pores water penetration rate is supposed to be slower leading to the observed delay in tablet disintegration. Furthermore, the surface erosion form tablet with a more rigid texture is slower, thus contributing to prolonged disintegration time.

An increase in the medium viscosity leads to an increase in disintegration time (Figure 54). These observations are consistent with other published work (Radwan et al., 2012; Radwan et al., 2013; Radwan et al., 2014; Abrahamsson et al., 2004; Anwar et al., 2005) and can be attributed to the low water diffusivity and slow water penetration in viscous media. The slow solvent penetration hampers swelling and rupture thereby prolonging disintegration.

In SGF the influence of moving speed on disintegration time is similar for both basket designs (Figure 54). At low tablet hardness, disintegration is very fast and the influence of moving speed on disintegration times is minimal. Due to the high porosity of these tablets water penetration is fast. Therefore, rupture is the driving force of disintegration. The effect of moving velocity on disintegration time becomes more pronounced with increasing tablet hardness. Higher moving speeds reduce disintegration times. Due to the higher hardness, the tablets possess fewer pores. The water penetration rate is slower and the mechanism of disintegration changes from rupture to surface erosion. The higher the moving speed, the higher the fluid velocity and shear stress leading to decreased disintegration times. Due to short disintegration times, fragmentation may play a minor role in SGF. Dissolution of the excipients may also contribute to disintegration. But since the dissolution is less dependent on the hydrodynamics, the contribution will be similar for 40 and 80 mm/s and will not explain the different disintegration times.

In 1.4 % HPMC solution the effect of moving speed on tablet disintegration is different for the two basket designs (Figure 54). While the moving speed has a significant influence on disintegration time for the compendial basket, it has only a negligible influence for the modified basket. This observation is quite surprisingly and must be related to the different design of the baskets leading to different hydrodynamic conditions and forces. Especially in 1.4 % HPMC solution, fluid velocities and shear stress are much different for the two basket designs. These differences observed for 1.4 % HPMC solution might lead to different disintegration mechanisms in the compendial and modified basket design. It can only be hypothesized, that due to the different fluid velocities and shear forces in the compendial and the modified basket, the formation of the boundary layer around the tablet that occurs in viscous media is influenced. Average shear stress in the compendial basket is much higher compared to the modified. This high shear stress might hinder the formation of a thick protective boundary layer in the compendial basket, making the tablet sensitive to changes in hydrodynamics. This hypothesis is supported by the fact that in SGF, where no film is developed, the influence of moving speed on disintegration time is similar in both baskets. It can not be clearly recognized

which mechanism is responsible for disintegration in 1.4 % HPMC solution due to the complexity of interactions.

An exponential correlation between disintegration time and moving speed and between disintegration time and average shear stress on tablet surface at the corresponding moving speed was observed in SGF (Figure 58).

No effect of moving velocity on the disintegration times of commercially available calibrator tablets was observed in SGF as well as in 1.4 % HPMC solution (see Figure 59). Since the disintegration is independent of the hydrodynamics, rupture and dissolution are the driving forces of disintegration while the contribution of surface erosion is negligible. Since disintegration times are short, fragmentation due to softening should not contribute to disintegration. The observations prove the robustness of the calibrator tablets against changes in hydrodynamic conditions. The robustness cannot be related to formulation variables since the exact composition is unknown. However, the main excipient is lactose, which is the same for the IR tablets that are sensitive to hydrodynamic changes.

Applied mechanical forces may shift the disintegration mechanism towards fragmentation due to high local forces. The importance of externally applied mechanical forces for accurate prediction of dissolution from extended release tablet has been demonstrated by Garbacz et al. (2009; 2014; 2015; 2008; 2010). They developed a biorelevant dissolution test apparatus that is able to simulate the mechanical forces of the human GIT. They described that the release of the drug from all investigated formulations was sensitive to mechanical stress. Unfortunately, the investigation of the influence of physiological relevant pressure forces using the in house-built pressure unit was not possible in this work due to shortcomings of the construction (Figure 60).

## **5.7 Effect of polymer properties and hydrodynamics on in vitro performance the of gastroretentive drug delivery systems**

An *in situ* interpolyelectrolyte gastroretentive drug delivery system was developed. Several requirements were imposed: fast and high degree of swelling, adequately floating ability, sufficient stability against hydrodynamic and mechanical stresses and extended drug release over 24 h. To achieve these targets two polymers were combined to build a polyelectrolyte matrix upon contact with fluid. The *in vitro* performance of the systems investigated here is influenced by a complex interaction of the properties of the polymers, their ratio, pH of the test medium as well as the hydrodynamic test conditions (see 4.6 and 4.7). However, the

formulation of chitosan 80/1000 (80 % deacetylation, viscosity 1000 mPa\*s) and the iota-carrageenan (379) in the ratio 1:8 (80/1000:379 1:8) is regarded as the optimized formulation since it shows sufficient pH-independent swelling that is resistant to hydrodynamic stress and prolonged drug release over a period of 24 h. However, the drug release from this optimized formulation is very sensitive to changes in hydrodynamic forces (see Figure 71). Gastroretention of the dosage form and enhancement of bioavailability of the model drug trospium chloride need to be proofed in an *in vivo* study.

Several polyelectrolyte complexes have been proposed for gastroretentive and controlled drug delivery (Bawa et al., 2011; Bani-Jaber et al., 2011; de la Torre et al., 2005; Gómez-Burgaz et al., 2008; Ngwuluka et al., 2013; Moustafine et al., 2013; Park et al., 2008; Prado et al., 2008). Traditionally, the complexes are prepared by dissolving the polyelectrolytes separately and subsequent mixing of the solution. The complexes precipitate and need to be lyophilized before further processing. Usually, the dried powders are compressed to tablets. This manufacturing approach is time and cost intensive. This work demonstrated that it is possible to form the polyelectrolyte complex *in situ* by appropriate polymer selection.

Upon contact with fluids the polymers become charged and form the polyelectrolyte complex. Due to the hydrophilic nature of the polymers the polyelectrolyte network starts to swell forming a gel layer which acts as release controlling barrier. The drug release from hydrophilic swelling matrices is controlled by dissolution of the drug, diffusion of the drug through the gel layer, and erosion of the swollen matrix (Colombo, 1993; Maderuelo et al., 2011) (Figure 75).

The effect of several polymer properties and medium characteristics on drug release from hydrophilic matrix tablets has intensively been studied (Colombo, 1993; Maderuelo et al., 2011, Conti et al., 2007a, 2007b, Maggi et al., 2002; Siah et al., 2005; Siah-Shadbad et al., 2011). The viscosity of the matrix polymer was found to influence drug dissolution significantly. For HPMC matrices, for example, drug release from matrices comprised of higher viscosity grade HPMC was slower compared to the lower viscosity grade HPMC (Nagarwal et al., 2010). Similar results were obtained for the polyelectrolyte swelling system evaluated in this work (Figure 68, Figure 69). The release from systems containing the higher viscous lambda-carrageenan 209 was retarded compared to formulations with the low viscous iota-carrageenan 379. It is supposed that the higher viscosity grade of a polymer can strengthen the gel layer and thereby retard water penetration. Therefore, less swelling is observed using the high viscous lambda-carrageenan 209 (Figure 63). A close correlation between water penetration and drug release is obvious.

Several studies reported the dependence of drug release on the hydrodynamic conditions present during dissolution testing (Li et al., 2013a; Yang and Fassihi, 1997). Resistance against hydrodynamic and mechanical stresses is especially important for controlled release dosage forms. Firstly because they are exposed to gastric forces for several hours experiencing a wide range of hydrodynamic and mechanical stresses due to different prandial states and moving patterns of the stomach. And secondly, insufficient stability against stresses will cause loss of control of drug release and change in release profile showing undesired effects like dose dumping. Therefore, the influence of moving velocity on the degree of swelling and drug release from an *in situ* polyelectrolyte gastroretentive matrix system was investigated to provide greater insight into the systems ability to withstand physiological relevant hydrodynamic stress *in vivo*.

Both were largely dependent on the hydrodynamic conditions (Figure 70, Figure 71). The degree of swelling increased with rising hydrodynamic stress and drug release was accelerated by increasing moving speed. Drug release from swellable hydrophilic matrices is reported to be determined by the degree of swelling and the thickness of the gel layer (Colombo, 1993). By correlating the released amount of drug with the degree of swelling a linear relationship was obtained (Figure 72). However, the slopes of the correlations were different at varying hydrodynamic stress. Therefore, the degree of swelling might not be the only factor determining drug release. Surface erosion and flow through the polymeric gel layer may also influence drug release. Figure 75 summarizes the factors affecting drug release from the swelling gastroretentiv systems and their dependence on hydrodynamics. Shear stress, fluid velocity and the Reynolds number have large impact on the surface erosion. Therefore, surface erosion might be higher at rising hydrodynamic stress accelerating drug release. Diffusion of the drug through the gel layer is dependent on the solubility of the drug as well as on the viscosity of the polymers. These two parameters are independent of the hydrodynamics. Diffusion is also controlled by the thickness of the boundary layer, which is dependent on the hydrodynamics. A thicker boundary layer constitutes a longer diffusion path, thereby decreasing drug release rate. The boundary layer formed at low hydrodynamic stress might be thicker compared to the one formed at higher hydrodynamic stress. Additionally, the drug can be released by liberation from the polymeric network. This process is highly dependent on the hydrodynamic conditions since higher fluid flow through the polymeric network is present at higher hydrodynamic stress. The fluid passing through the polymeric network might liberate the drug.

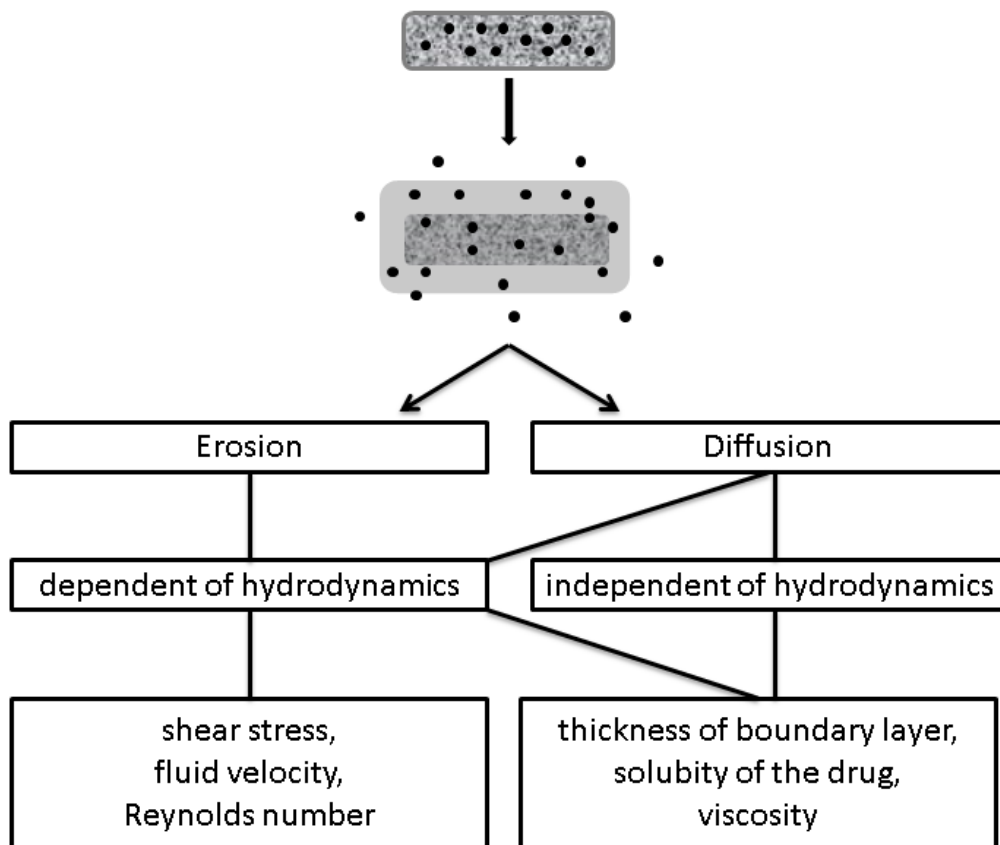


Figure 75: Drug release mechanisms from gastroretentive swelling drug delivery systems. Drug release from swelling systems is controlled by erosion and diffusion. Diffusion is both dependent and independent on hydrodynamic conditions. Diffusion as such is independent on the hydrodynamics but dependent on the diffusion pathway, which is determined by the thickness of the boundary layer. The latter is dependent on the hydrodynamics. Erosion is largely dependent on the hydrodynamics since they control the shear stress on the surface, the velocity of the fluid passing the dosage form, and the Reynold's number.

## 6 Conclusion and future work

For the first time computational fluid dynamics (CFD) was used to characterize the fluid flow field and forces in the PhEur/USP disintegration test device. The comparison of the predicted values with *in vivo* literature data proved difficult as either little is known or the information is diverging. Nevertheless, the biorelevance of the compendial device is questionable, especially in terms of fluid velocity and forces on the tablet surface. Furthermore, hydrodynamic conditions are variable during the movement cycle and not controllable. This observation led to the development of a modified disintegration test device to examine the relationship between hydrodynamic flow as well as destructive forces and disintegration times of oral solid dosage forms. The modifications comprised three steps: 1) change of moving profile and velocity by application of a computerized numerical control, 2) development of a modified basket allowing two-sided fluid flow, and 3) possibility to exert mechanical pressure by inflation of balloons.

First experiments showed that hydrodynamic forces may influence the disintegration time of immediate release tablets as well as controlled release dosage forms. These investigations contributed to a better understanding of the role of hydrodynamics for oral solid dosage form disintegration and dissolution. Appropriate test conditions need to be evaluated. *In vitro* disintegration and dissolution studies need to be undertaken under physiologically relevant conditions to strengthen the predictive power of the results. The two case studies with IR and CR dosage forms showed the importance of hydrodynamics for the evaluation of *in vivo* performance. Using the modified test device operated at appropriate conditions the predictive power of *in vitro* disintegration testing can be enhanced.

The in house-built pressure basket was designed with the aim to simulate physiologically relevant mechanical stress on the dosage form surface. However, the constructed unit needs further development to simulate biorelevant mechanical processes. By inflation of the balloons, the tablet was pushed towards the bottom and settled. At this position it was not in contact with the balloons and thus no pressure could be applied to the tablets. Therefore, the pressure basket needs to be modified. A setup where the tablet is fixed in the tube with the help of a pouch seems promising.

The investigations described in this work were limited to the vertical movement of the basket. The influence of horizontal and radial movement on disintegration needs to be investigated.

More ambitious moving profiles need to be defined to simulate the movement of the dosage form through the different parts of the stomach.

Both media used in this work, SGF and 1.4 % HPMC solution, were chosen as model fluids representing the fasted and fed state in terms of viscosity. Further experiments could be performed using more biorelevant media to evaluate the utility of the model media for disintegration testing.

A method to measure disintegration times *in vivo* is urgently required. The results of these measurements will help to validate the modified disintegration test device. For this purpose we developed a multiple unit dosage form depicted in Figure 76 (Formulation and manufacture procedure can be found in the appendix). Three minitables, loaded with a marker substance detectable with magnetic resonance imaging (MRI), are incorporated in a surrounding matrix of excipients. After ingestion, the spots of the three minitables are detected in direct vicinity to each other. Upon disintegration the three spots separate and are detected as individual signals.

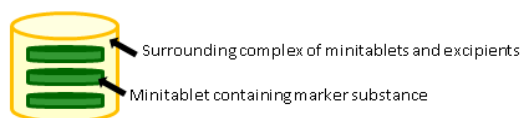


Figure 76: Schematic representation of tablets for *in vivo* disintegration measurement using MRI.

Concluding, the results of this thesis contribute to a better understanding of the role of hydrodynamic forces in disintegration and dissolution of solid oral dosage forms. The development of a modified disintegration test device paved the way towards improved *in vitro* disintegration testing. The experiments performed so far showed the importance of hydrodynamic conditions for disintegration and dissolution. However, appropriate test conditions need to be evaluated on the basis of *in vivo* disintegration times, which are not available so far.

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## 8 Appendix

### 8.1 Mesh cell information

Table 22: Mesh cells.

	Modified basket design	Compendial basket design	
		Newtonian fluid	Non-Newtonian fluids
Cells	69574	234476	100164
Fluid cells	44441	163710	64397
Solid cells	7018	16958	7310
Partial cells	18115	53808	28457
Irregular cells	0	0	0
Trimmed cells	0	0	0

## 8.2 Supporting information on the modified disintegration test device

### device

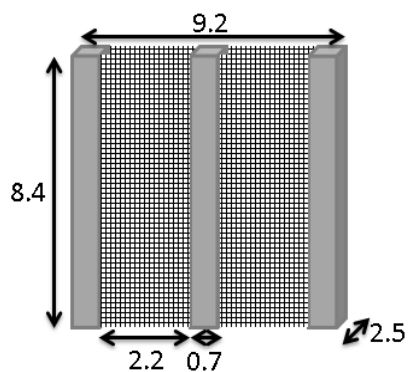


Figure 77: Dimensions (cm) of the modified basket.

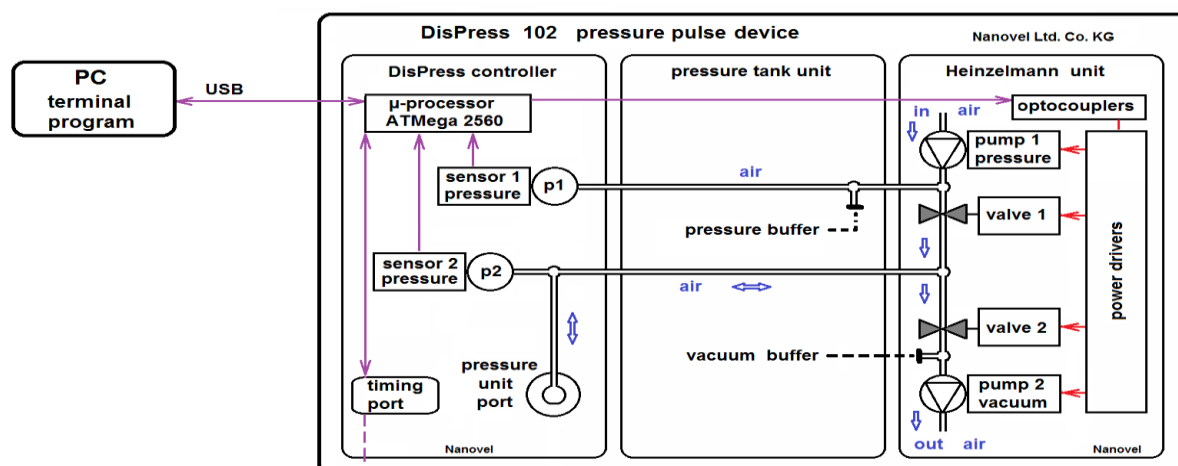


Figure 78: DisPress unit. The active elements of pressure regulation of the DisPress unit are controlled by a microprocessor (Arduino). Programming was accomplished by numeric parameters.

### 8.3 Application program of CNC controller

ProgBegin

N01 Type Referenzfahrt in allen Achsen...

N02 Ref

MoveAbs X250 F80

R1=MessageBox YESNO „Tablette eingelegt?“

If R1=6

MoveAbs X55 F 80

Endif

Repeat

MoveAbs X55 F80\*

MoveAbs X0 F80\*

Until E1.4

;

ProgEnd

\*: moving speed needs to be specified

## 8.4 DoE worksheet

Table 23: Design of experiments worksheet for the modified basket design (spe=speed, vis=viscosity, com=compression force).

Exp No	Exp Name	Run Order	Incl/Excl	spe	vis	com
1	N1	4	Incl	40	0	1
17	N17	35	Incl	40	0	1
33	N33	29	Incl	40	0	1
2	N2	44	Incl	80	0	1
18	N18	43	Incl	80	0	1
34	N34	14	Incl	80	0	1
3	N3	17	Incl	40	1.4	1
19	N19	1	Incl	40	1.4	1
35	N35	12	Incl	40	1.4	1
4	N4	46	Incl	80	1.4	1
20	N20	37	Incl	80	1.4	1
36	N36	27	Incl	80	1.4	1
5	N5	19	Incl	40	0	2
21	N21	34	Incl	40	0	2
37	N37	15	Incl	40	0	2
6	N6	22	Incl	80	0	2
22	N22	38	Incl	80	0	2
38	N38	10	Incl	80	0	2
7	N7	2	Incl	40	1.4	2
23	N23	3	Incl	40	1.4	2
39	N39	9	Incl	40	1.4	2
8	N8	11	Incl	80	1.4	2
24	N24	28	Incl	80	1.4	2
40	N40	40	Incl	80	1.4	2
9	N9	5	Incl	40	0	3
25	N25	32	Incl	40	0	3
41	N41	21	Incl	40	0	3
10	N10	13	Incl	80	0	3
26	N26	41	Incl	80	0	3
42	N42	6	Incl	80	0	3
11	N11	7	Incl	40	1.4	3
27	N27	30	Incl	40	1.4	3
43	N43	36	Incl	40	1.4	3
12	N12	20	Incl	80	1.4	3
28	N28	45	Incl	80	1.4	3
44	N44	39	Incl	80	1.4	3
13	N13	47	Incl	40	0	4
29	N29	48	Incl	40	0	4
45	N45	25	Incl	40	0	4
14	N14	23	Incl	80	0	4
30	N30	33	Incl	80	0	4
46	N46	18	Incl	80	0	4
15	N15	31	Incl	40	1.4	4
31	N31	8	Incl	40	1.4	4
47	N47	42	Incl	40	1.4	4
16	N16	16	Incl	80	1.4	4
32	N32	24	Incl	80	1.4	4
48	N48	26	Incl	80	1.4	4

For the compendial basket the design is the same expect that 5 replicates were performed resulting in 96 runs.

## 8.5 Tablet for in vivo disintegration studies

### Formulations:

Markertablets: 50 mg Neusillin

Markersubstance (Magnetic iron for proton MRI, perfluoro-15-crown-5-ether for fluorine MRI)

Matrixtablets: a) 9,45 g MCC 101

0,5 g Carbopol 971

0,05 g Magnesiumstearate

b) 9,65 g MCC 101

0,35 g Carbopol 971

### Preparation:

Markertablets:

50 mg Neusillin are weighed and compressed at 3 kN for 10 s using a hydraulic press. The markertablets are immersed in the liquid markersubstance overnight. After removing surface liquid with a tissue paper, the markertablets are coated with 5 % Ethylcellulose in acetone.

Matrixtablets:

The formulation componetns are weighed and homogenized using a motar and pestel. Powder and markertablets are layered alternating into the die. The mixture is compressed at 5 kN for 10 s using a hydraulic press.

### Disintegration time:

Disintegration times were measured in SGF at 37 °C using the compendial disintegration test device.

Table 24: Disintegration times of the two tablet formulations developed for *in vivo* disintegration time measurements.

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Formulation a)	
1	15:30 min
2	16:30 min
3	18:00 min
Mittelwert	16:53 min

Formulation b)	
1	3:05 min
2	4:32 min
3	6:02 min
Mittelwert	4:46 min

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## 9 List of related publications

### Publications:

Kindgen, S., Wachtel H., Abrahamsson B., Langguth P.: Computational Fluid Dynamics Simulation of Hydrodynamics and Stresses in the PhEur/USP Disintegration Tester Under Fed and Fasted Fluid Characteristics, J. Pharm. Sci, accepted, **2015**.

Kindgen, S., Rach, R., Wachtel, H., Nawroth, T., Langguth, P.: A Modified Disintegration Test Device- Computational Fluid Dynamics Investigations, in preparation, **2015**.

Kindgen, S., Rach, R., Zaheer, K., Nawroth, T., Langguth, P.: Influence of Hydrodynamics on Tablet Disintegration Investigated using a Modified Disintegration Test Device, in preparation, **2015**.

### Poster presentations:

S. Kindgen, M. Knoell, U. Schmidt, J. Müller, P. Langguth: Effect of process parameters during high-shear granulation on the content uniformity of resulting low dose tablets, 8<sup>th</sup> World Meeting on Pharmaceutics, Biopharmaceutics and Pharmaceutical Technology, Istanbul, Turkey, March 2012.

J. Schröder, S. Kindgen, S. Fischer, M. Schuppert, K. Gogoll, P. Langguth, L.M. Schreiber: Untersuchung des Auflösungsverhaltens von Tabletten mittels <sup>19</sup>F-Magnetresonanzspektroskopie und –tomographie, DGMP Jahrestagung 2012, Jena, Germany, September 2012.

J. Friedrich, J. Schröder, S. Kindgen, S. Fischer, M. Schuppert, K. Gogoll, P. Langguth, L.M. Schreiber: Drug dissolution: Investigation of different fluor containing substances using <sup>19</sup>F-MRI, ISMRM, Milano, Italy, May 2014.

S. Kindgen, H. Wachtel, P. Langguth: Hydrodynamics in the PhEur/USP disintegration tester, Predictive biopharmaceutic methods in drug discovery and oral product development, workshop, Mainz, Germany, September 2014.

S. Kindgen, H. Wachtel, P. Langguth: Hydrodynamics in the PhEur/USP disintegration tester, DPhG annual meeting 2014, Frankfurt, Germany, September 2014,

# 10 Acknowledgements

## **11 Curriculum vitae**